

# Spatially Coupled LDPC Codes: Is This What Shannon Had In Mind?



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University of Notre Dame

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*University of Michigan, Nov. 17, 2016*

Research Collaborators: David Mitchell,  
Michael Lentmaier, and Ali Pusane

## ■ From Shannon to Modern Coding Theory

➔ Channel capacity, structured codes, random codes, LDPC codes

## ■ LDPC Block Codes

➔ Parity-check matrix and Tanner graph representations, minimum distance bounds, iterative decoding thresholds, protograph-based constructions

## ■ Spatially Coupled LDPC Codes

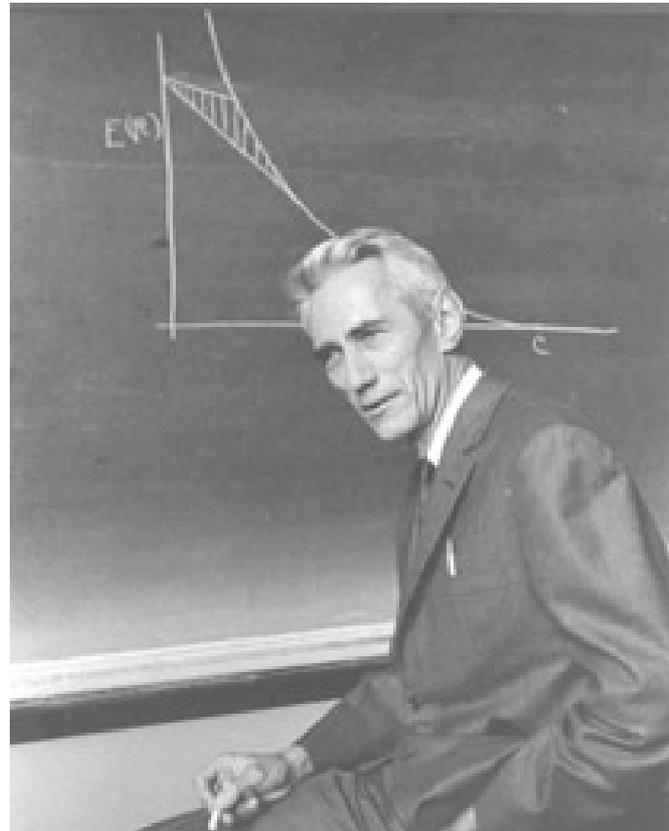
➔ Protograph representation, edge-spreading construction, termination

➔ Iterative decoding thresholds, threshold saturation, minimum distance

## ■ Practical Considerations

➔ Window decoding, performance, latency, and complexity comparisons to LDPC block codes, rate-compatibility, implementation aspects

# Shannon's Legacy



Claude Elwood Shannon  
Apr. 30, 1916 – Feb. 24, 2001  
Father of **Information Theory**

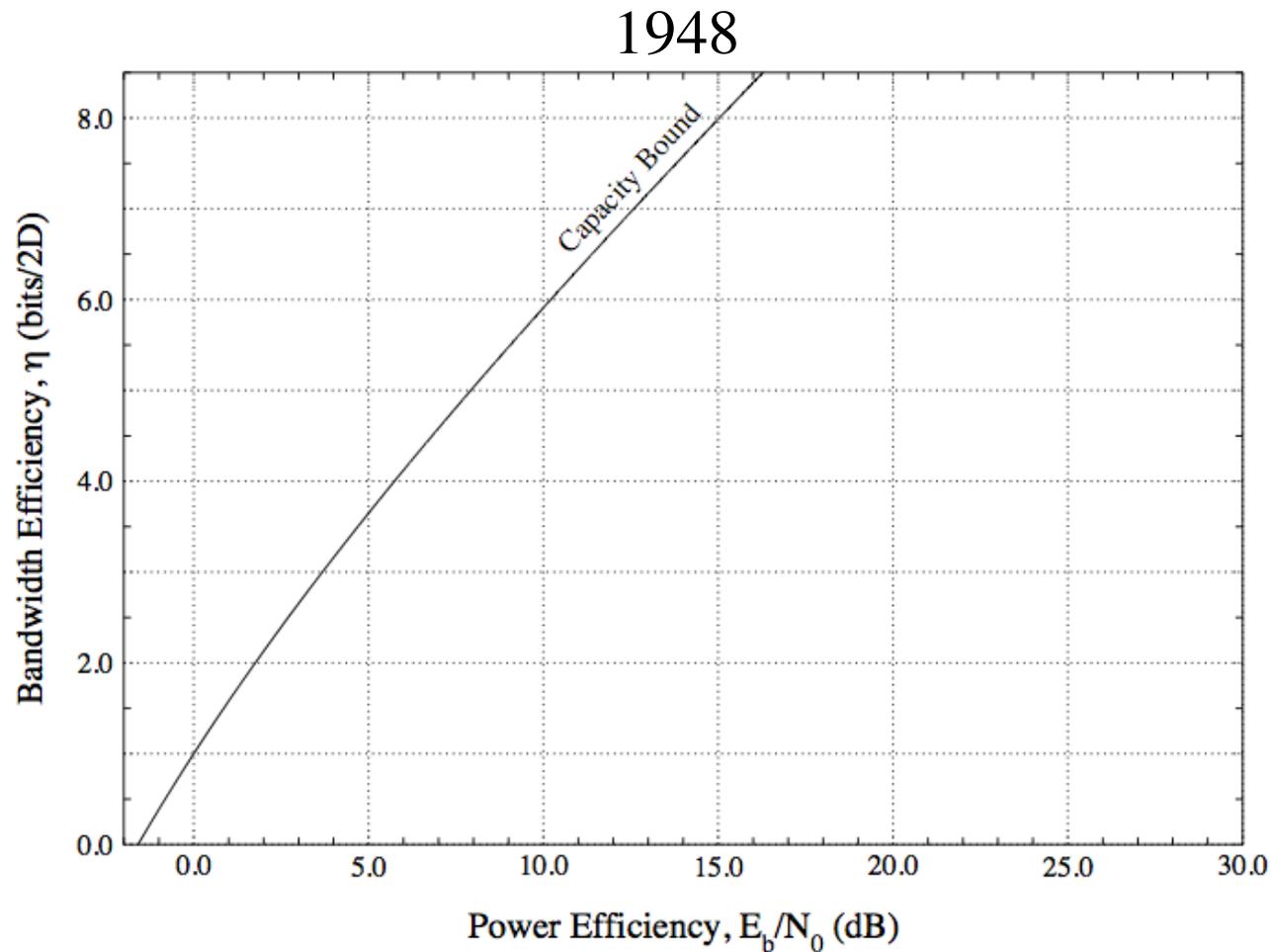
## Shannon's Theory Was Invented at Bell Labs

Bell Labs in Murray Hill,  
New Jersey



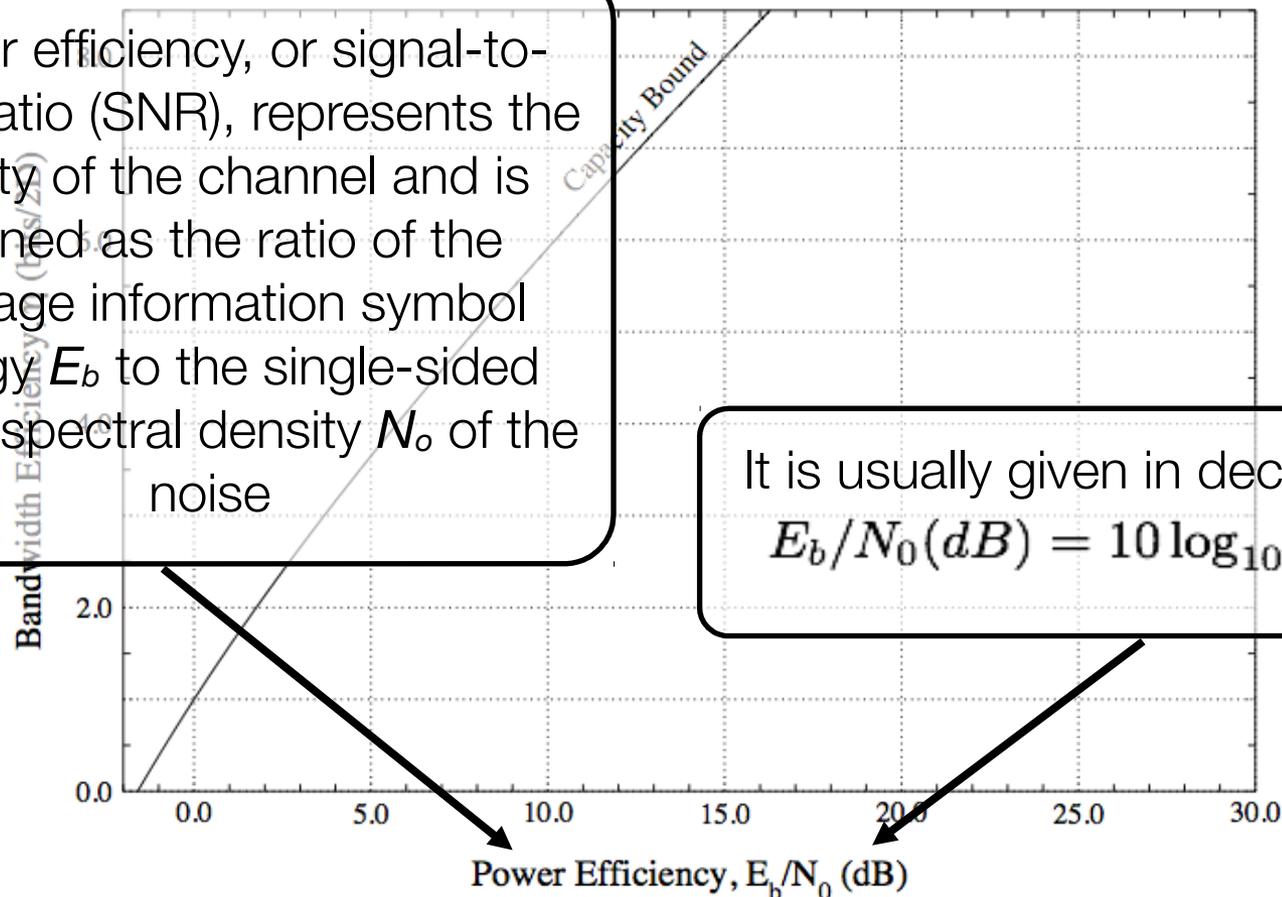
## Three Great Successes of Information Theory

- Source Coding for Data Compression
- Secret Coding (Cryptography) for Data Security
- Channel Coding for Data Reliability (*the focus of this presentation*)



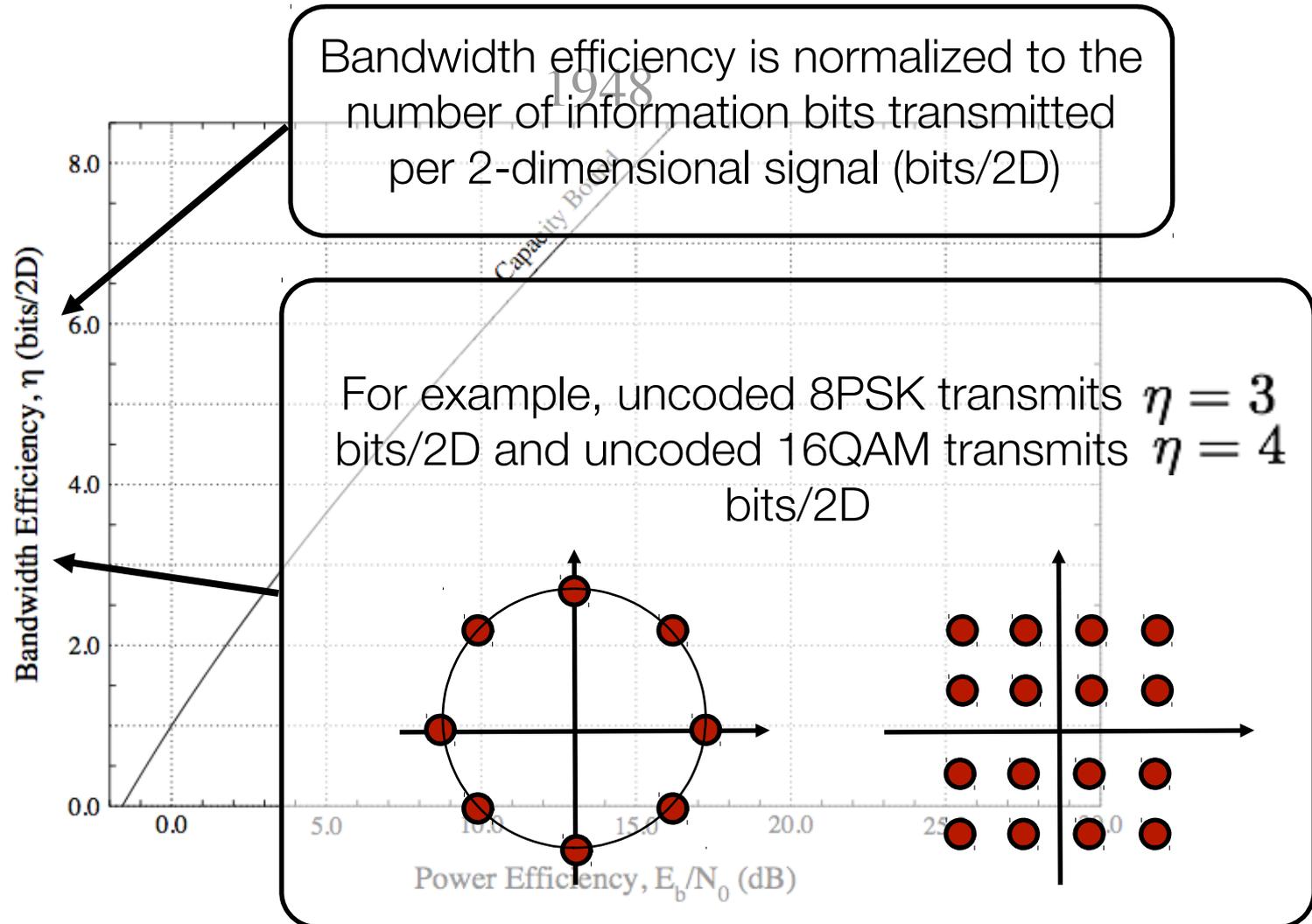
1948

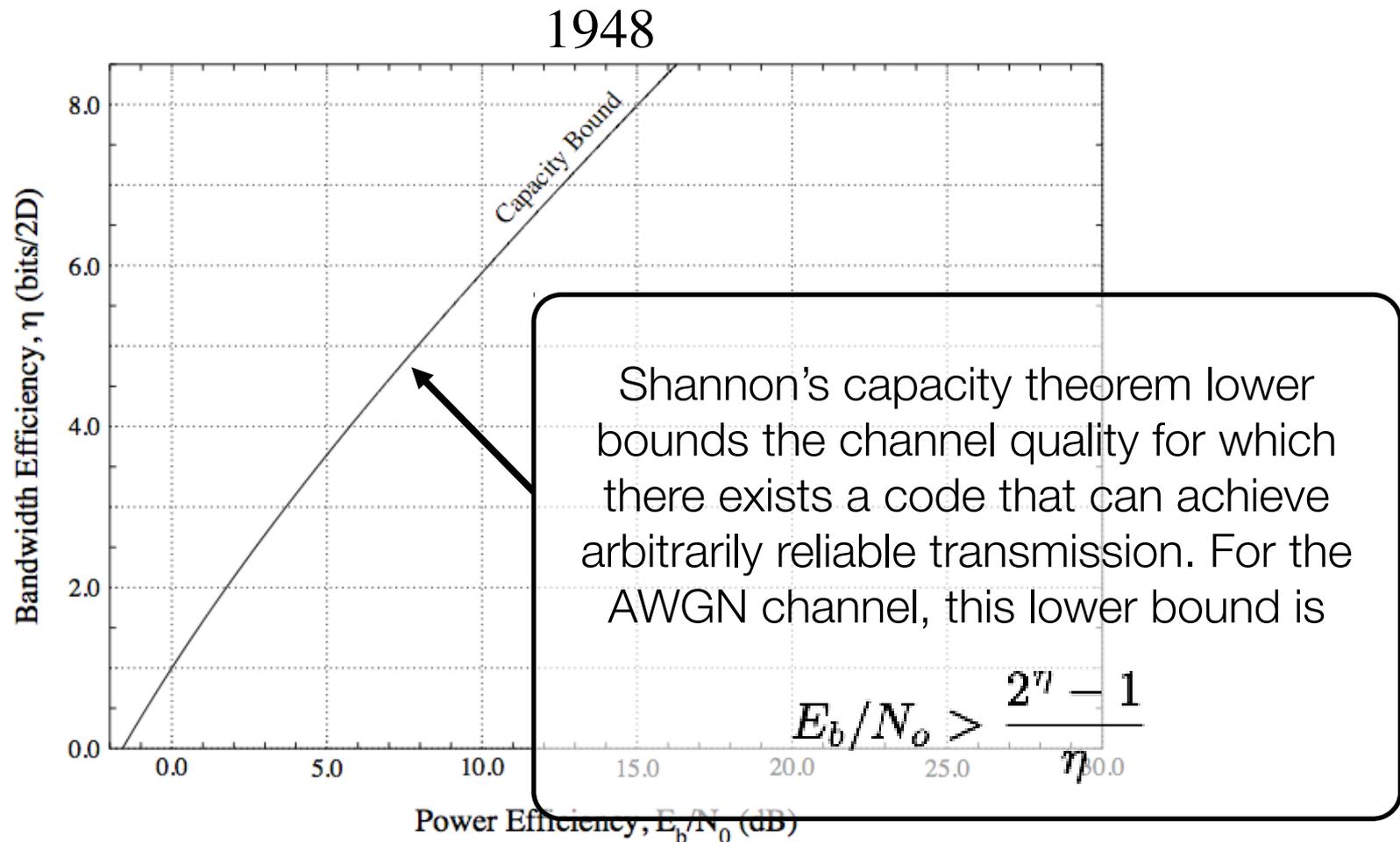
Power efficiency, or signal-to-noise ratio (SNR), represents the quality of the channel and is defined as the ratio of the average information symbol energy  $E_b$  to the single-sided power spectral density  $N_o$  of the noise



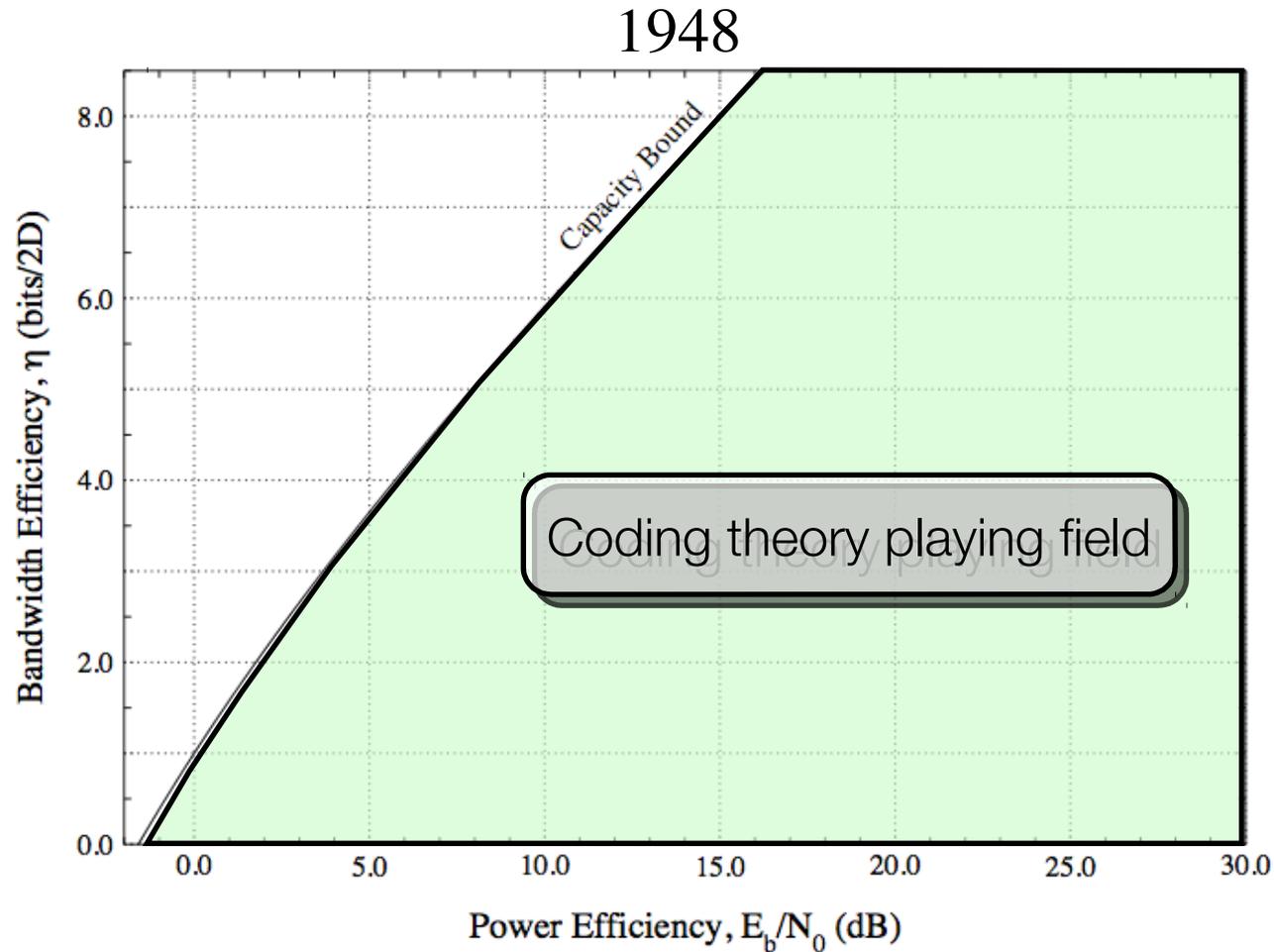
It is usually given in decibels (dB).

$$E_b/N_0(\text{dB}) = 10 \log_{10} E_b/N_o$$

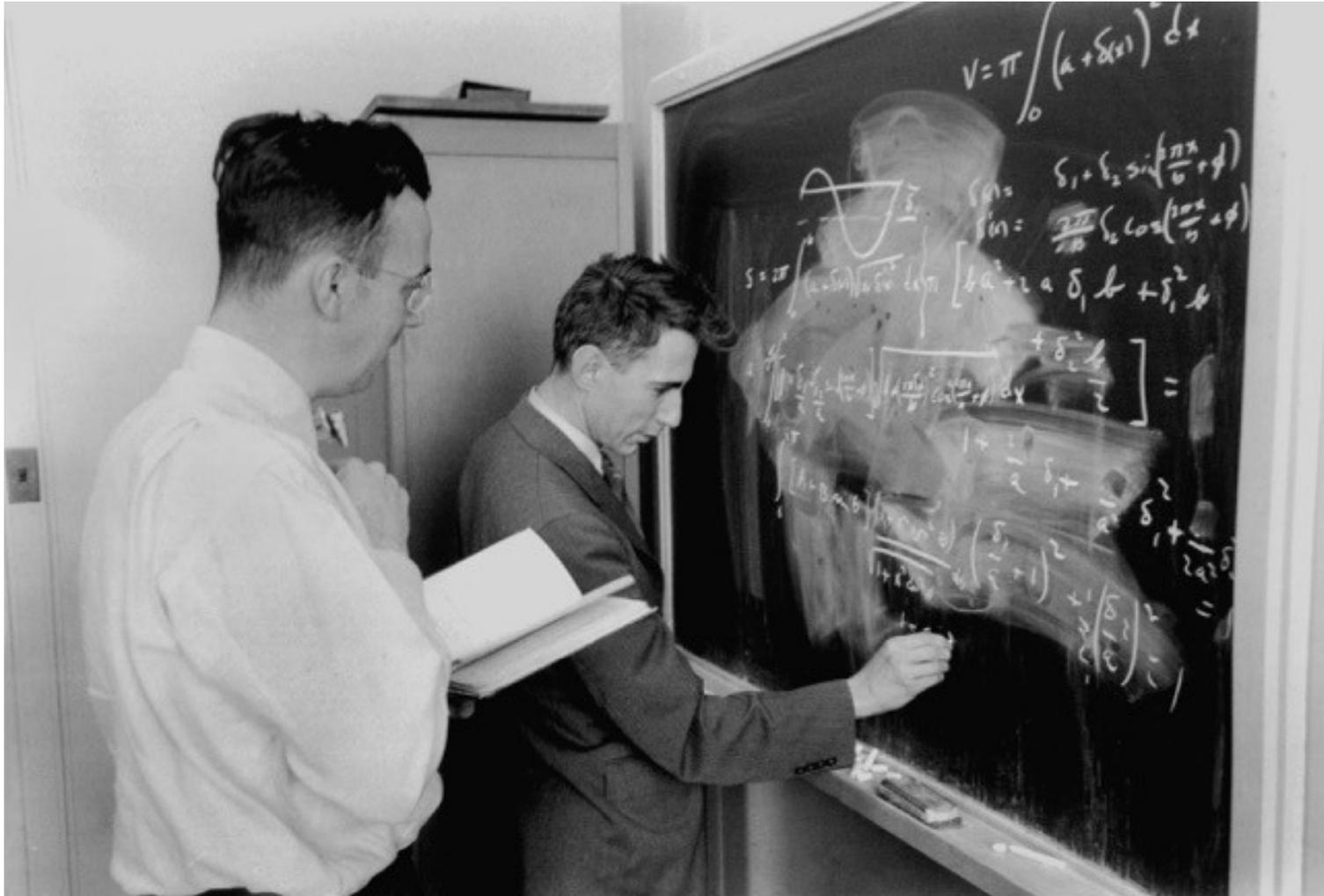




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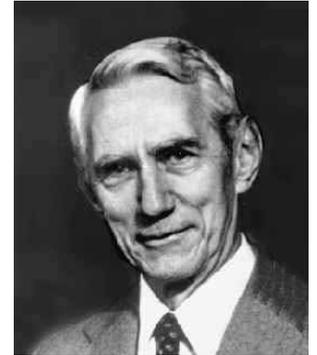


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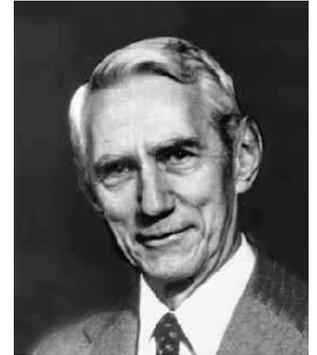
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- Shannon showed that **random codes** with large block length can **achieve capacity**, but...



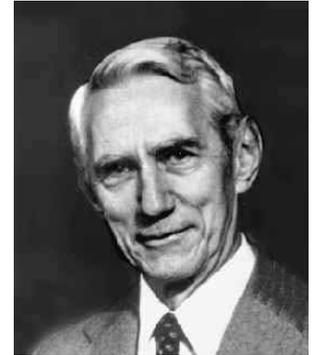
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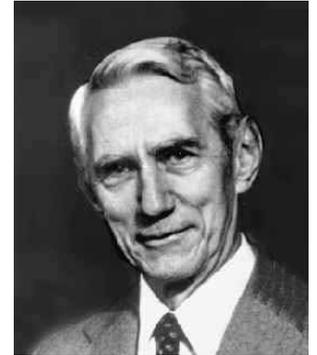
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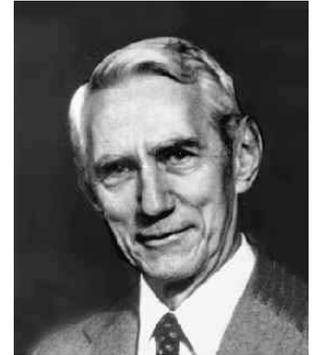
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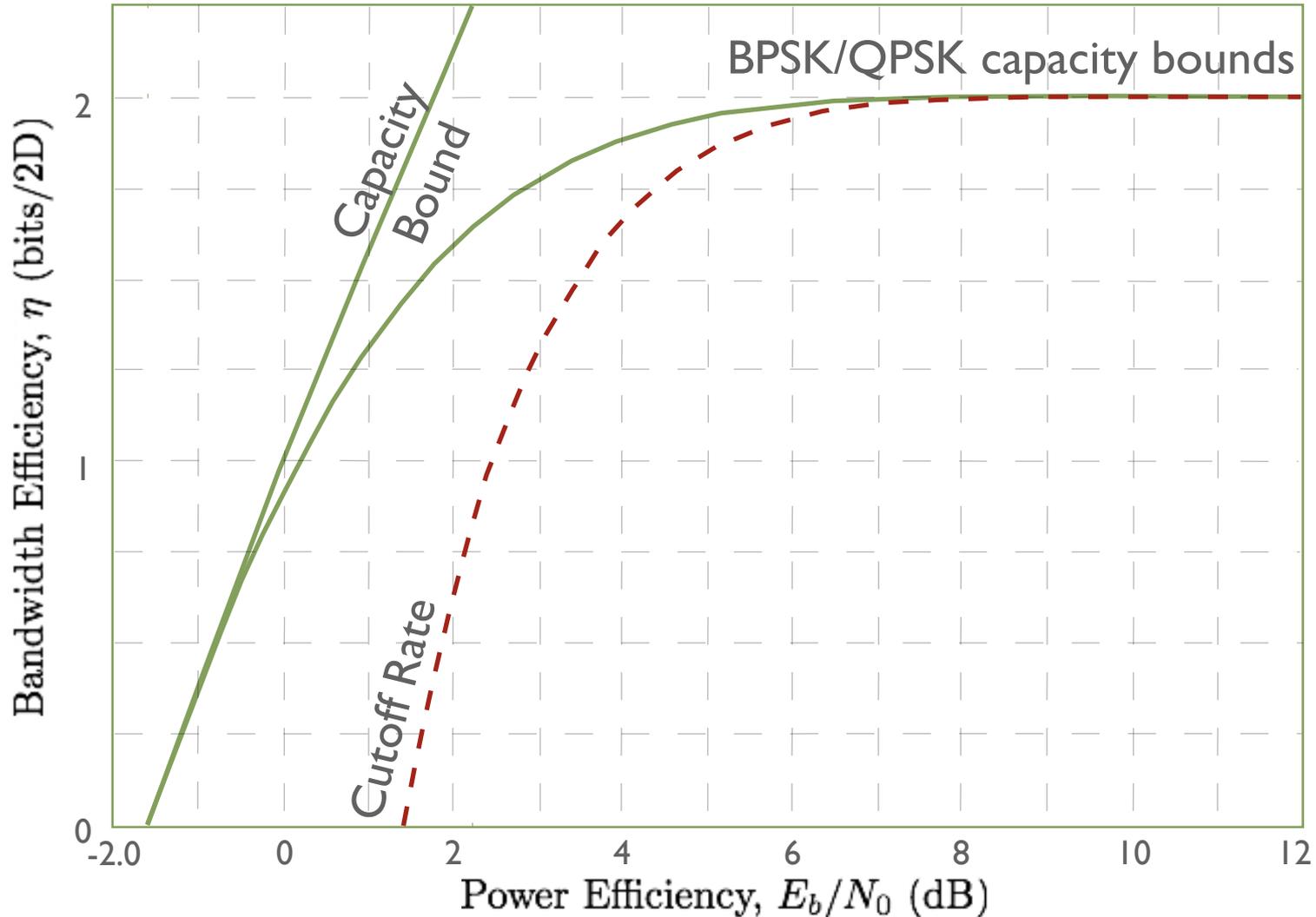
“Almost all codes are good... except those we can think of.”

**Solution:** Construct random-like codes with just enough structure to allow efficient decoding

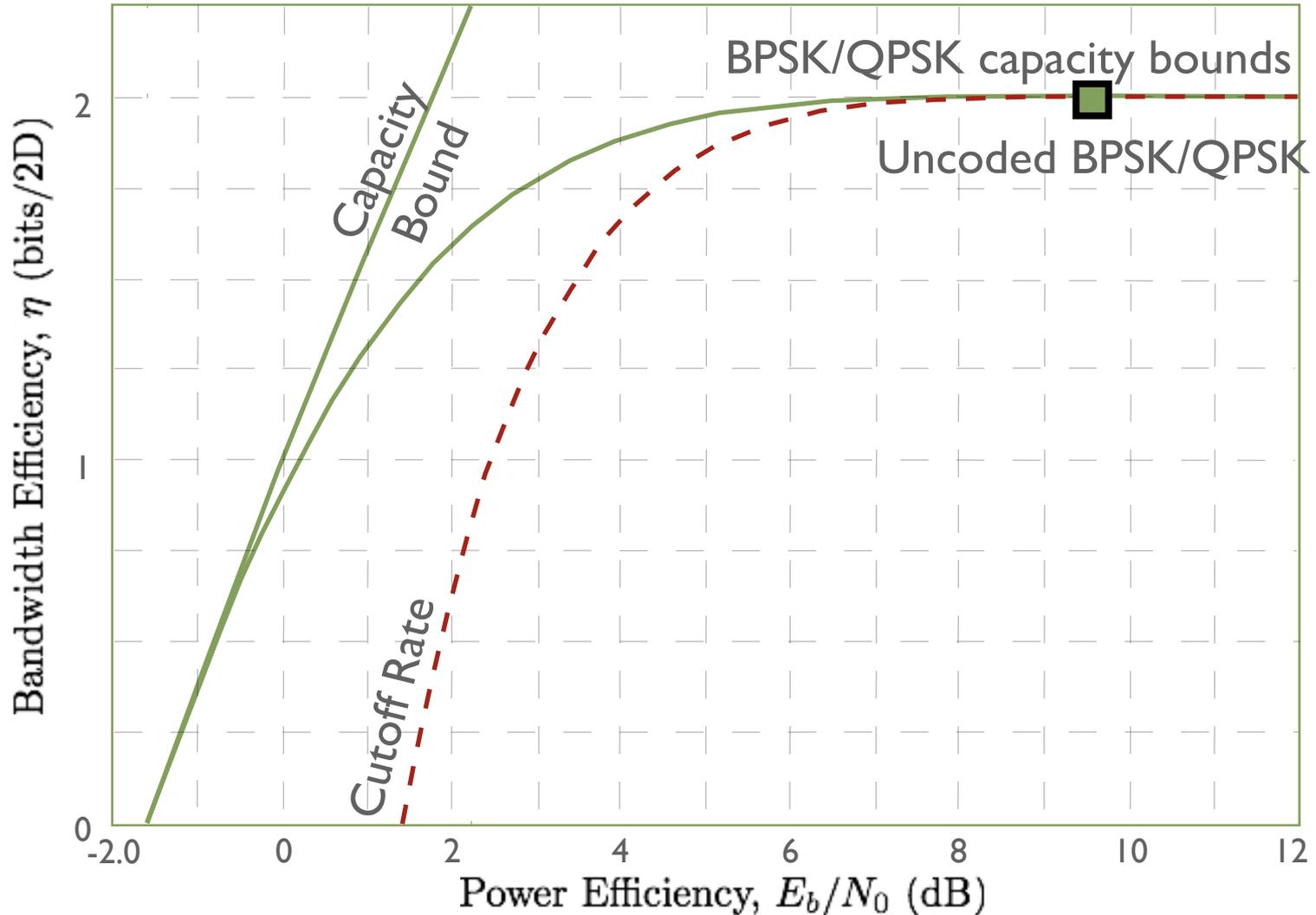
➔ Modern Coding Theory



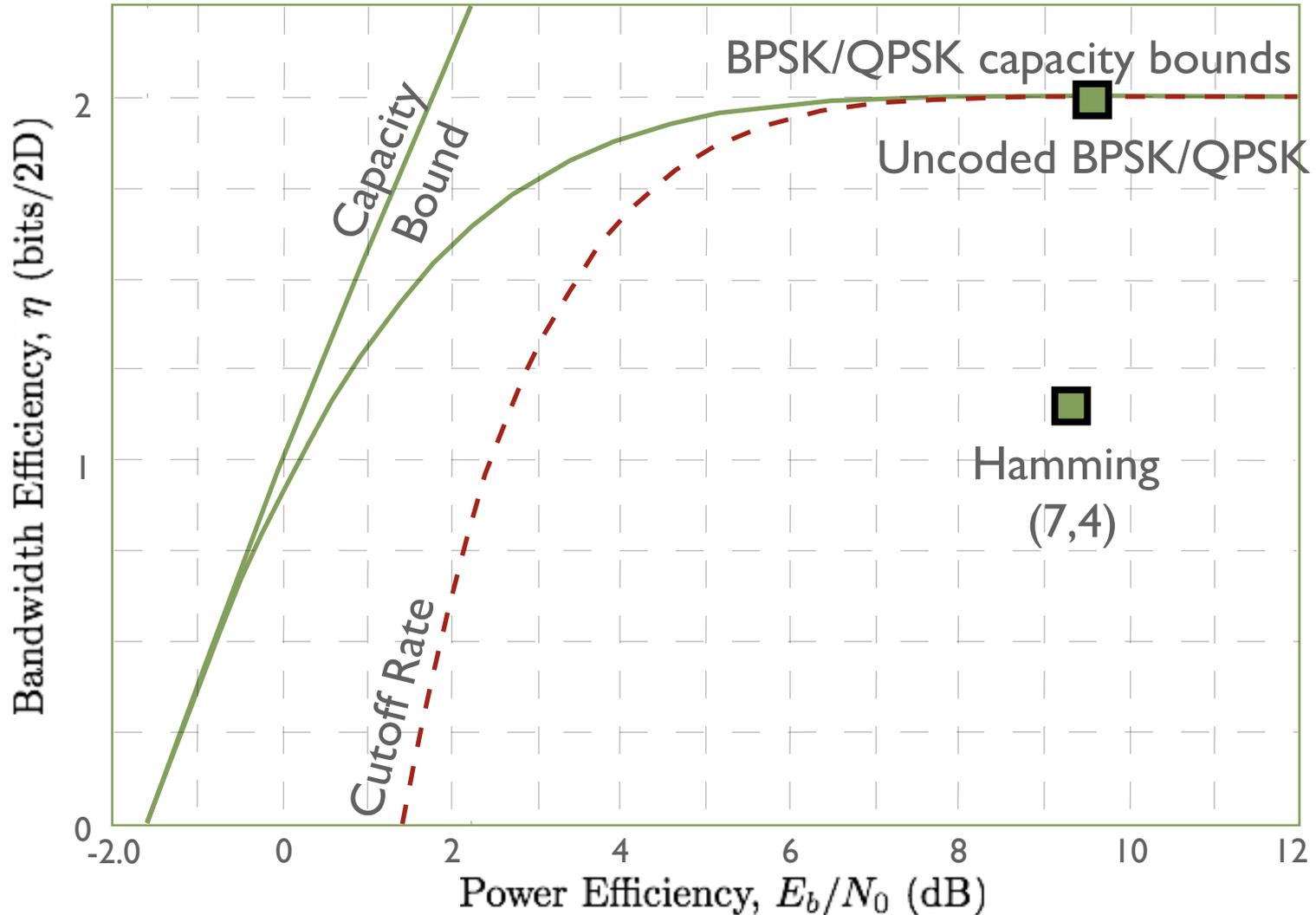
# LDPC Codes: motivation (for a target BER $10^{-5}$ )



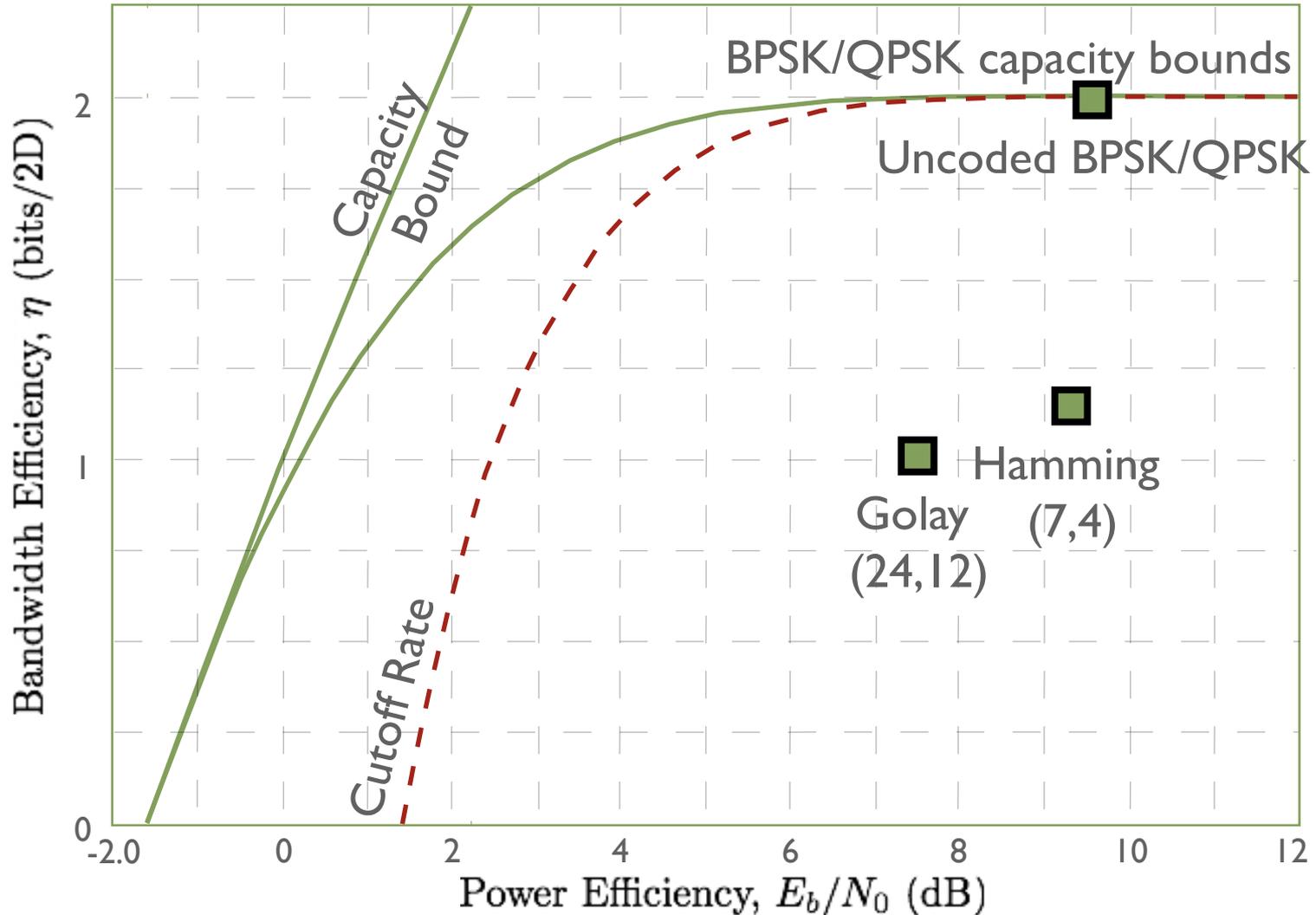
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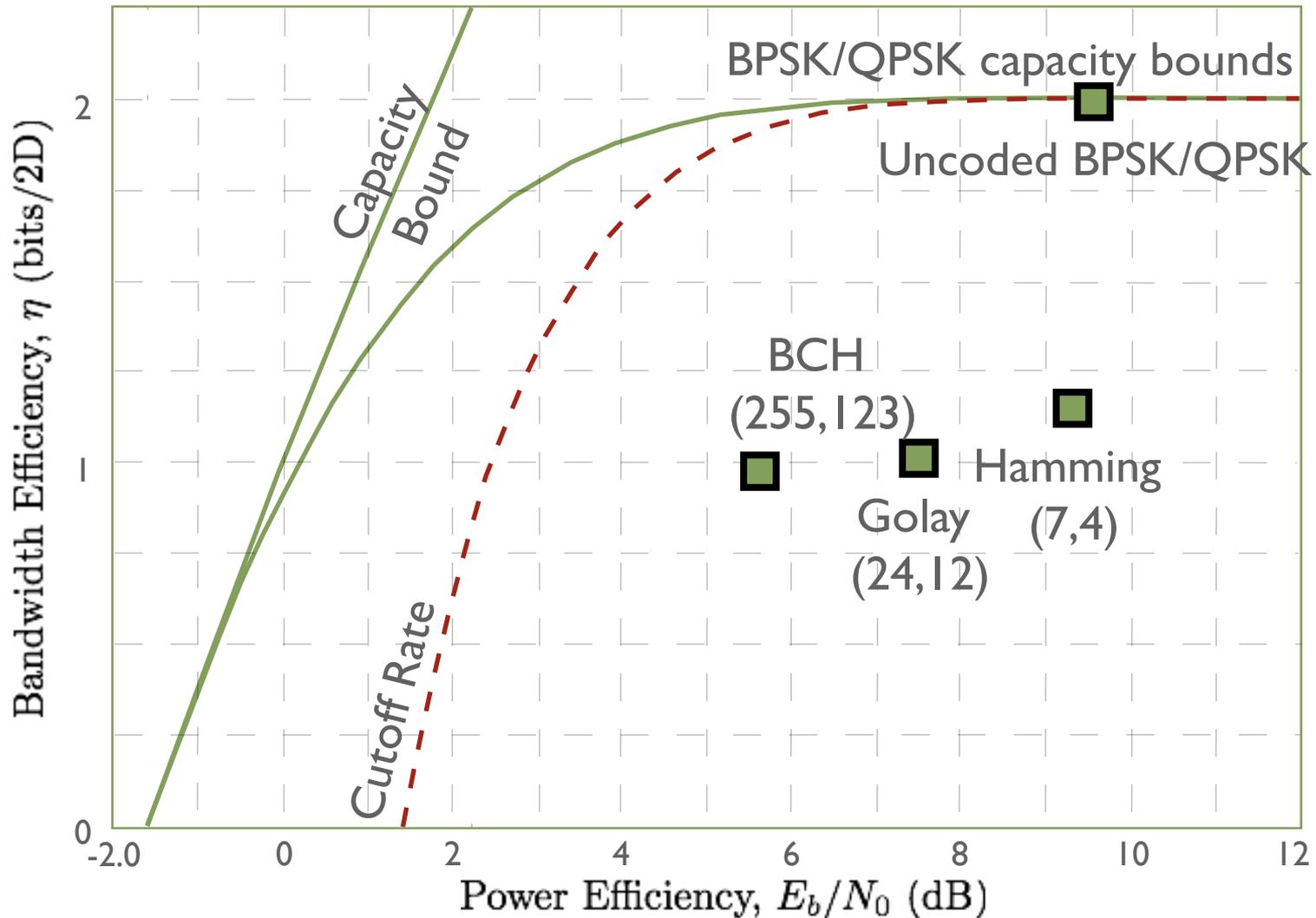
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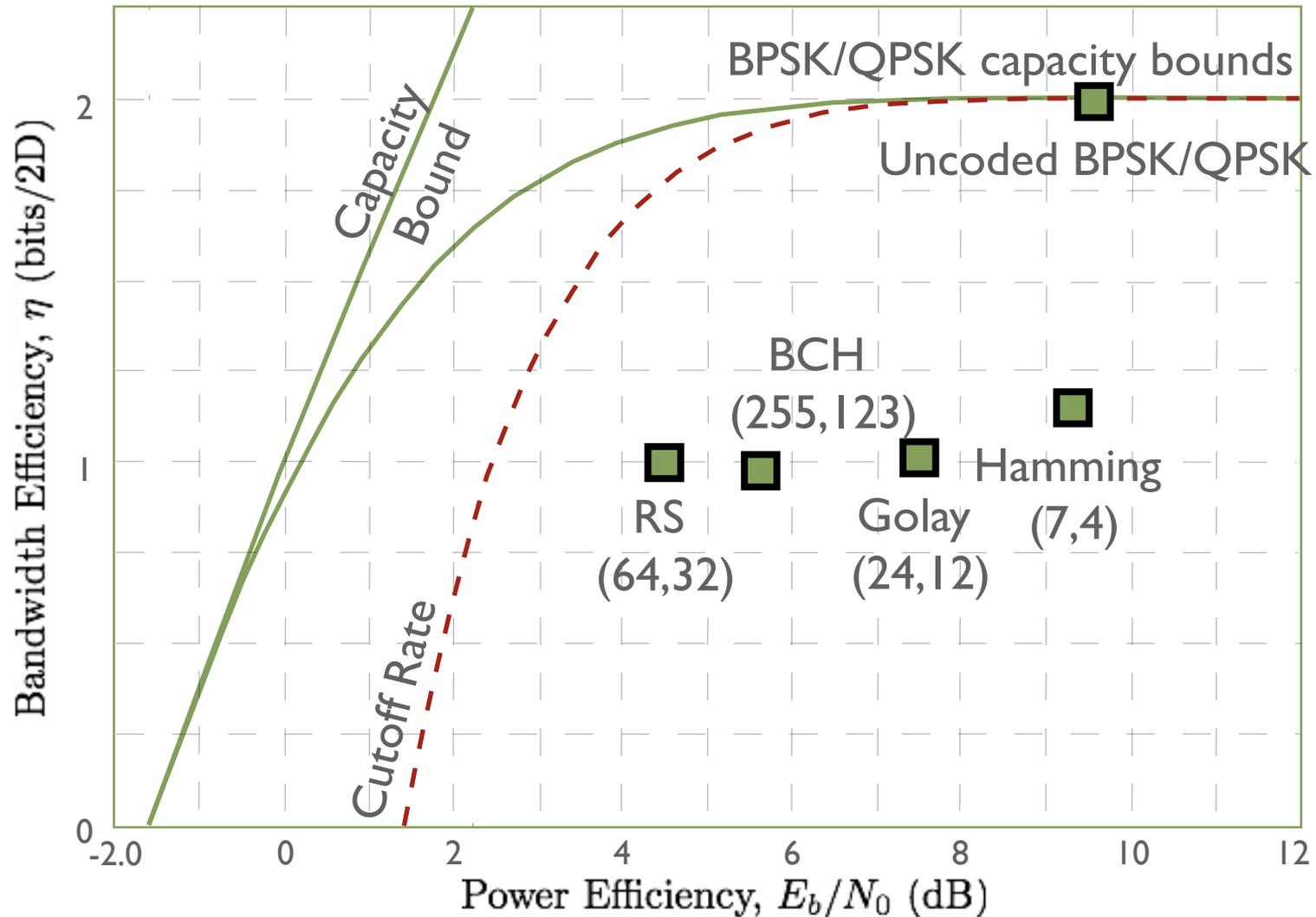
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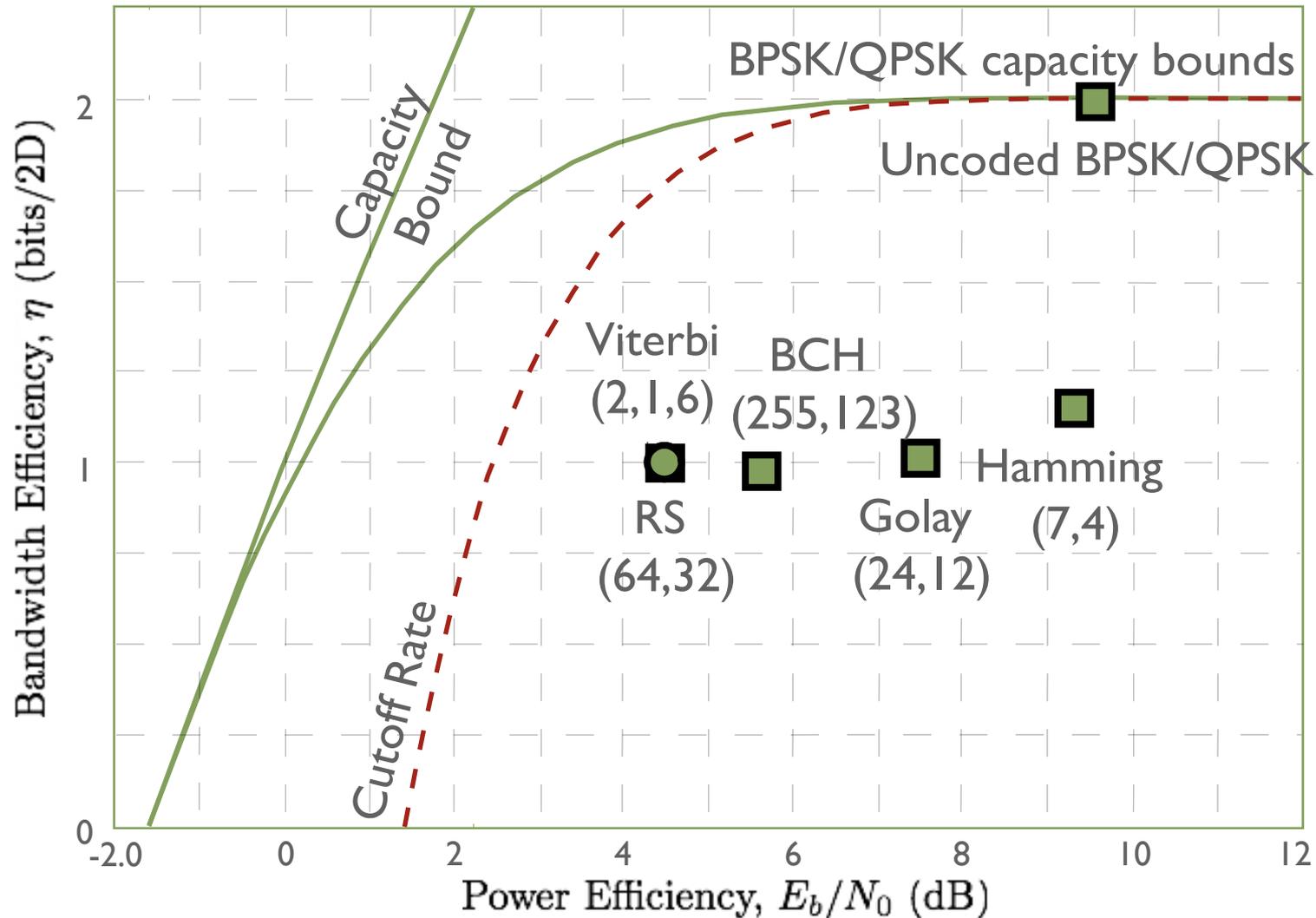
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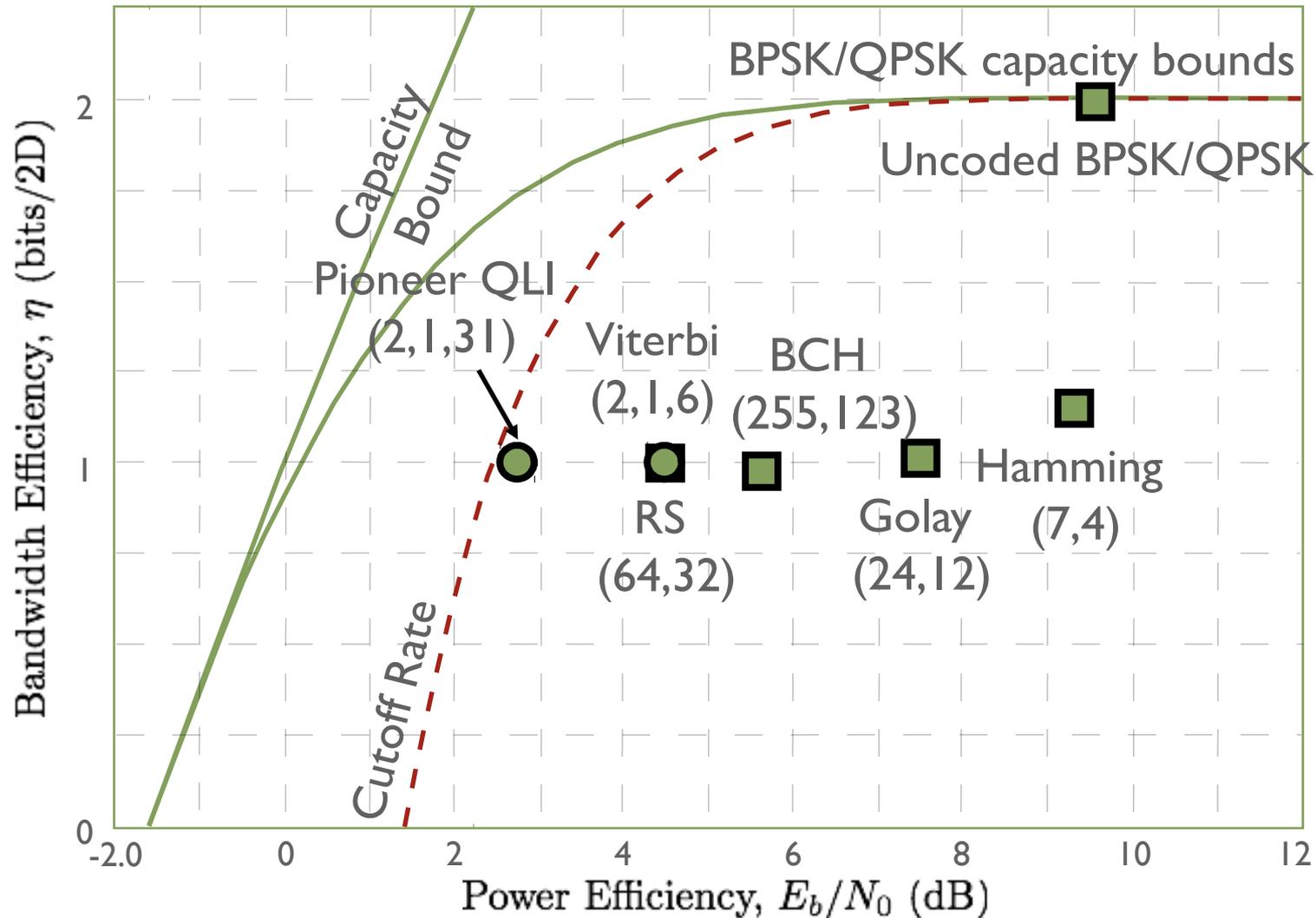
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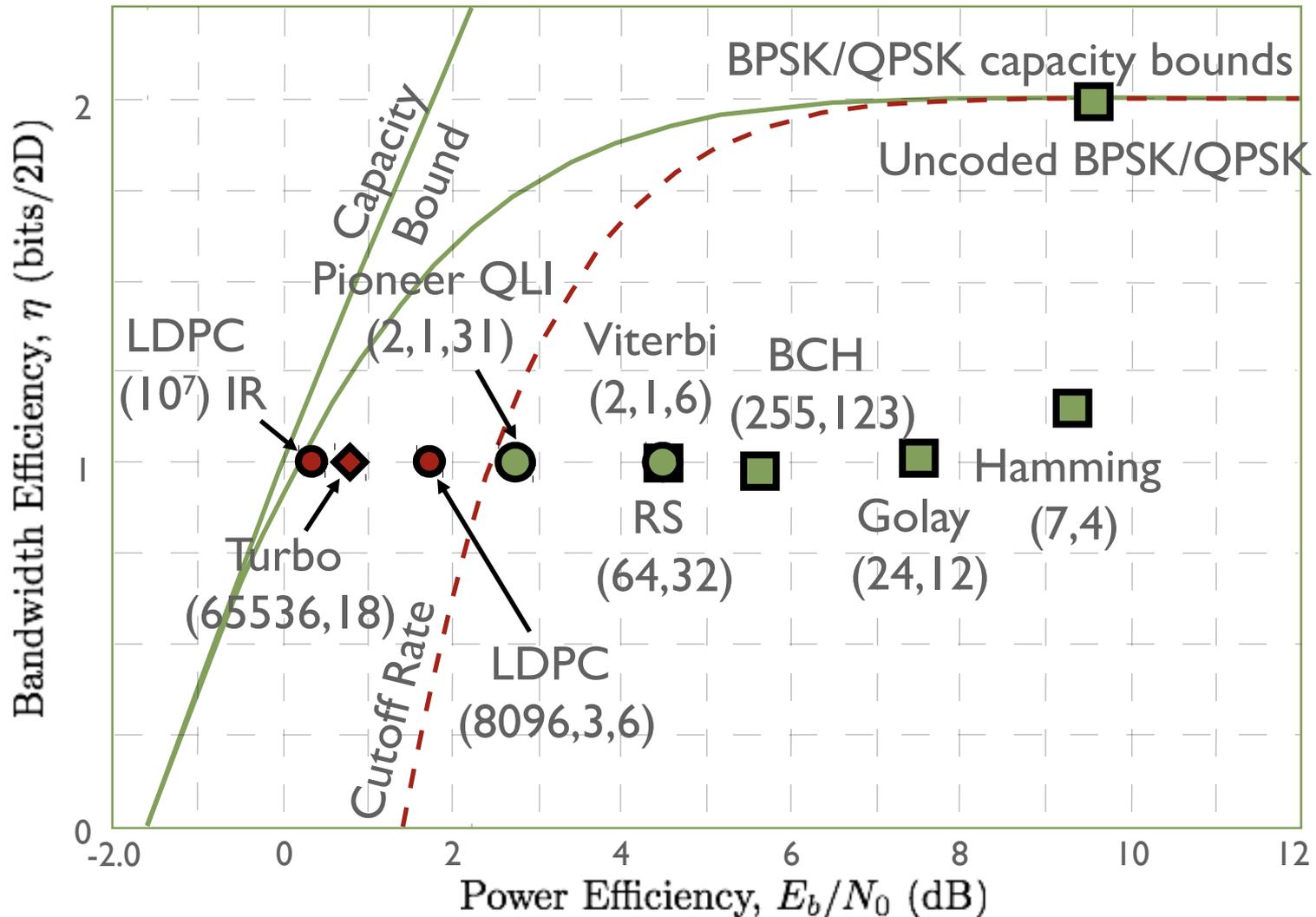
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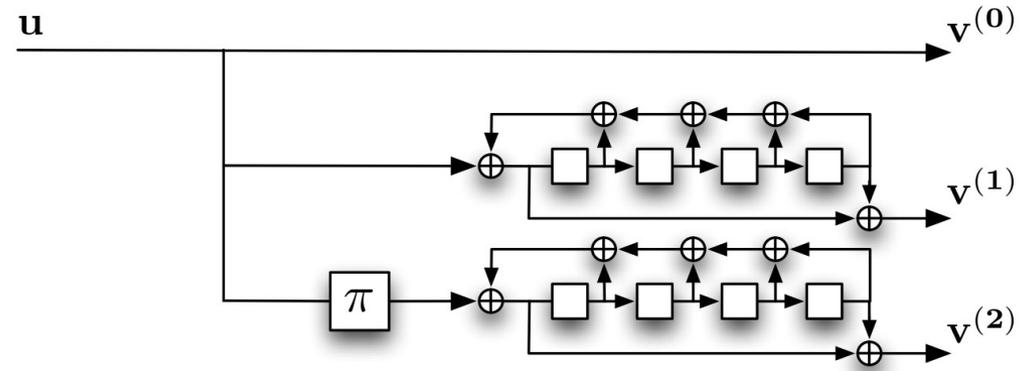
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- Turbo codes use a long pseudorandom interleaver

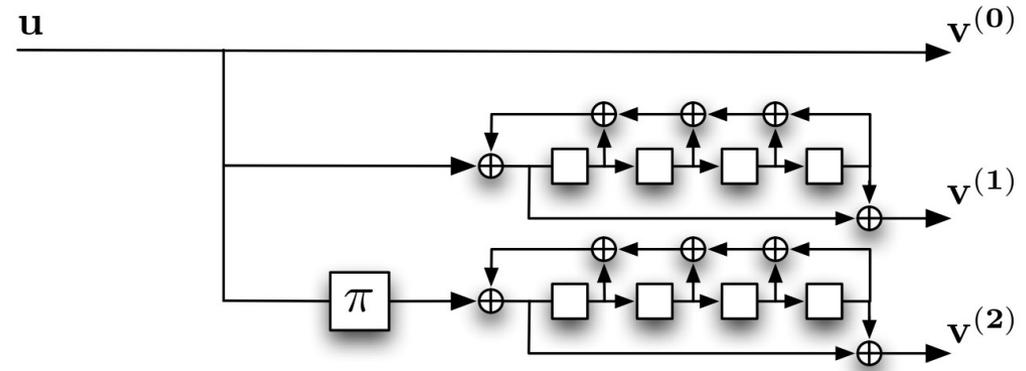
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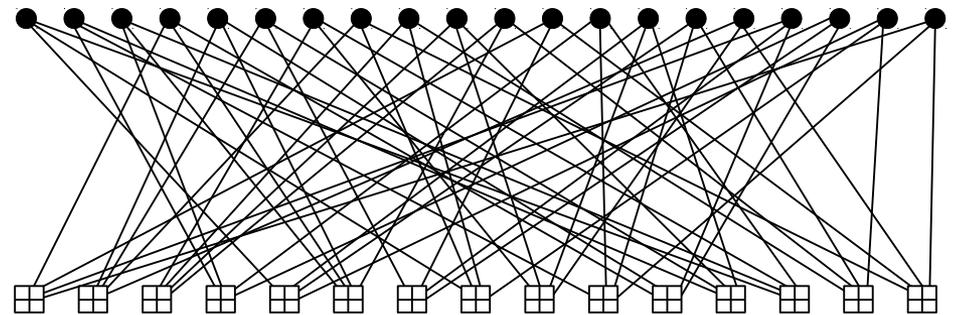
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- Low-density parity-check (LDPC) codes are defined on a large sparse graph

➔ DVB-S2, ITU-T G.hn standard (data networking over power lines, phone lines, and coaxial cables), 10GBase-T Ethernet, Wi-Fi standards 802.11, and so on.



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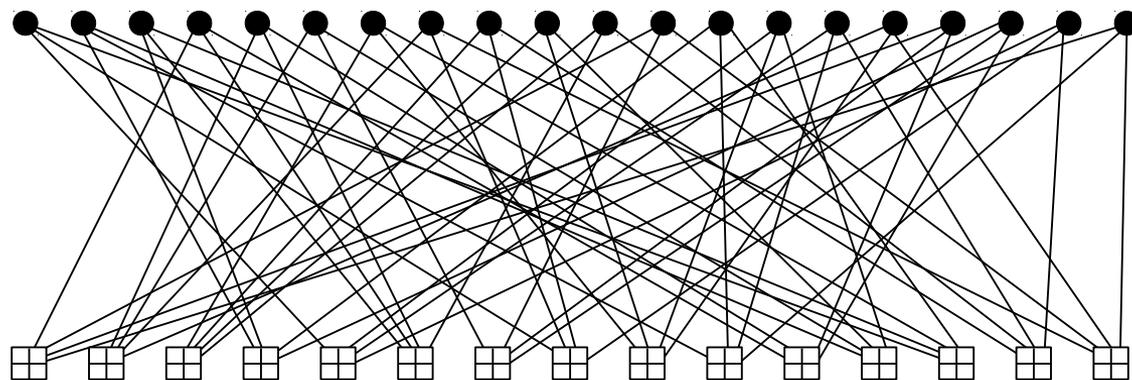
Definition by parity-check matrix: [Gallager, '62]

Bipartite graph representation: [Tanner, '81]

$$H = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 \\ \hline 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

15 × 20

$n = 20$  variable nodes of degree  $J = 3$



$l = 15$  check nodes of degree  $K = 4$

Code:  $\{ \mathbf{v} \mid \mathbf{v} \mathbf{H}^T = \mathbf{0} \}$

(J,K)-regular LDPC block code:  $R \geq 1 - \frac{J}{K}$

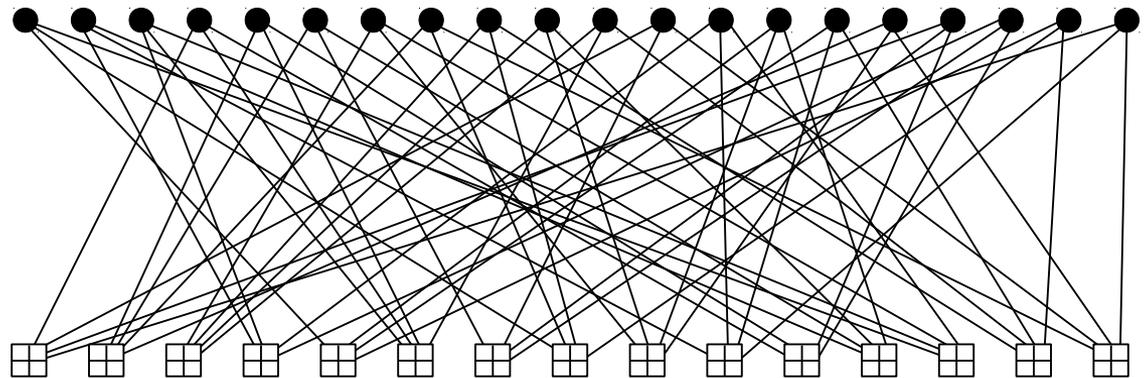
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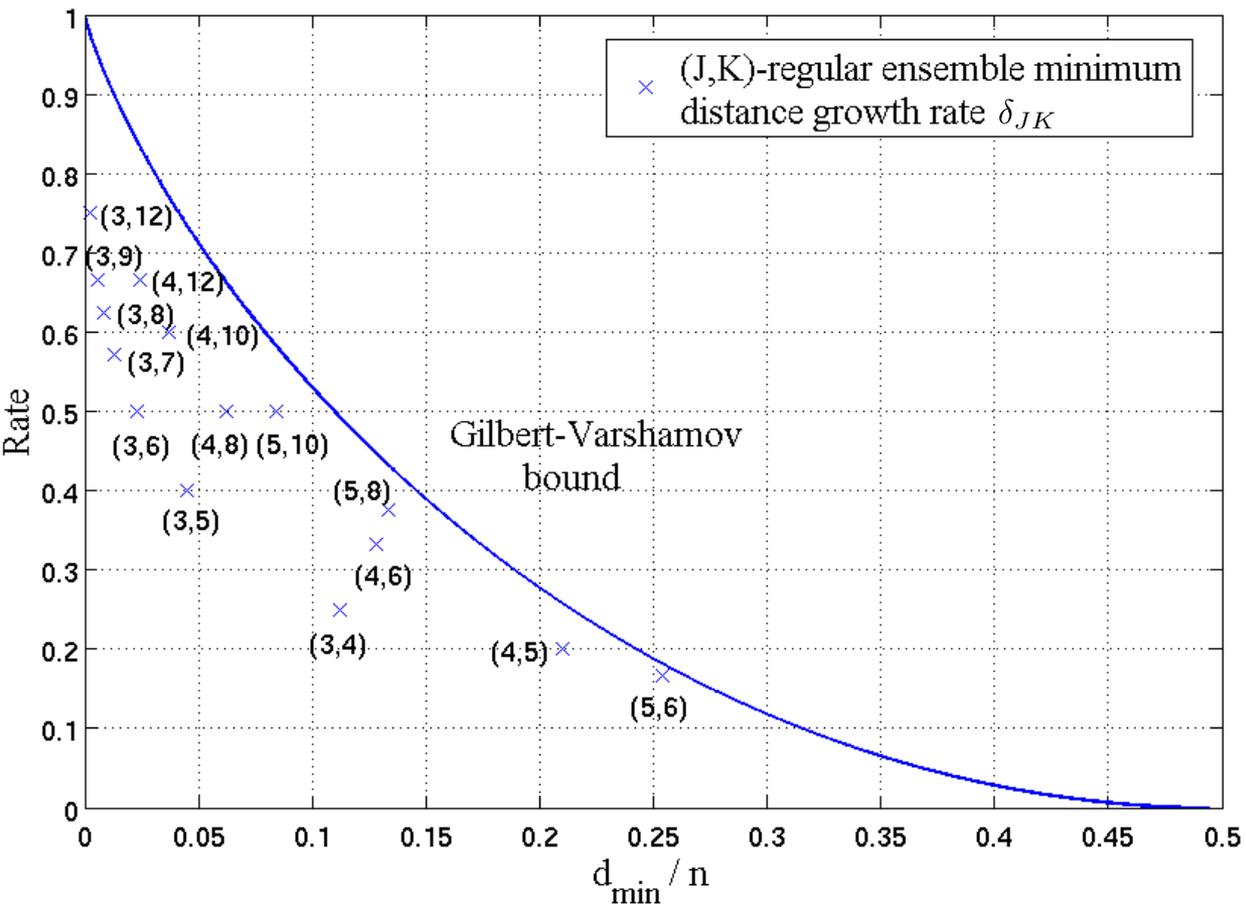
(J,K)-regular LDPC block code:  $R \geq 1 - \frac{J}{K}$

- Graph-based codes can be decoded iteratively with low complexity by exchanging messages in the graph using Belief Propagation (BP).

# Minimum Distance Growth Rates of (J,K)-Regular LDPC Block Code Ensembles



- For an **asymptotically good** code ensemble, the minimum distance grows linearly with the block length  $n$

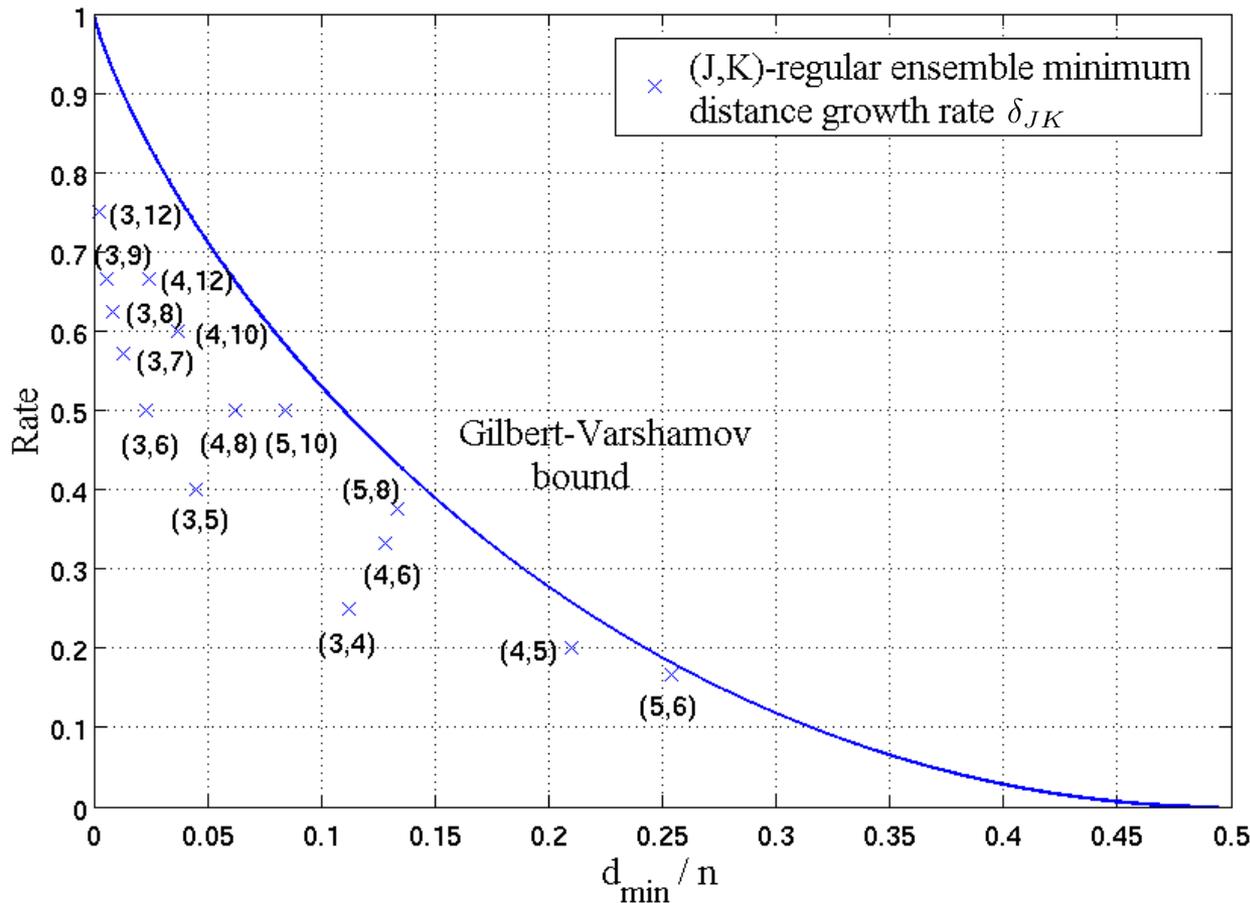


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where  $\delta_{JK}$  is called the **typical minimum distance ratio**, or **minimum distance growth rate**.



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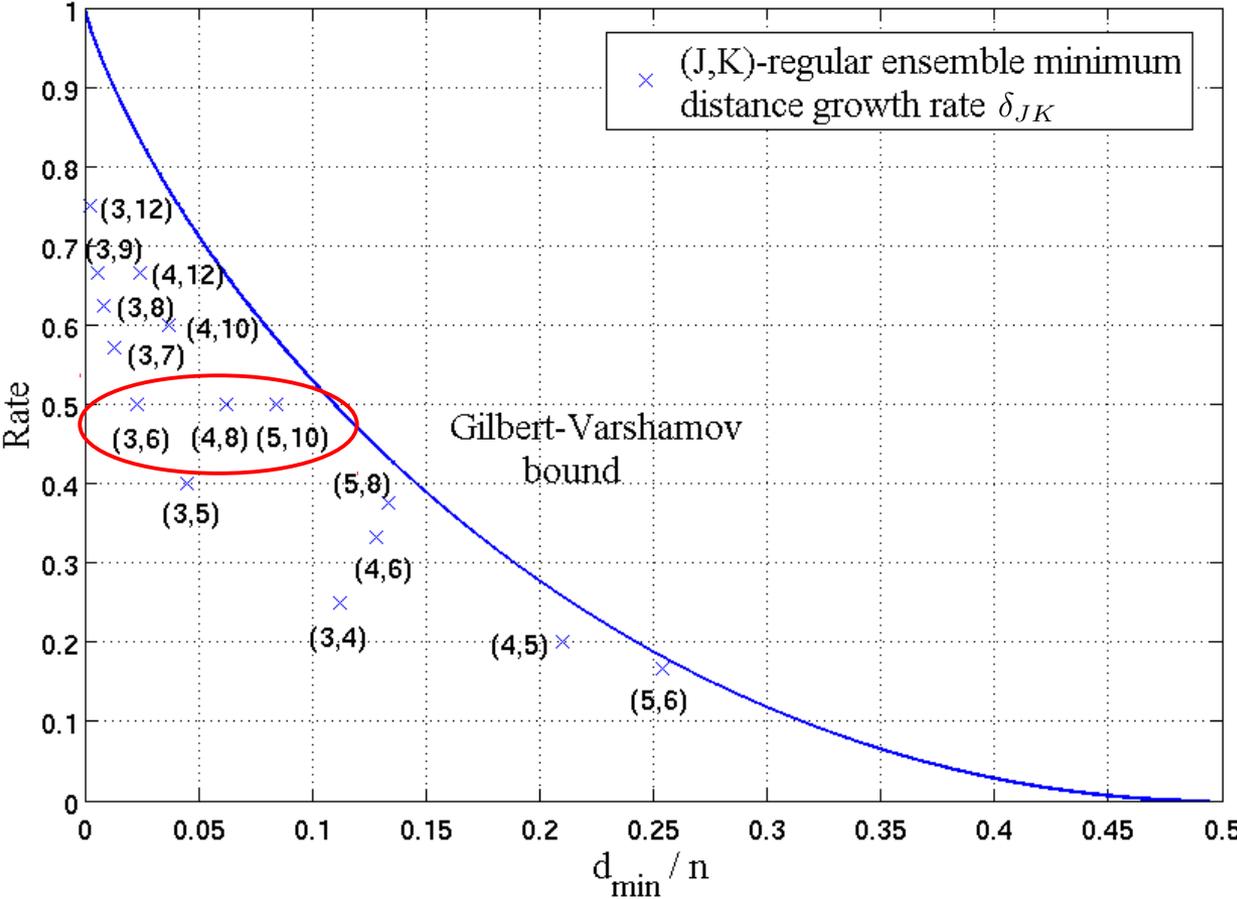
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- As the density of  $(J,K)$ -regular ensembles increases,  $\delta_{JK}$  approaches the **Gilbert-Varshamov bound**.



# Thresholds of $(J,K)$ -regular LDPC Block Code Ensembles

- Iterative decoding thresholds can be calculated for  $(J,K)$ -regular LDPC block code ensembles using density evolution (DE).

## BEC thresholds

$J$	$K$	Rate	$\varepsilon^*$	$\varepsilon_{\text{Sh}}$
3	6	0.5	0.429	0.5
4	8	0.5	0.383	0.5
5	10	0.5	0.341	0.5
3	5	0.4	0.517	0.6
4	6	0.333	0.506	0.667
3	4	0.25	0.647	0.75

## AWGNC thresholds

$J$	$K$	Rate	$(E_b/N_0)^*$	$(E_b/N_0)_{\text{Sh}}$
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3	5	0.4	0.96	-0.229
4	6	0.333	1.67	-0.480
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[RU01] T. J. Richardson, and R. Urbanke, "The capacity of low-density parity-check codes under message passing decoding", *IEEE Transactions on Information Theory*, vol. 47 no. 2, Feb. 2001.

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- There exists a relatively **large gap to capacity**.
- Iterative decoding thresholds get **further from capacity** as the graph **density increases**.

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# Protographs (Matrix Description)

- Large LDPC codes can be obtained from a small **base parity-check matrix  $\mathbf{B}$**  by replacing each nonzero entry in  $\mathbf{B}$  with an  $M \times M$  **permutation matrix**, where  $M$  is the **lifting factor**.

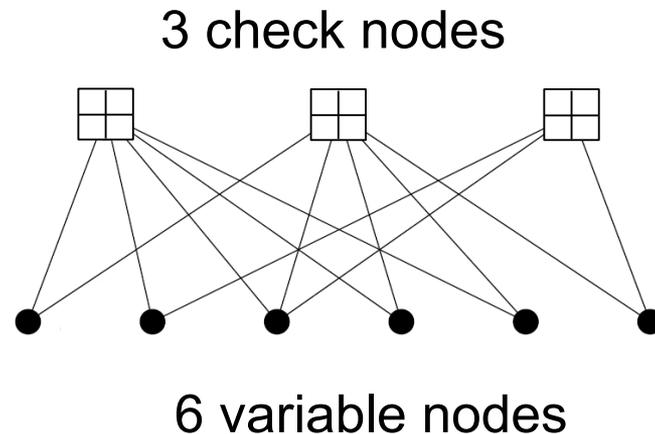
$$\mathbf{B} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{bmatrix}_{3 \times 6} \rightarrow \mathbf{H} = \begin{bmatrix} \mathbf{\Pi}_{1,1} & \mathbf{\Pi}_{1,2} & \mathbf{\Pi}_{1,3} & \mathbf{\Pi}_{1,4} & \mathbf{\Pi}_{1,5} & \mathbf{0} \\ \mathbf{\Pi}_{2,1} & \mathbf{0} & \mathbf{\Pi}_{2,3} & \mathbf{\Pi}_{2,4} & \mathbf{\Pi}_{2,5} & \mathbf{\Pi}_{2,6} \\ \mathbf{0} & \mathbf{\Pi}_{3,2} & \mathbf{\Pi}_{3,3} & \mathbf{0} & \mathbf{0} & \mathbf{\Pi}_{3,6} \end{bmatrix}_{3M \times 6M}$$





- Protographs are often represented using a bipartite **Tanner graph**

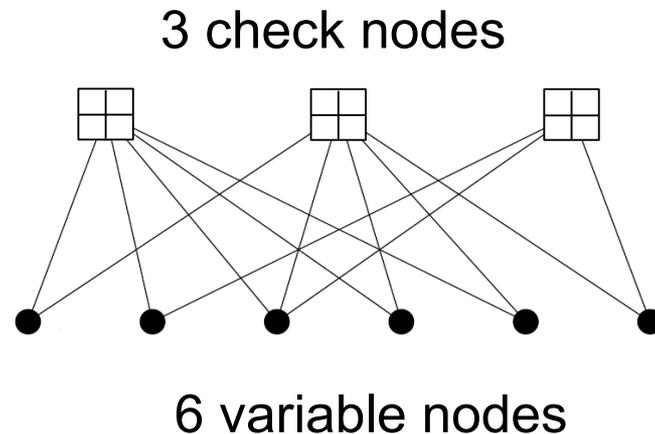
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- The collection of all possible parity-check matrices with lifting factor  $M$  forms a **code ensemble**, where all the codes share a **common structure**

$$\mathbf{H} = \begin{bmatrix} \mathbf{\Pi}_{1,1} & \mathbf{\Pi}_{1,2} & \mathbf{\Pi}_{1,3} & \mathbf{\Pi}_{1,4} & \mathbf{\Pi}_{1,5} & \mathbf{0} \\ \mathbf{\Pi}_{2,1} & \mathbf{0} & \mathbf{\Pi}_{2,3} & \mathbf{\Pi}_{2,4} & \mathbf{\Pi}_{2,5} & \mathbf{\Pi}_{2,6} \\ \mathbf{0} & \mathbf{\Pi}_{3,2} & \mathbf{\Pi}_{3,3} & \mathbf{0} & \mathbf{0} & \mathbf{\Pi}_{3,6} \end{bmatrix}$$

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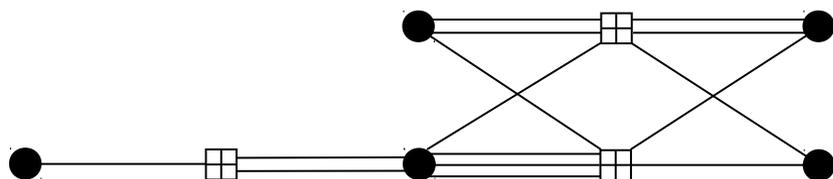
**Example:** protograph construction of a **(2,3)-regular** QC-LDPC block code

$$\mathbf{B} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}_{2 \times 3}$$



# Multi-Edge Protographs

- Protographs can have repeated edges (corresponding to integer values greater than one in  $\mathbf{B}$ )

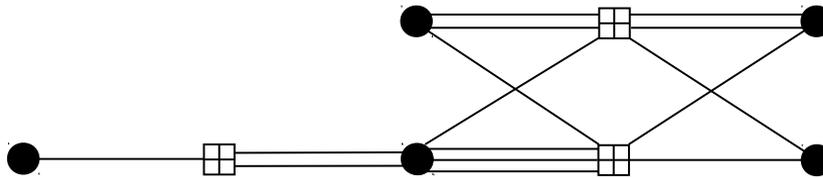


$$\mathbf{B} = \begin{bmatrix} 2 & 2 & 0 & 1 & 1 \\ 0 & 0 & 1 & 2 & 0 \\ 1 & 1 & 0 & 3 & 1 \end{bmatrix}_{3 \times 5}$$

- Note that this makes no sense without lifting

[DDJA09] D. Divsalar, S. Dolinar, C. Jones, and K. Andrews, “Capacity-approaching protograph codes”, *IEEE Journal on Select Areas in Communications*, vol. 27, no. 6 Aug. 2009.

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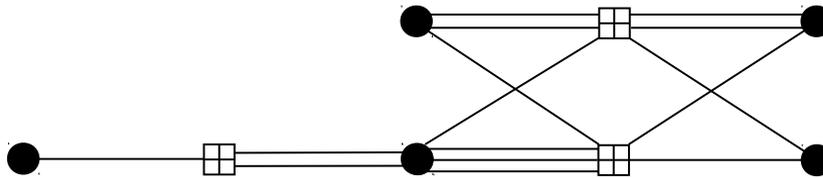
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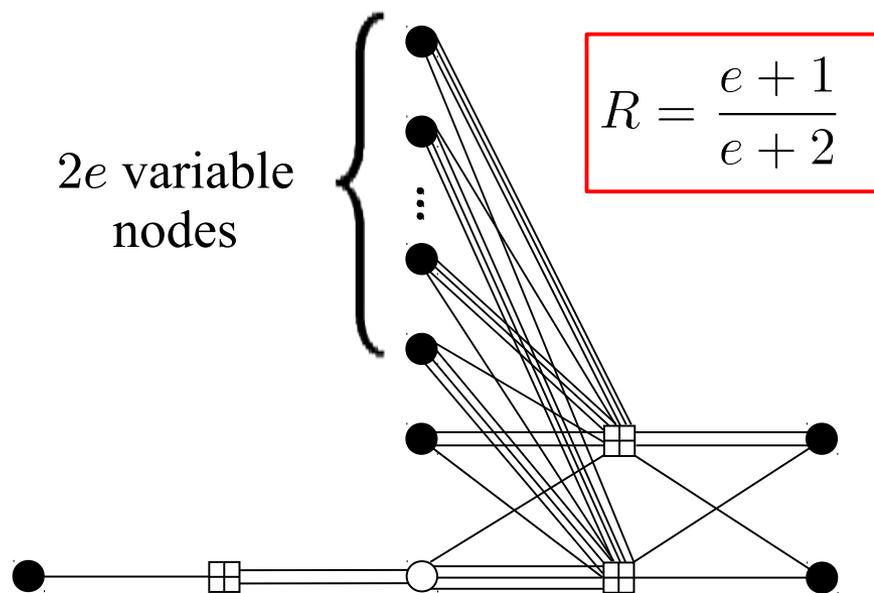
➔ denser graphs!

➔ can also be QC (using **circulant matrices**)!

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# 'Good' Protographs

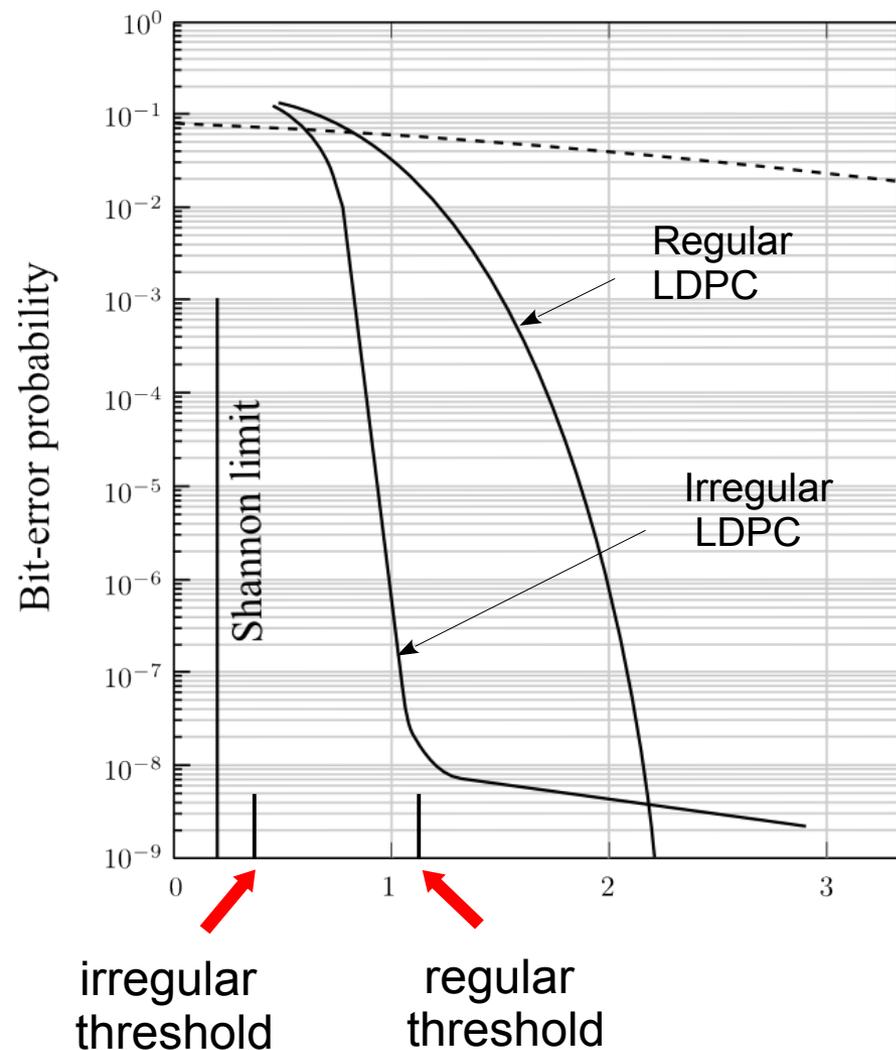
- Ensemble average properties can be easily calculated from a protograph, thus simplifying the construction of 'good' code ensembles.
  - Iterative decoding thresholds close to capacity for irregular protographs
  - Minimum distance growing linearly with block length (**asymptotically good**) for regular and some irregular protographs



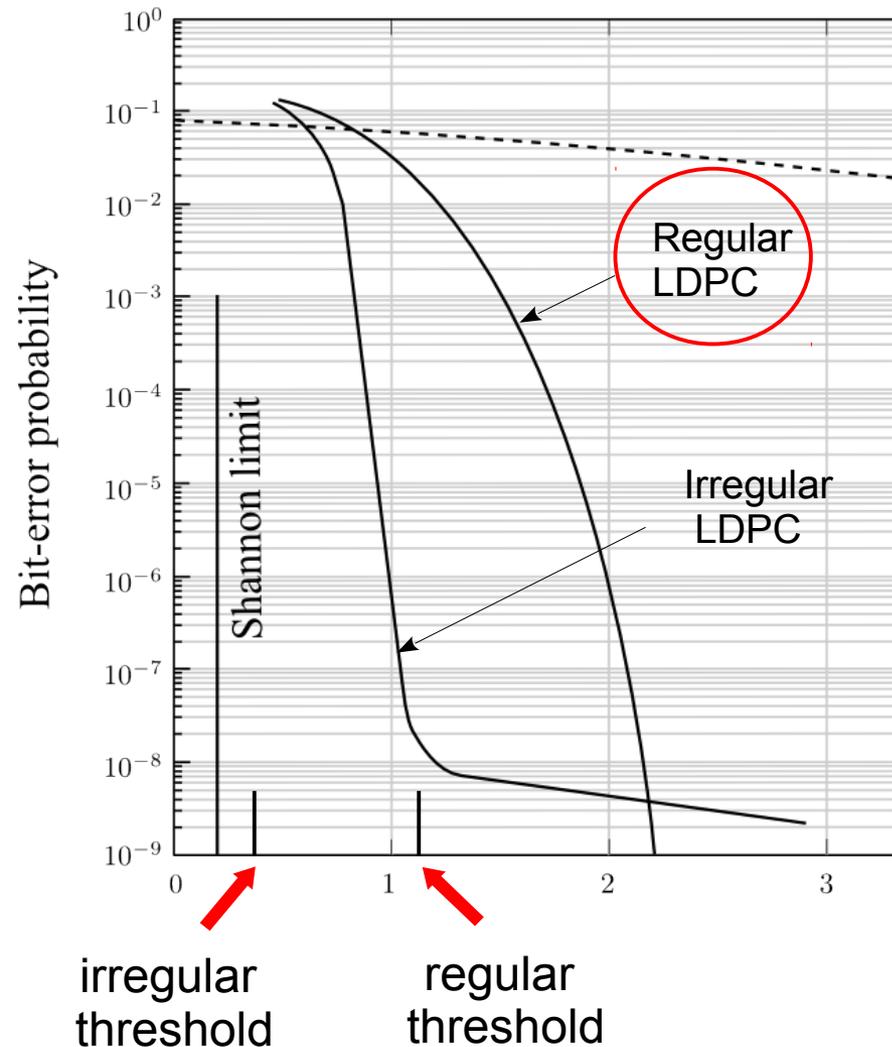
Rate	Threshold $(E_b/N_0)^*$	Capacity $(E_b/N_0)_{Sh}$	Distance growth rate
1/2	0.628	0.187	0.01450
2/3	1.450	1.059	0.00582
3/4	2.005	1.628	0.00323
4/5	2.413	2.040	0.00207
5/6	2.733	2.362	0.00145
6/7	2.993	2.625	0.00108

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# Regular vs. Irregular LDPC codes



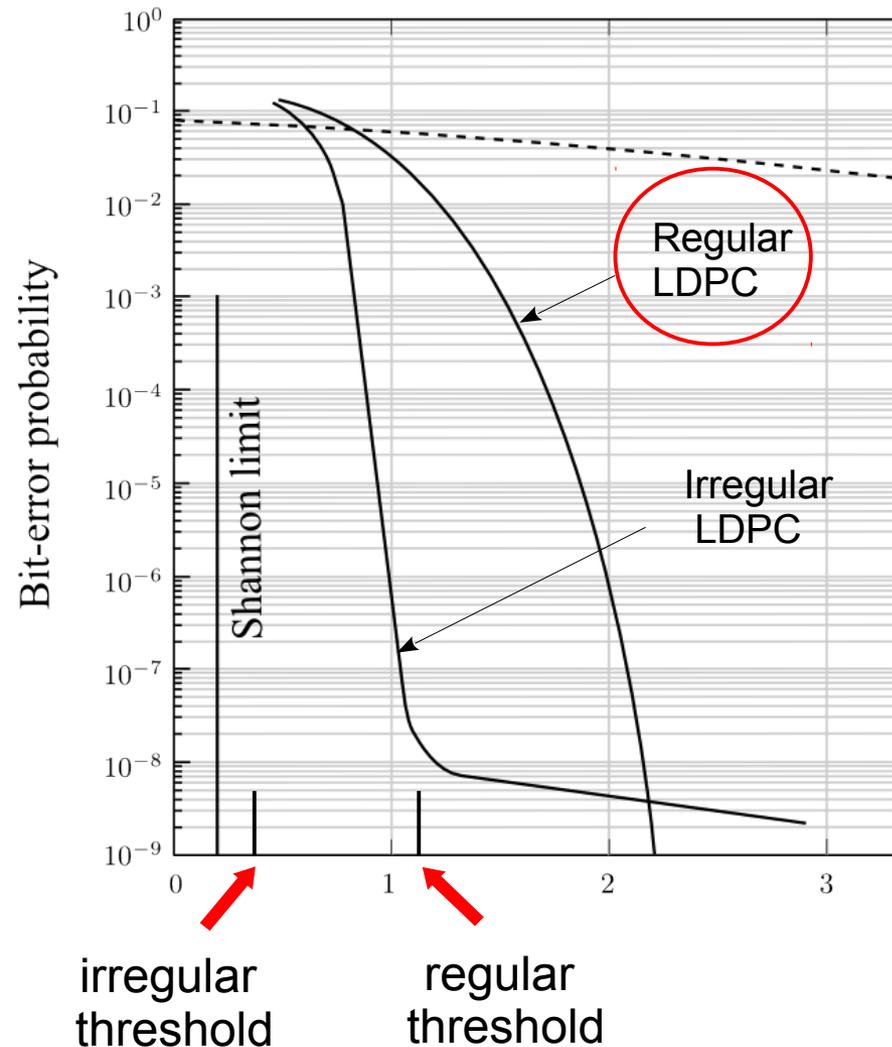
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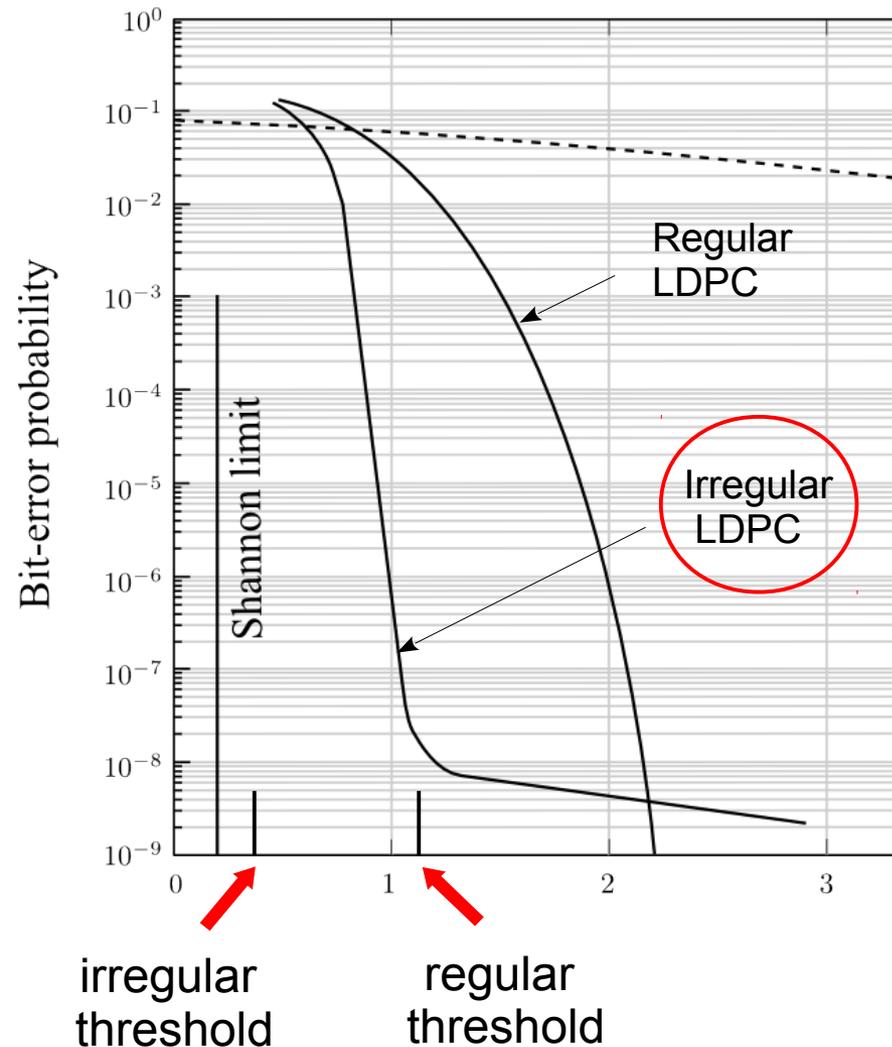
- ✓ structure **aids implementation**
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- ✗ thresholds **far from capacity**

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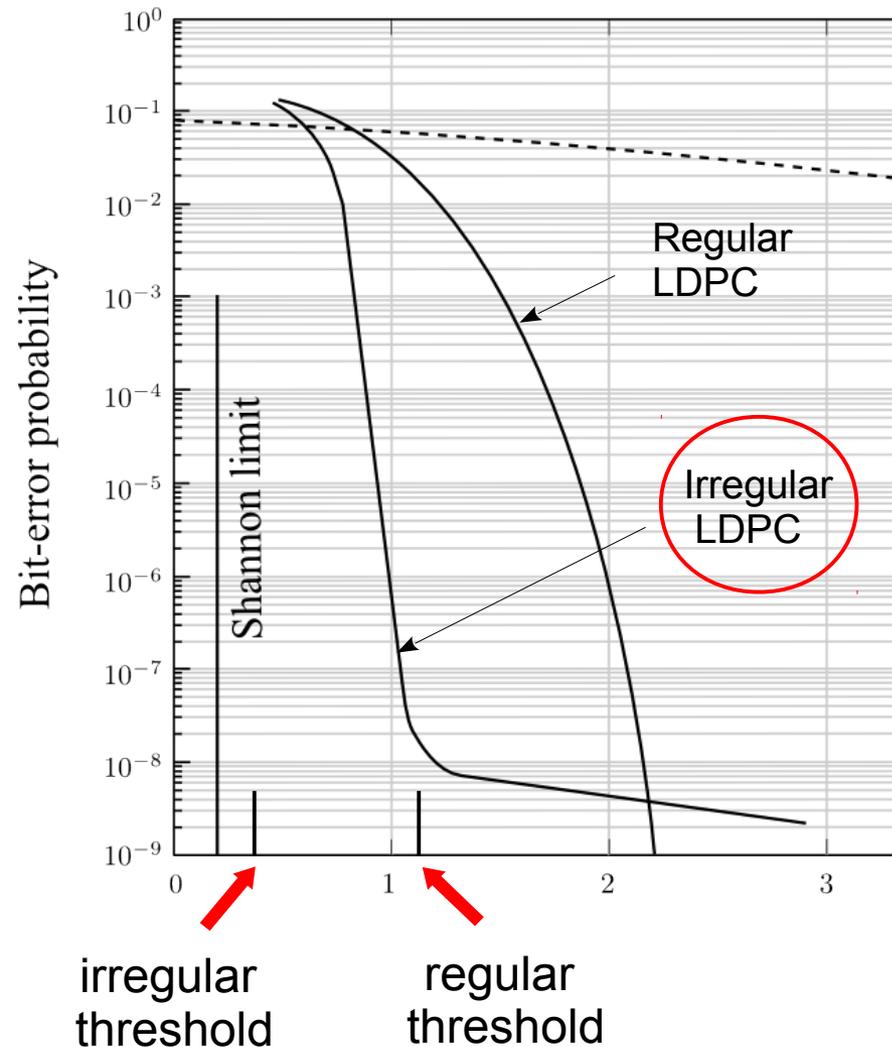
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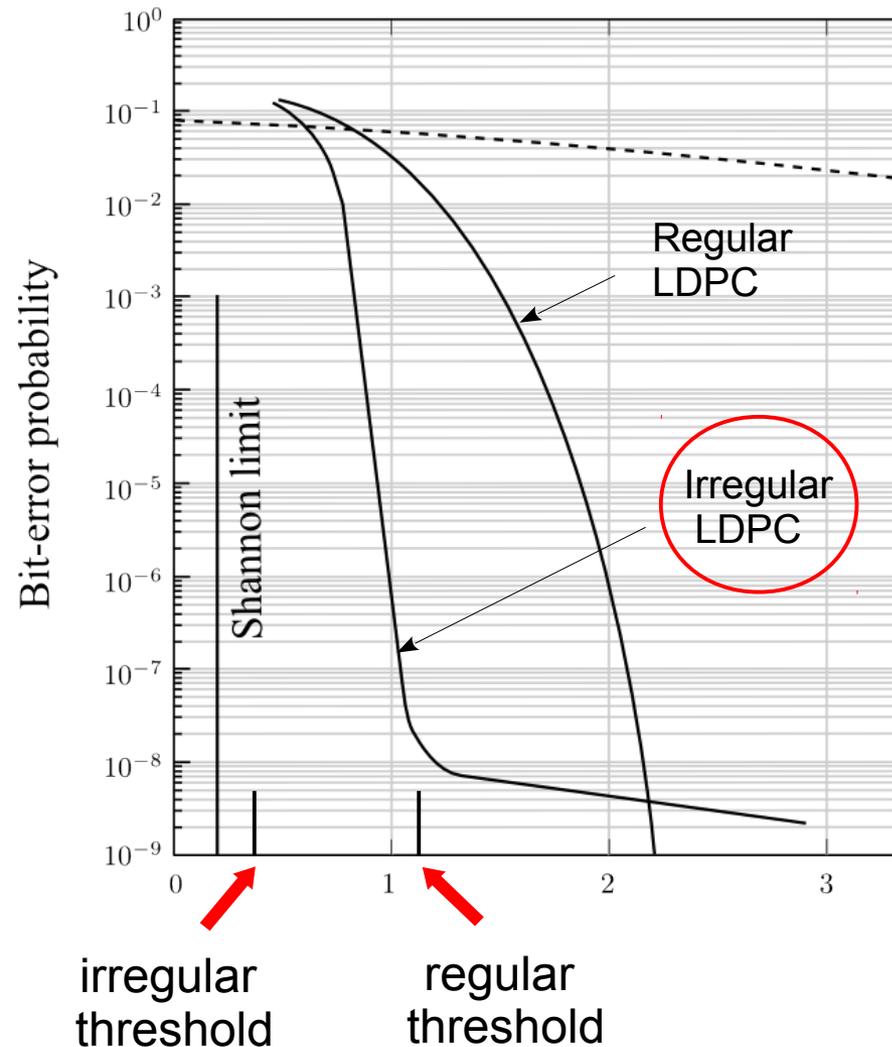
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- **Spatially coupled** LDPC codes combine all of the positive features!

## ■ LDPC Block Codes

- ➔ Parity-check matrix and Tanner graph representations, minimum distance bounds, iterative decoding thresholds, protograph-based constructions

## ■ Spatially Coupled LDPC Codes

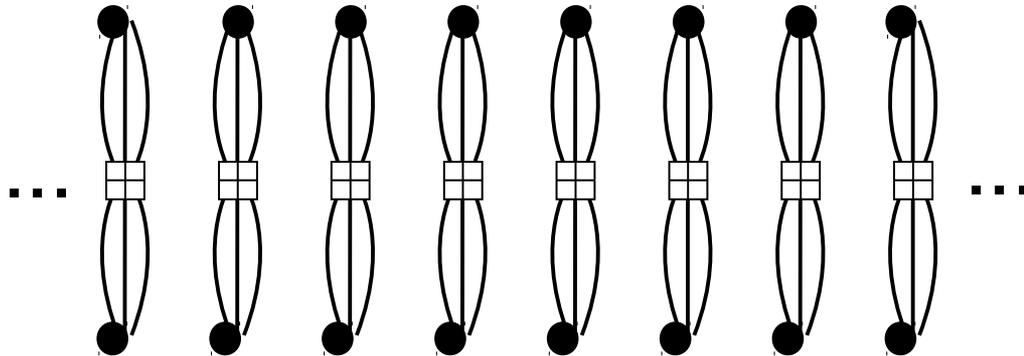
- ➔ Protograph representation, edge-spreading construction, termination
- ➔ Iterative decoding thresholds, threshold saturation, minimum distance

## ■ Practical Considerations

- ➔ Window decoding; performance, latency, and complexity comparisons to LDPC block codes; rate-compatibility; implementation aspects

# Spatially Coupled Protographs

- Consider transmission of consecutive blocks (protograph representation):

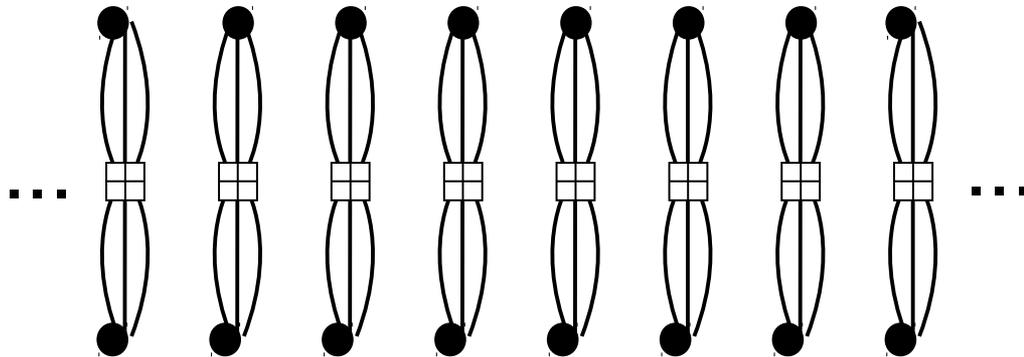


$$\mathbf{B} = \begin{bmatrix} 3 & 3 \end{bmatrix}_{b_c \times b_v}$$

(3,6)-regular  
LDPC-BC  
base matrix

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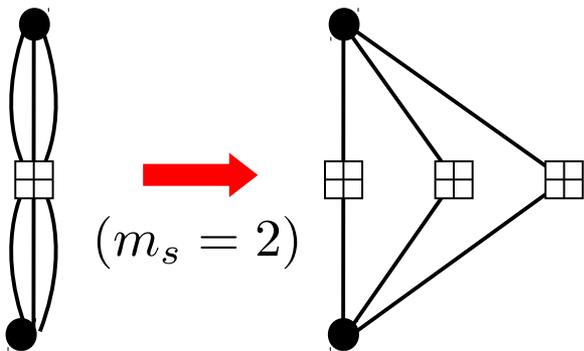
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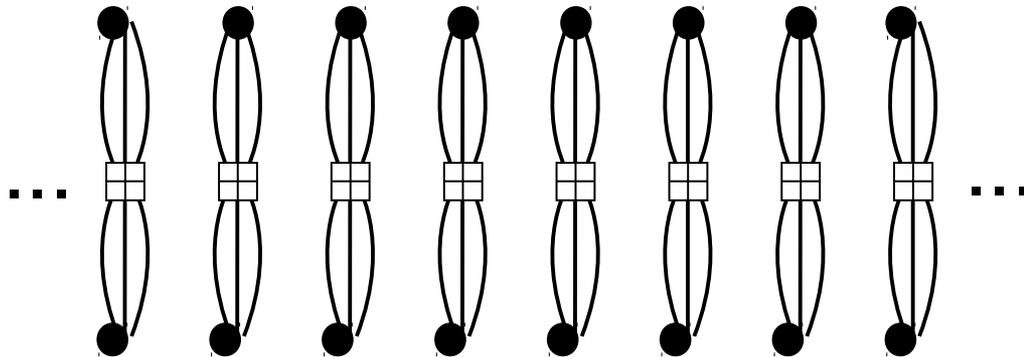
- Blocks are **spatially coupled** (introducing **memory**) by **spreading edges** over time:



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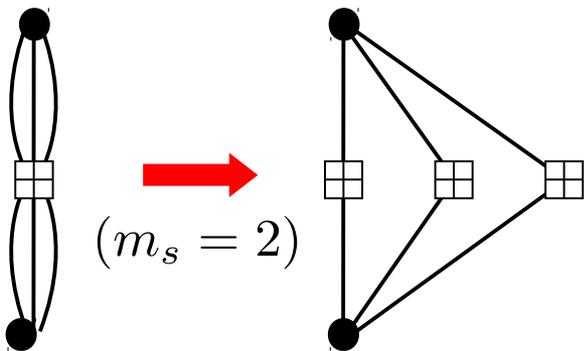
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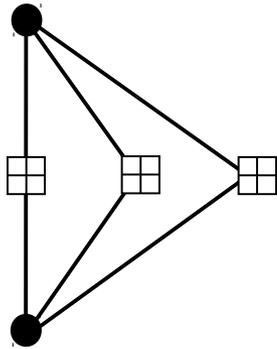


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- Spreading constraint:**

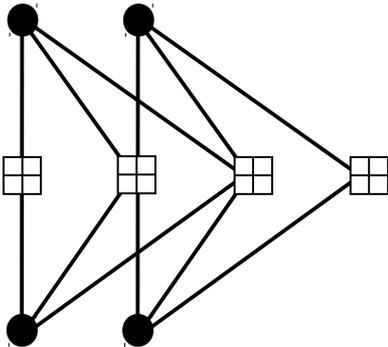
$$\sum_{i=0}^{m_s} \mathbf{B}_i = \mathbf{B} \quad (\mathbf{B}_i \text{ has size } b_c \times b_v)$$

- Transmission of consecutive spatially coupled (SC) blocks results in a **convolutional protograph**:



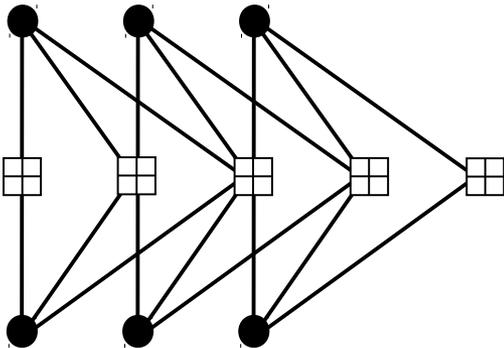
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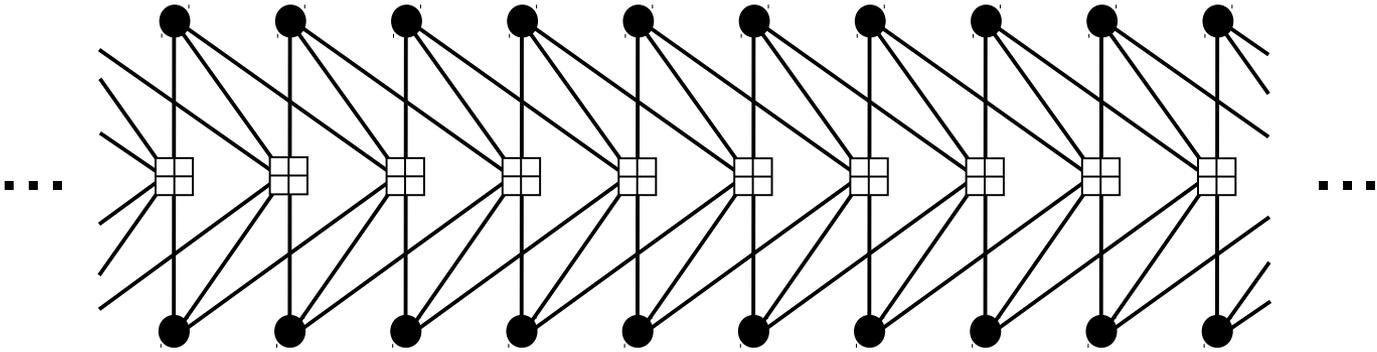
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- An ensemble of (3,6)-regular SC-LDPC codes can be created from the **convolutional protograph** by the graph lifting operation

$$\mathbf{B}_{[-\infty, \infty]} = \left[ \begin{array}{cccc} \ddots & \ddots & \ddots & \\ \mathbf{B}_2 & \mathbf{B}_1 & \mathbf{B}_0 & \\ & \mathbf{B}_2 & \mathbf{B}_1 & \mathbf{B}_0 \\ & & \mathbf{B}_2 & \mathbf{B}_1 & \mathbf{B}_0 \\ & & & \ddots & \ddots & \ddots \end{array} \right]$$

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 & \ddots & & & & \\
 & & \ddots & & & \\
 \boxed{1} & \boxed{1} & & & & & \\
 & \boxed{1} & \boxed{1} & & & & \\
 & & \boxed{1} & \boxed{1} & & & \\
 & & & \ddots & & & \\
 & & & & \ddots & & \\
 & & & & & \ddots & \\
 & & & & & & \ddots
 \end{array} \right] \quad \begin{array}{l}
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 \end{array}$$

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1	1	1	1	1	1				
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**Graph lifting:**  $\Pi_{i,j}$  is an  $M \times M$  permutation matrix ↓  $\nu_s = Mb_v(m_s + 1) = 6M$

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$\Pi_{5,t}$	$\Pi_{4,t}$	$\Pi_{3,t}$	$\Pi_{2,t}$	$\Pi_{1,t}$	$\Pi_{0,t}$				
		$\Pi_{5,t+1}$	$\Pi_{4,t+1}$	$\Pi_{3,t+1}$	$\Pi_{2,t+1}$	$\Pi_{1,t+1}$	$\Pi_{0,t+1}$		
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- If each permutation matrix  $\Pi_{i,j}$  is **circulant**, the codes are **quasi-cyclic**



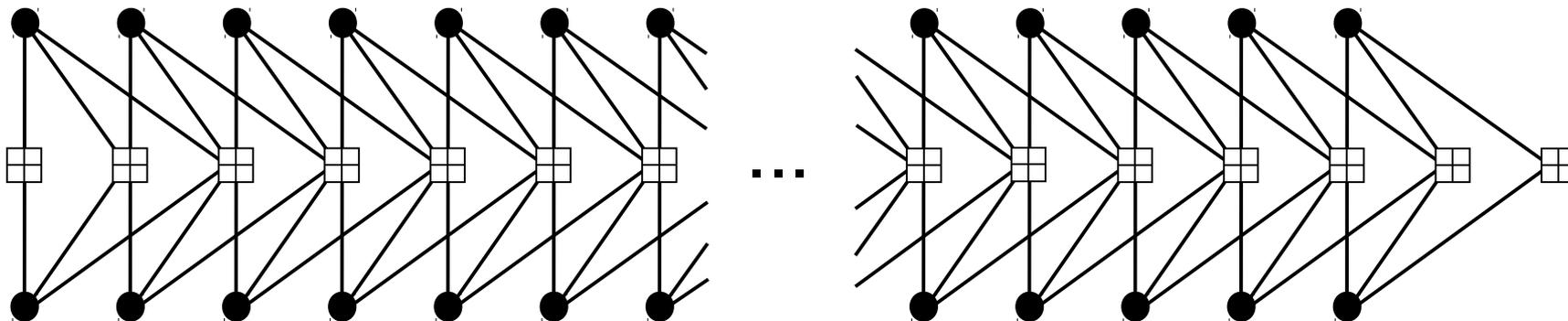






# Thresholds of SC-LDPC Codes

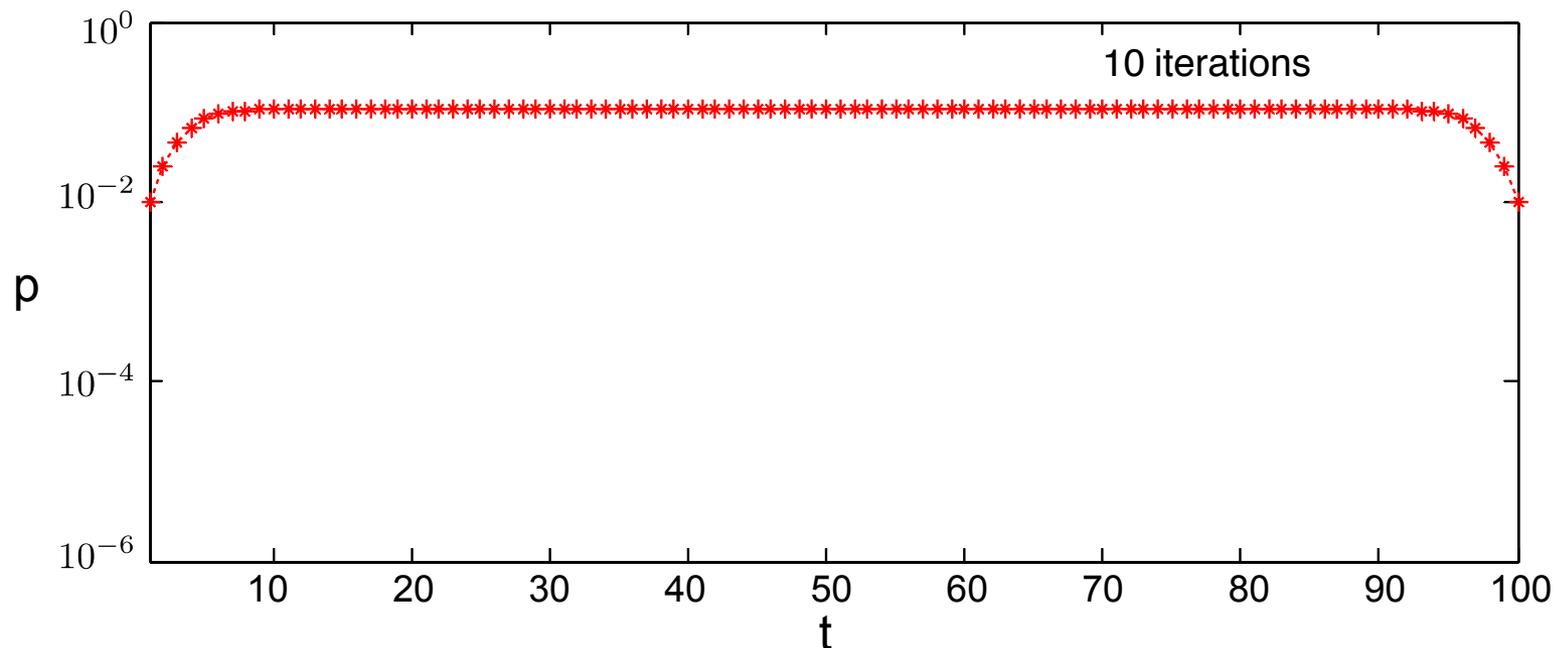
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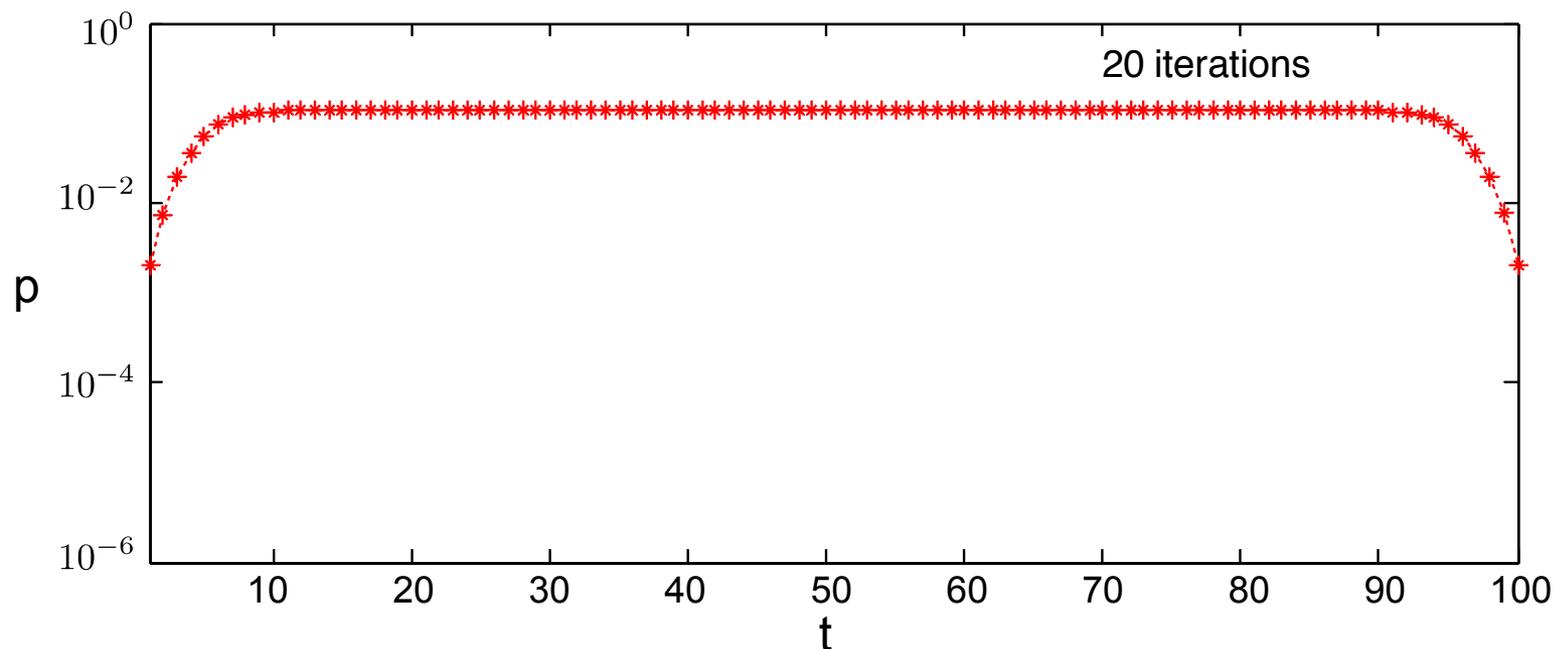
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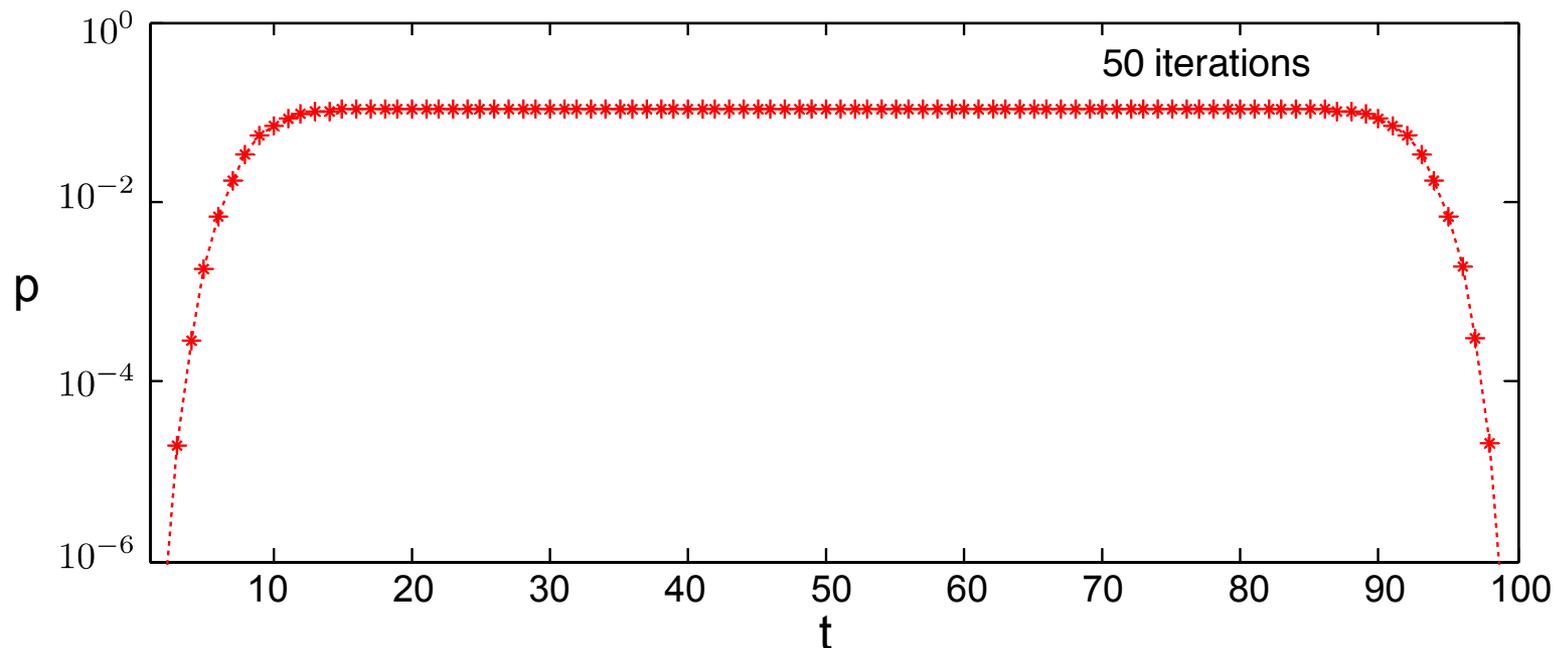
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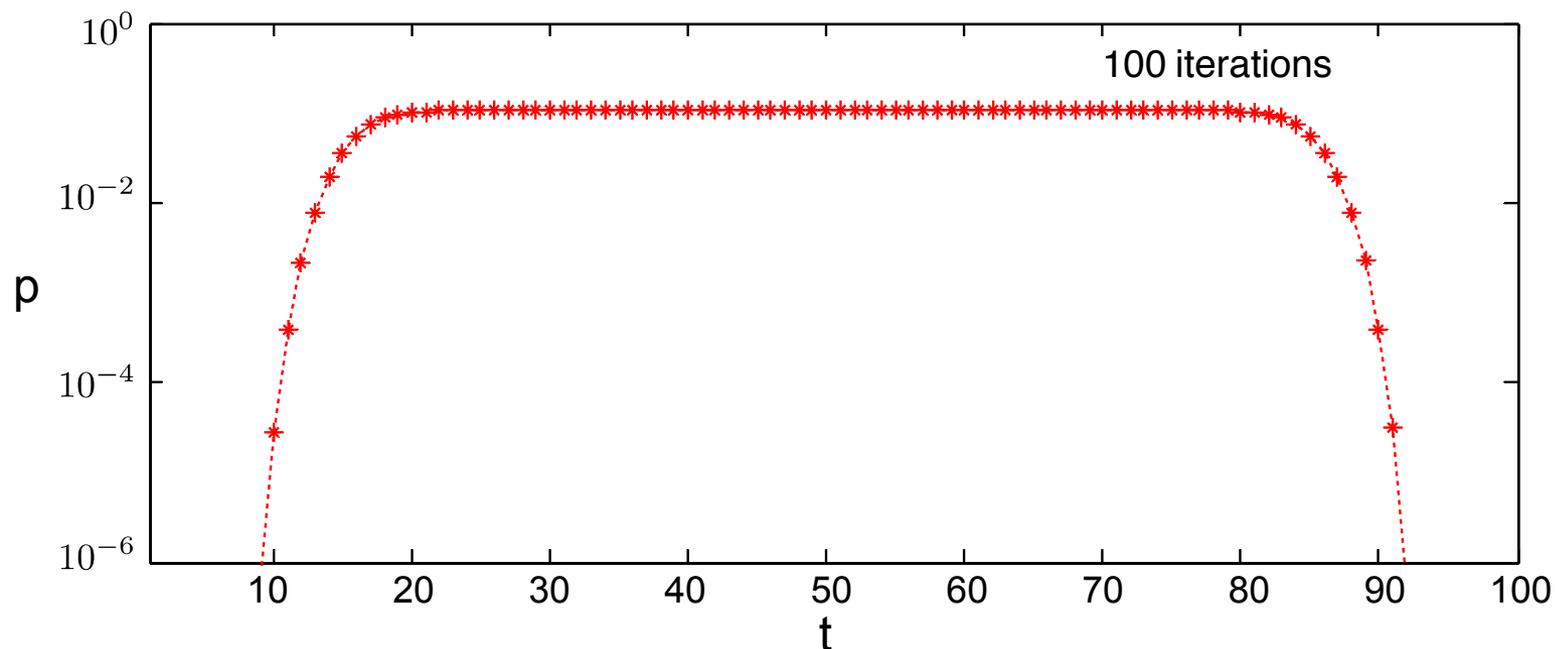
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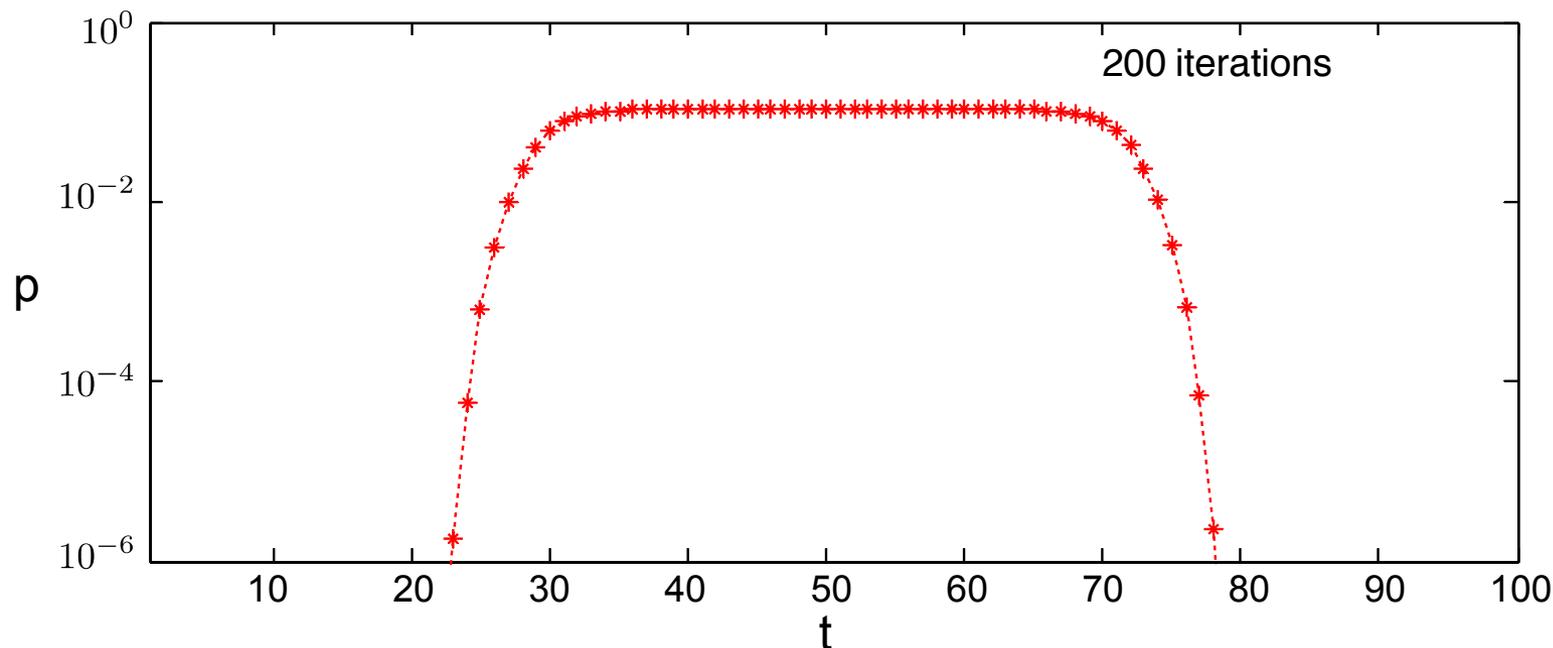
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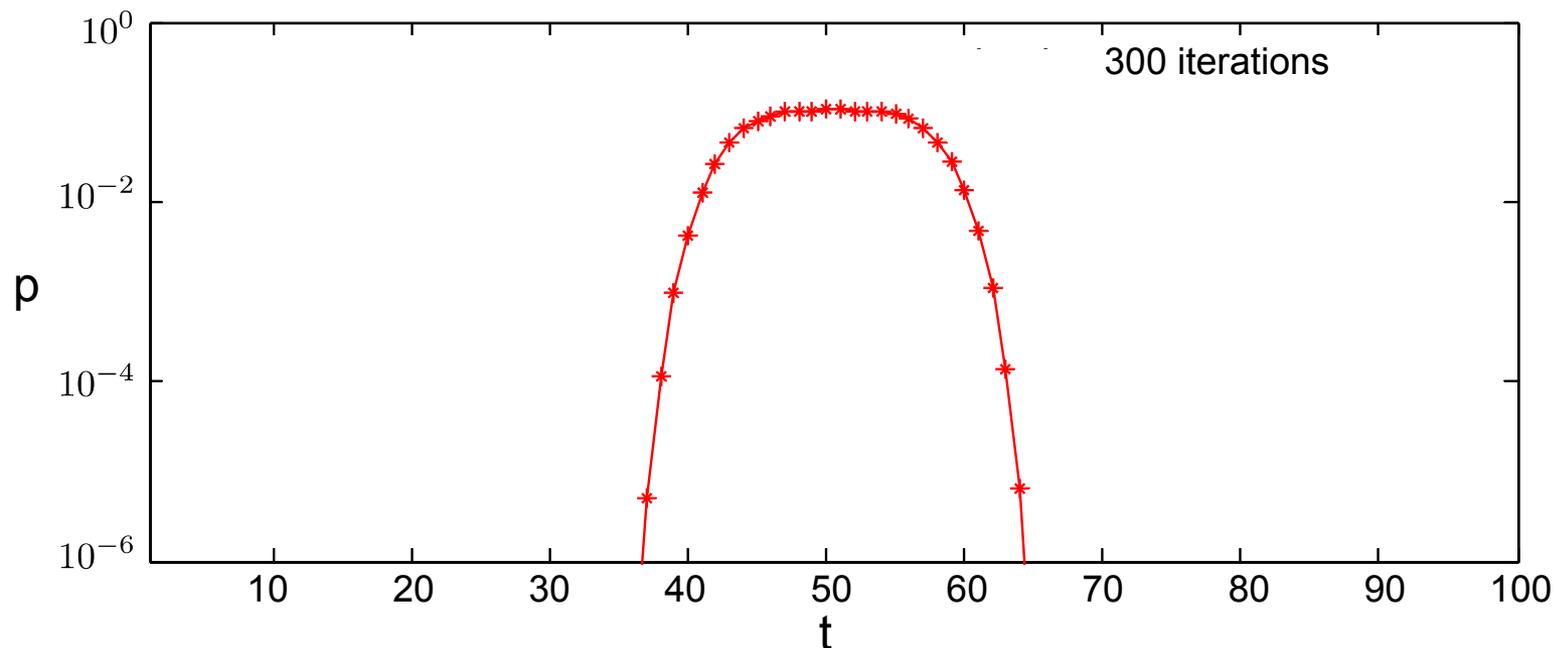
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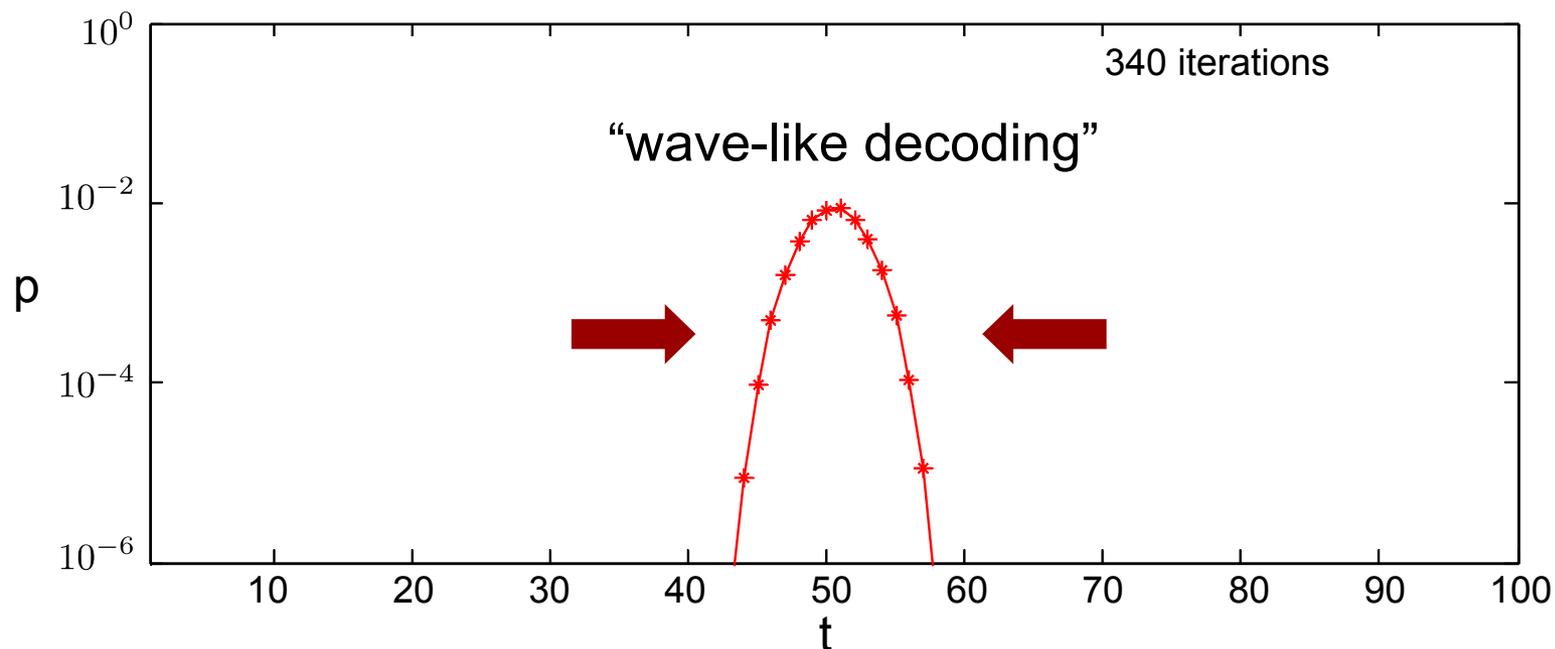
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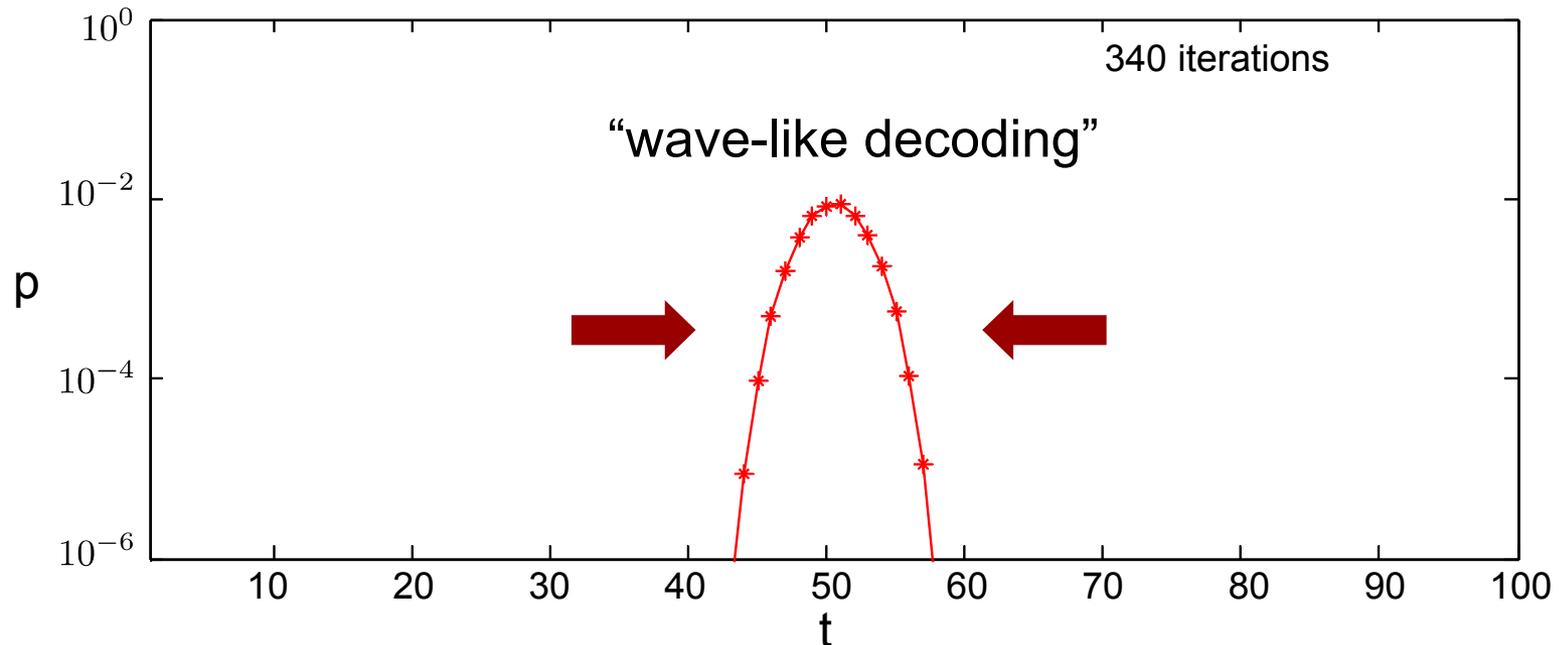
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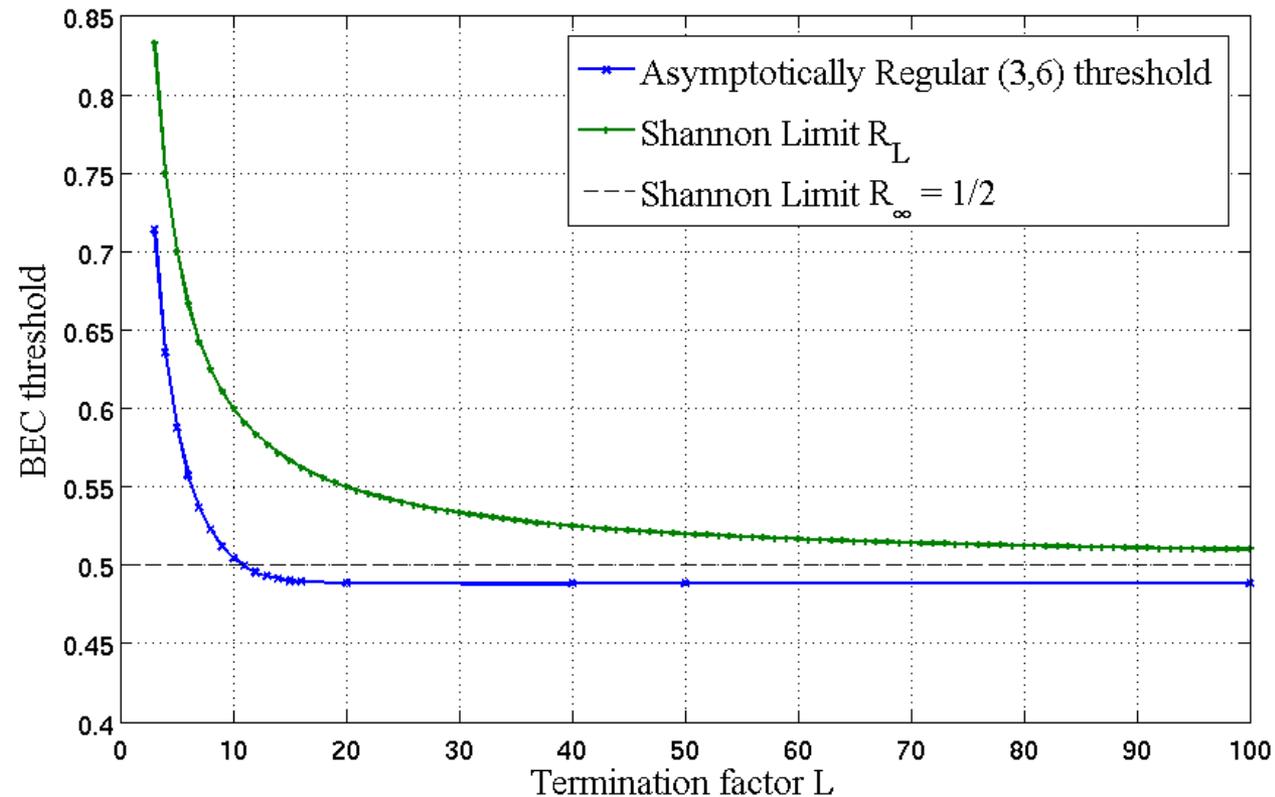


- Note: the **fraction** of **lower degree** nodes tends to zero as  $L \rightarrow \infty$ , i.e., the codes are **asymptotically regular**.

# Thresholds of SC-LDPC Codes

- **Density evolution** can be applied to the protograph-based ensembles with  $M \rightarrow \infty$  [Sridharan et al. '04]:

**Example:** BEC



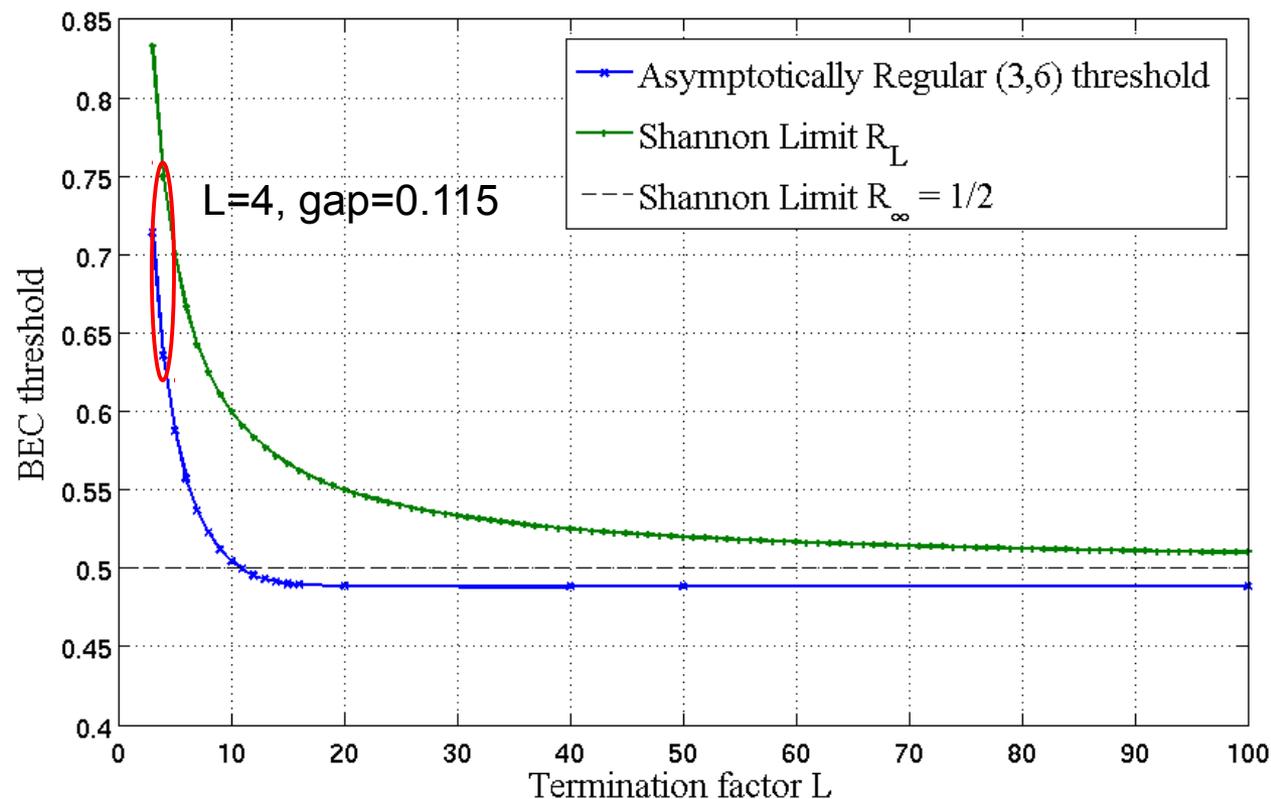
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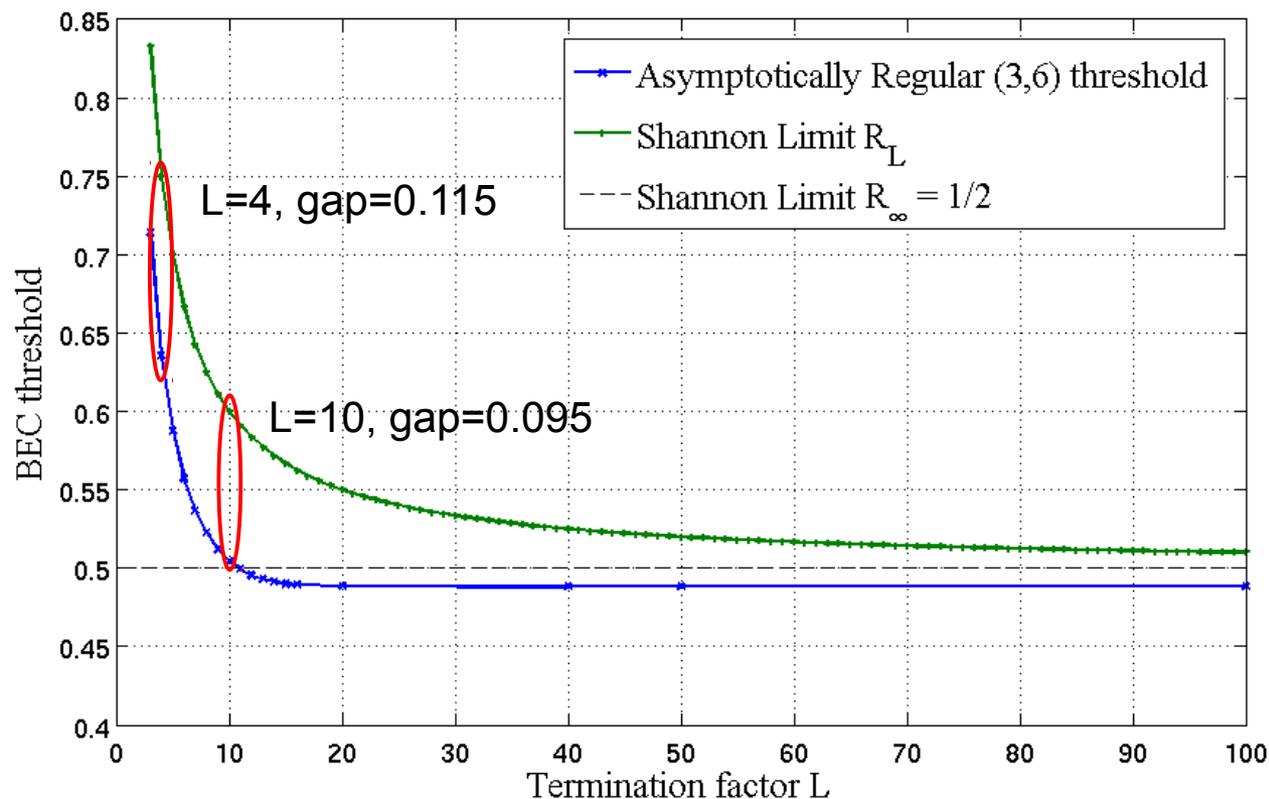
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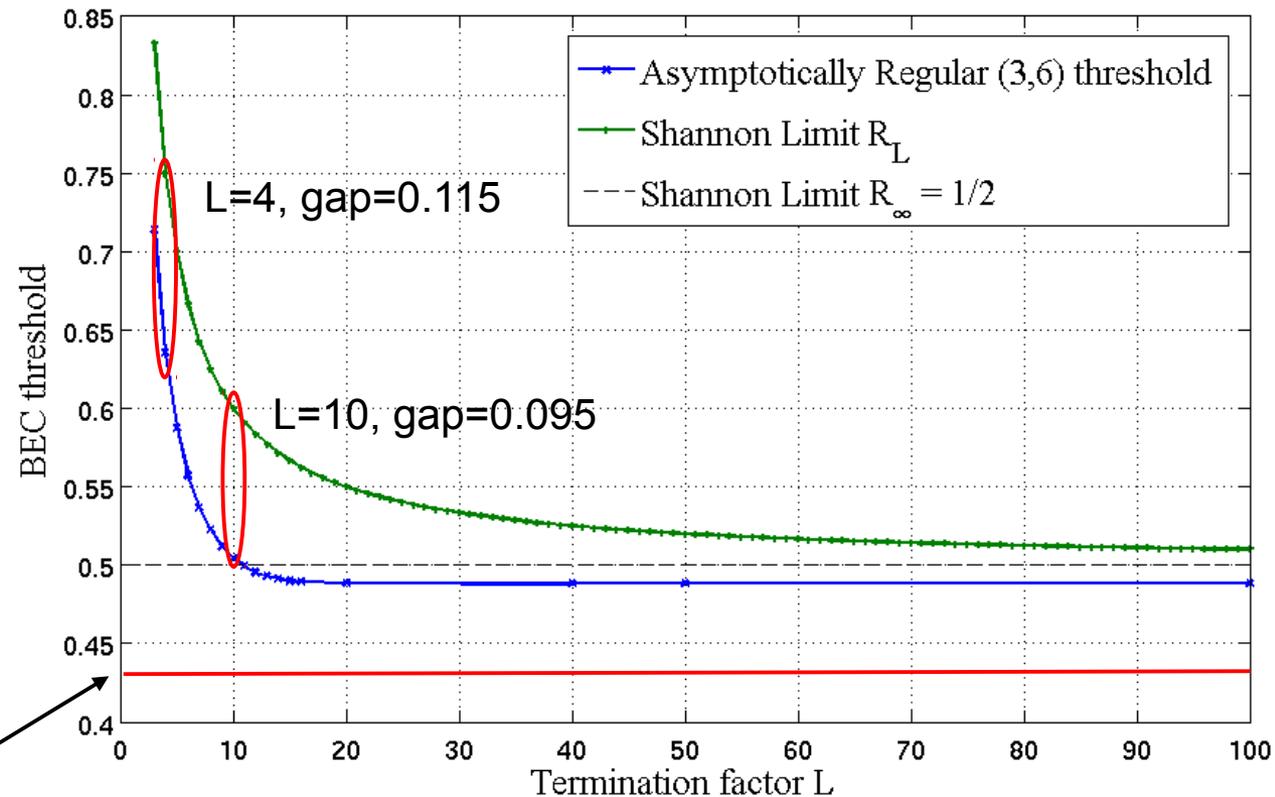
⋮

$$L \rightarrow \infty, R \rightarrow 1/2$$

$$\epsilon^* = 0.488, \epsilon_{Sh} = 0.5$$

(3,6)-regular block code:

$$\epsilon^* = 0.429$$



# Thresholds of SC-LDPC Codes

## Iterative decoding thresholds (protograph-based ensembles)

BEC

$(J, K)$	$\epsilon_{SC}^*$	$\epsilon_{blk}^*$
(3,6)	0.488	0.429
(4,8)	0.497	0.383
(5,10)	0.499	0.341

AWGN

$(J, K)$	$E_b/N_{o_{SC}}$	$E_b/N_{o_{blk}}$
(3,6)	0.46 dB	1.11 dB
(4,8)	0.26 dB	1.61 dB
(5,10)	0.21 dB	2.04 dB

- We observe a **significant improvement** in the thresholds of SC-LDPC codes compared to the associated LDPC block codes (LDPC-BCs) due to the lower degree check nodes at the ends of the graph and the wave-like decoding.

[LSCZ10] M. Lentmaier, A. Sridharan, D. J. Costello, Jr., and K.Sh. Zigangirov, "Iterative decoding threshold analysis for LDPC convolutional codes," *IEEE Trans. Inf. Theory*, 56:10, Oct. 2010.

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BEC

$(J, K)$	$\epsilon_{SC}^*$	$\epsilon_{blk}^*$
(3,6)	0.488	0.429
(4,8)	0.497	0.383
(5,10)	0.499	0.341

AWGN

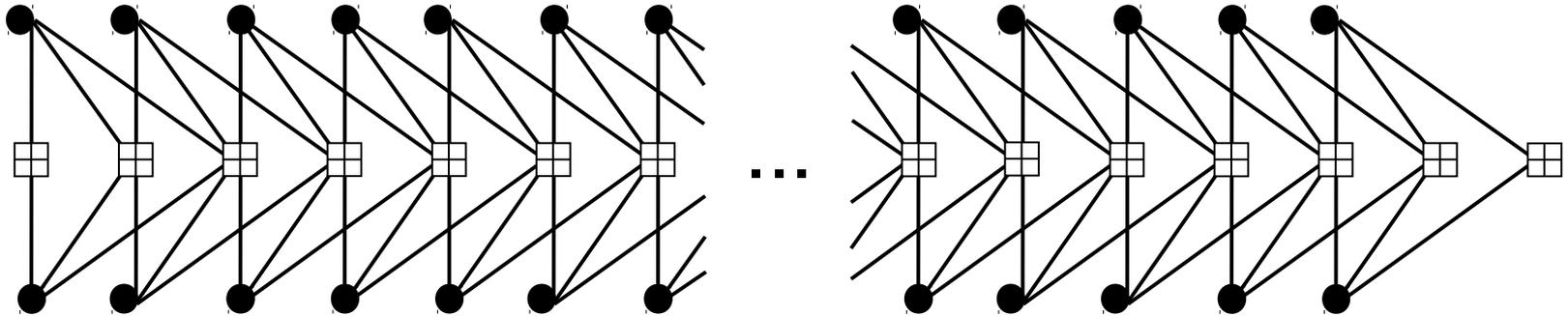
$(J, K)$	$E_b/N_{o_{SC}}$	$E_b/N_{o_{blk}}$
(3,6)	0.46 dB	1.11 dB
(4,8)	0.26 dB	1.61 dB
(5,10)	0.21 dB	2.04 dB

- We observe a **significant improvement** in the thresholds of SC-LDPC codes compared to the associated LDPC block codes (LDPC-BCs) due to the lower degree check nodes at the ends of the graph and the wave-like decoding.
- In contrast to LDPC-BCs, the iterative decoding thresholds of SC-LDPC codes **improve** as the graph density increases.

[LSCZ10] M. Lentmaier, A. Sridharan, D. J. Costello, Jr., and K.Sh. Zigangirov, "Iterative decoding threshold analysis for LDPC convolutional codes," *IEEE Trans. Inf. Theory*, 56:10, Oct. 2010.

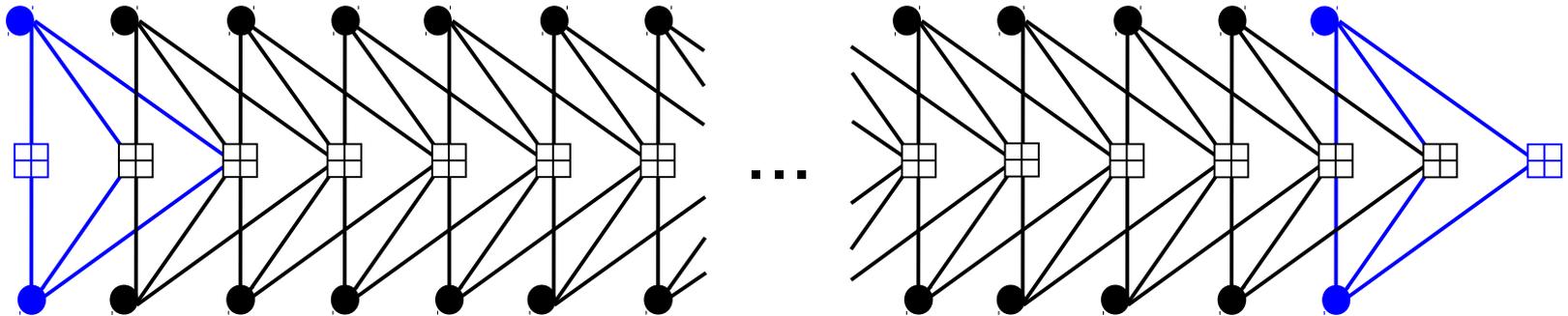
# Why are SC-LDPC Codes Better?

- When symbols are perfectly known (BEC), all adjacent edges can be removed from the Tanner graph.



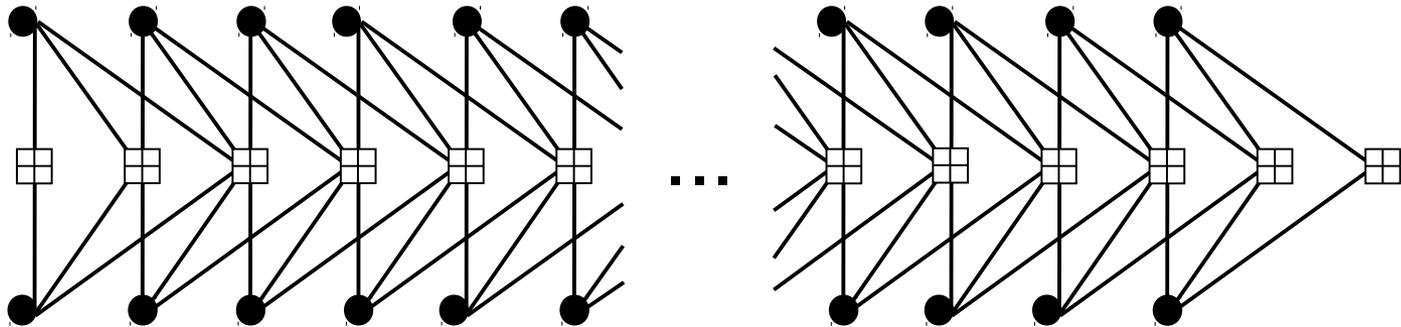
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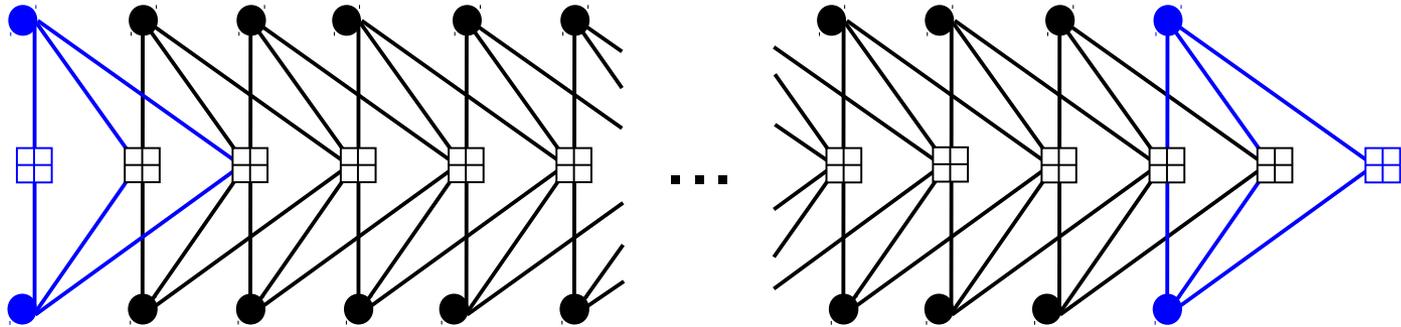
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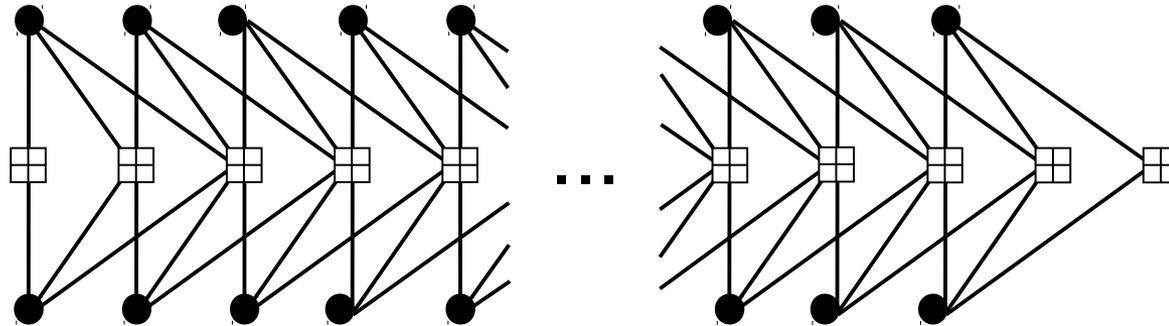
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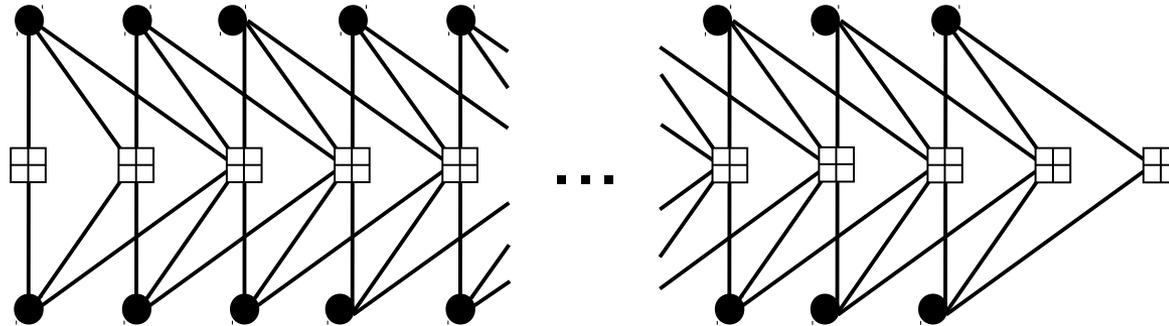
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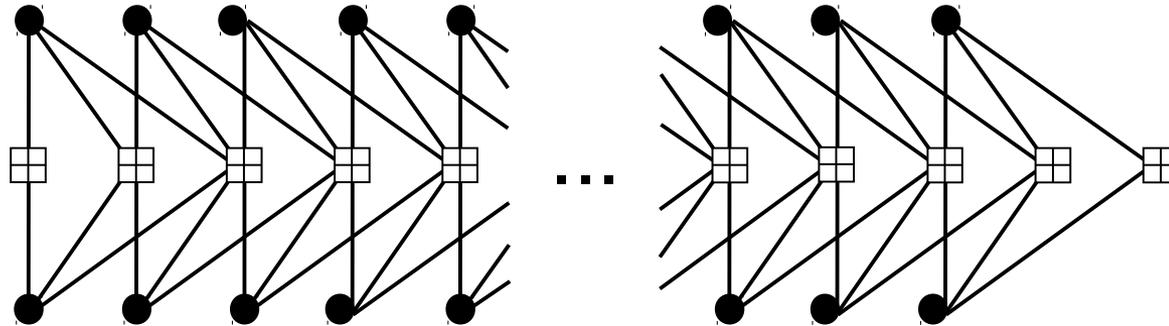


- The **threshold saturates** (converges) to a fixed value numerically indistinguishable from the **maximum a posteriori** (MAP) threshold of the  $(J, K)$ -regular LDPC-BC ensemble as  $L \rightarrow \infty$  [LSCZ10].

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- For a more random-like ensemble, this has been proven analytically, first for the BEC [KRU11], then for all BMS channels [KRU13].

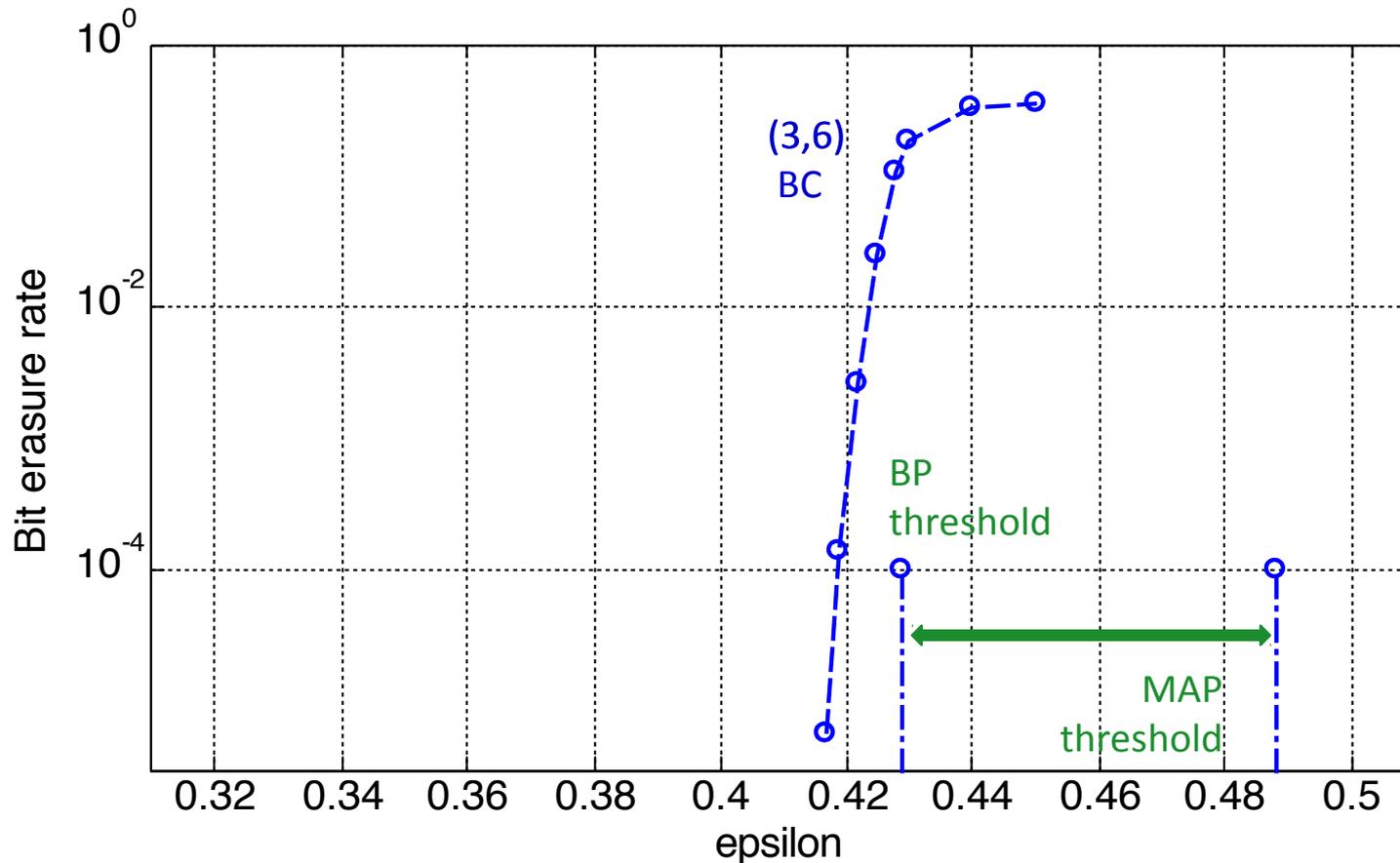
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[KRU11] S. Kudekar, T. J. Richardson and R. Urbanke, “Threshold saturation via spatial coupling: why convolutional LDPC ensembles perform so well over the BEC”, *IEEE Trans. on Inf. Theory*, 57:2, 2011

[KRU13] S. Kudekar, T. J. Richardson and R. Urbanke, “Spatially coupled ensembles universally achieve capacity under belief propagation”, *IEEE Trans. on Inf. Theory*, 59:12, 2013.

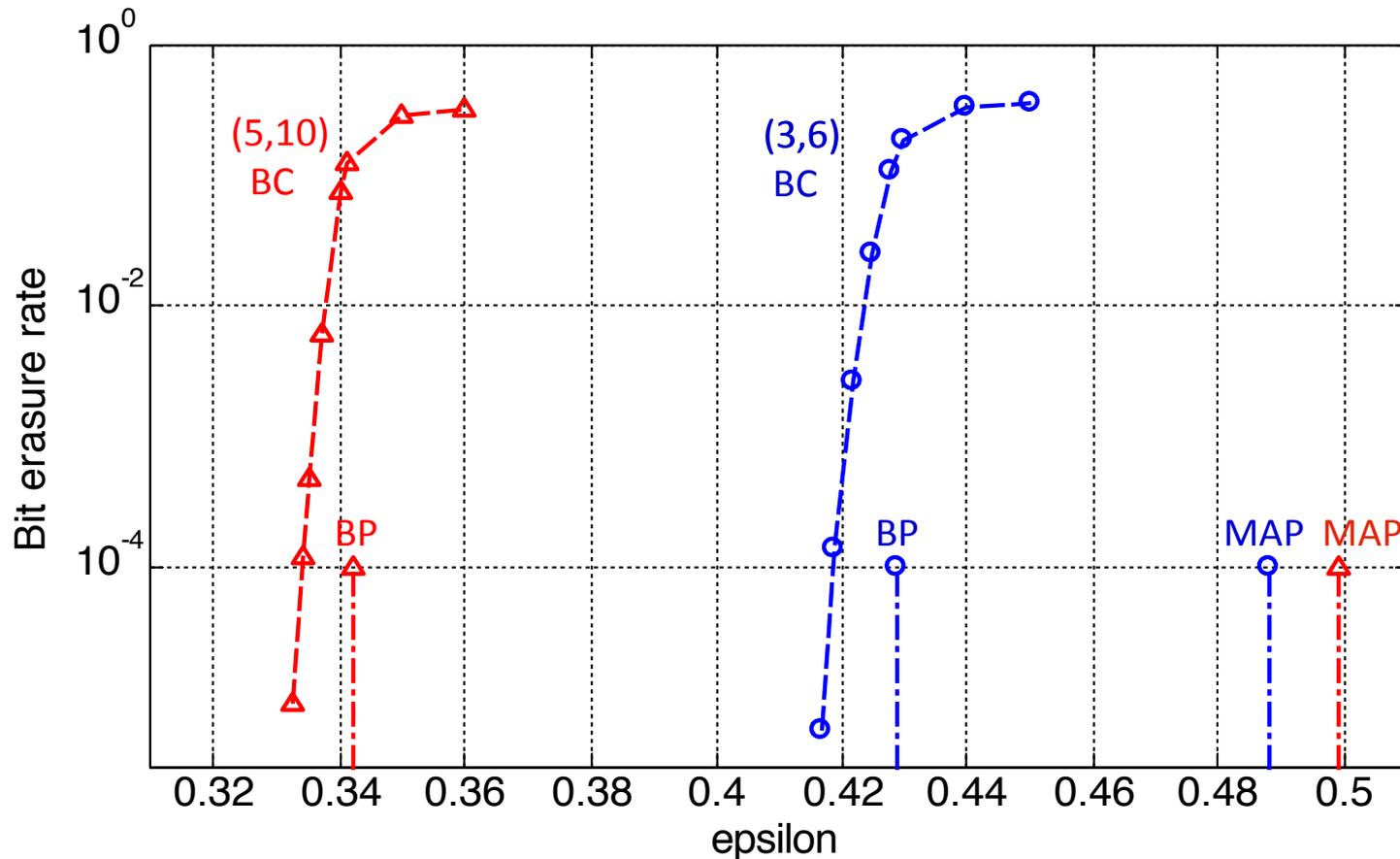
# Threshold Saturation (BEC)

BP = iterative (suboptimal) decoding threshold  
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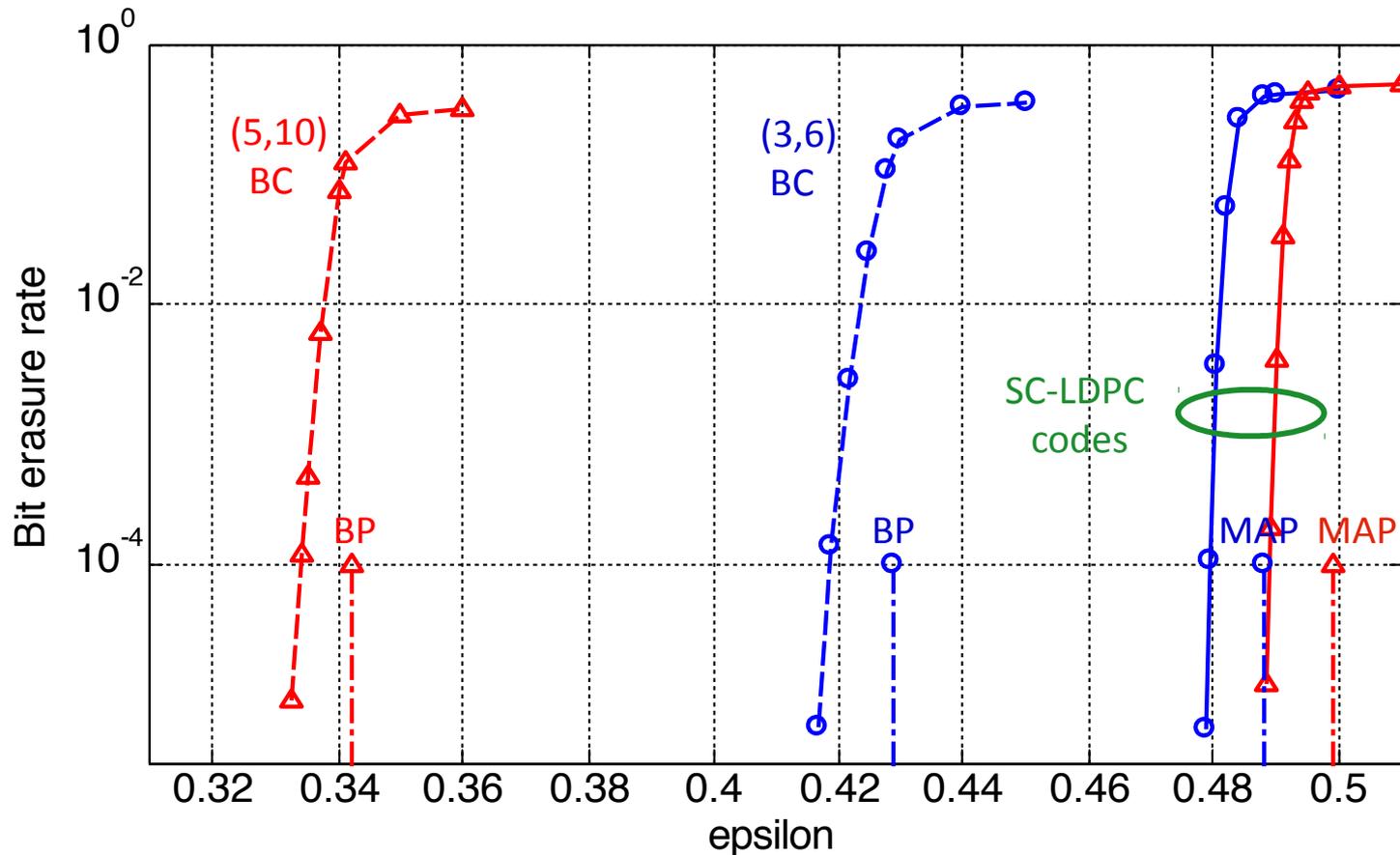
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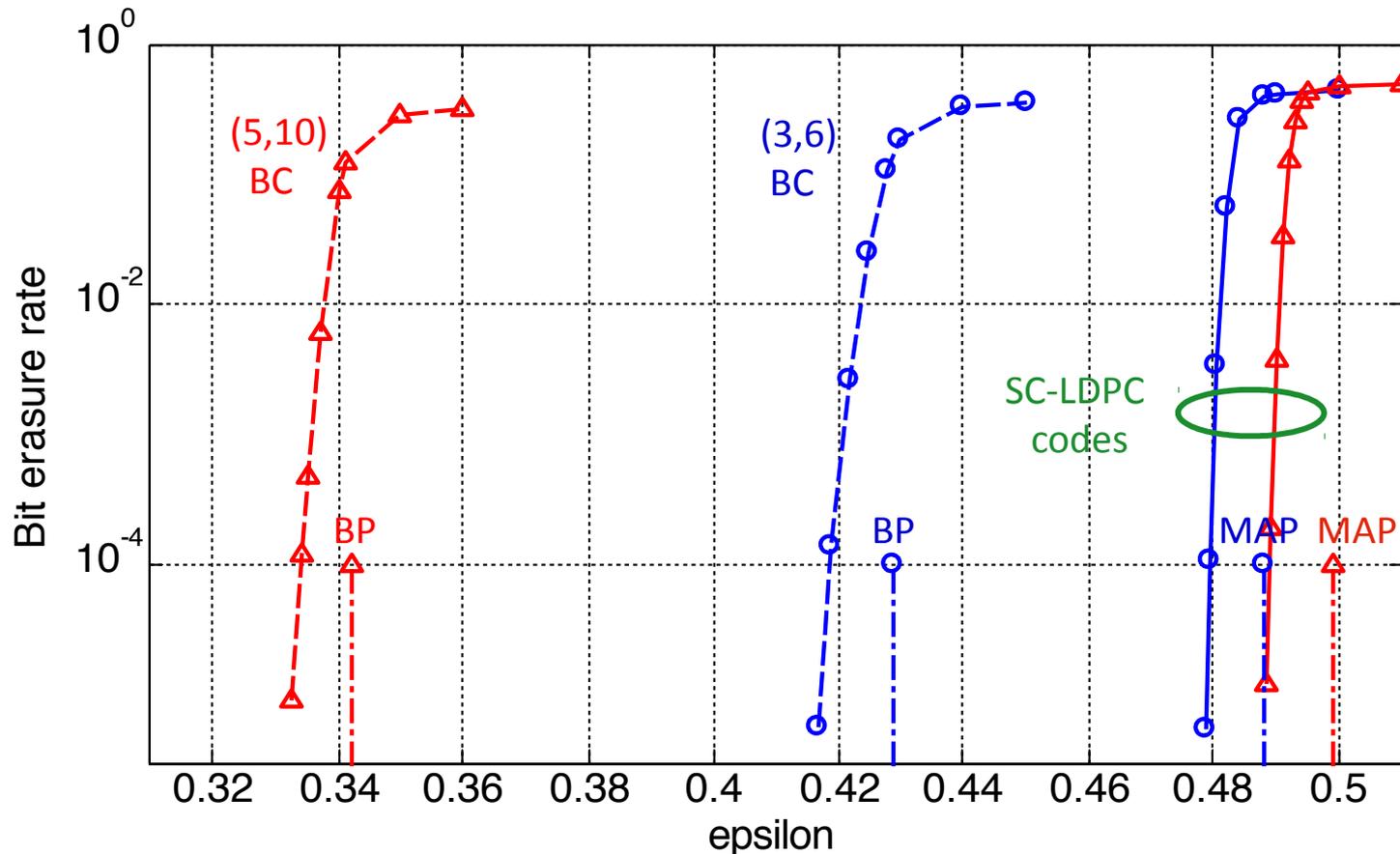
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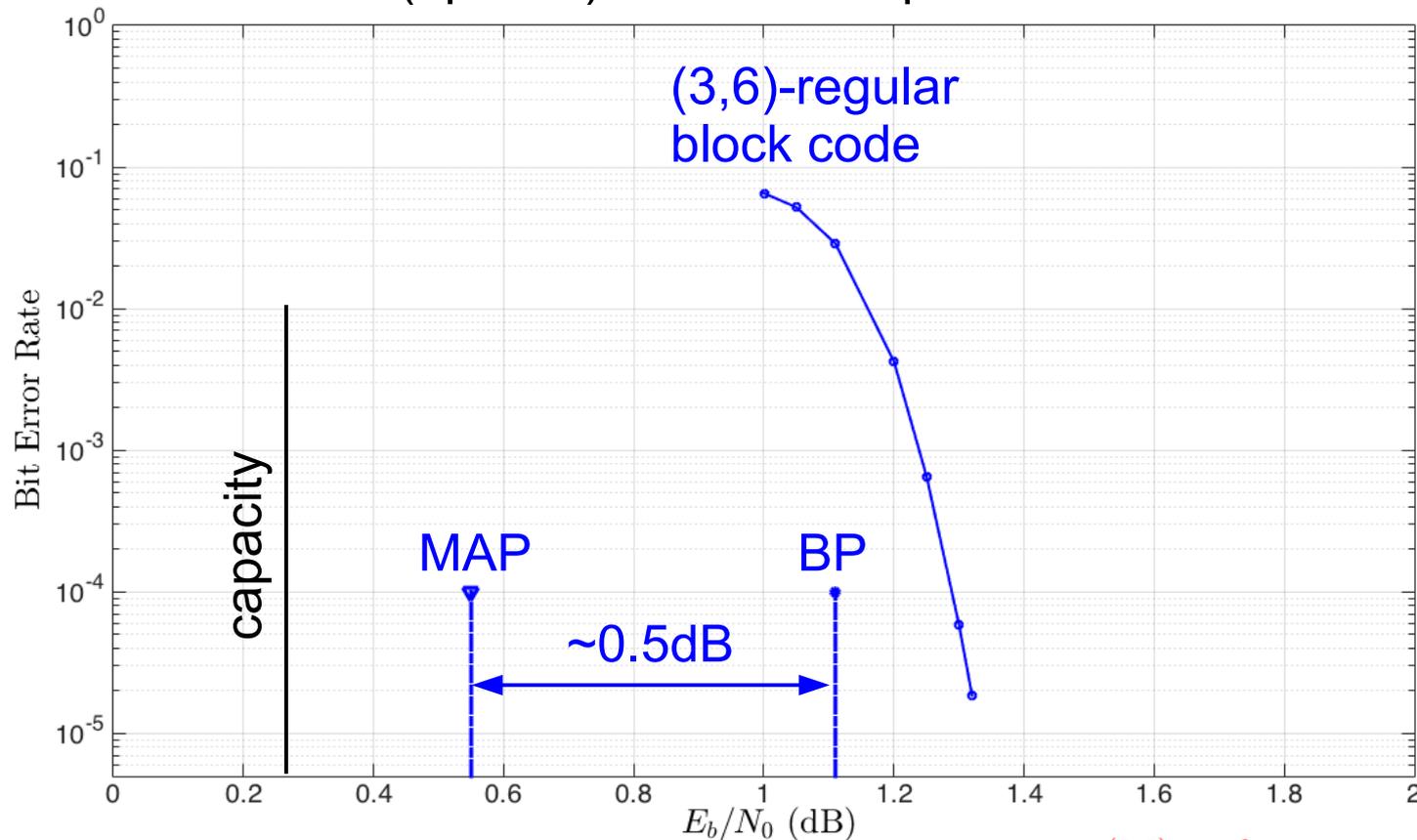
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➔ **optimal** decoding performance with a **suboptimal** iterative algorithm!

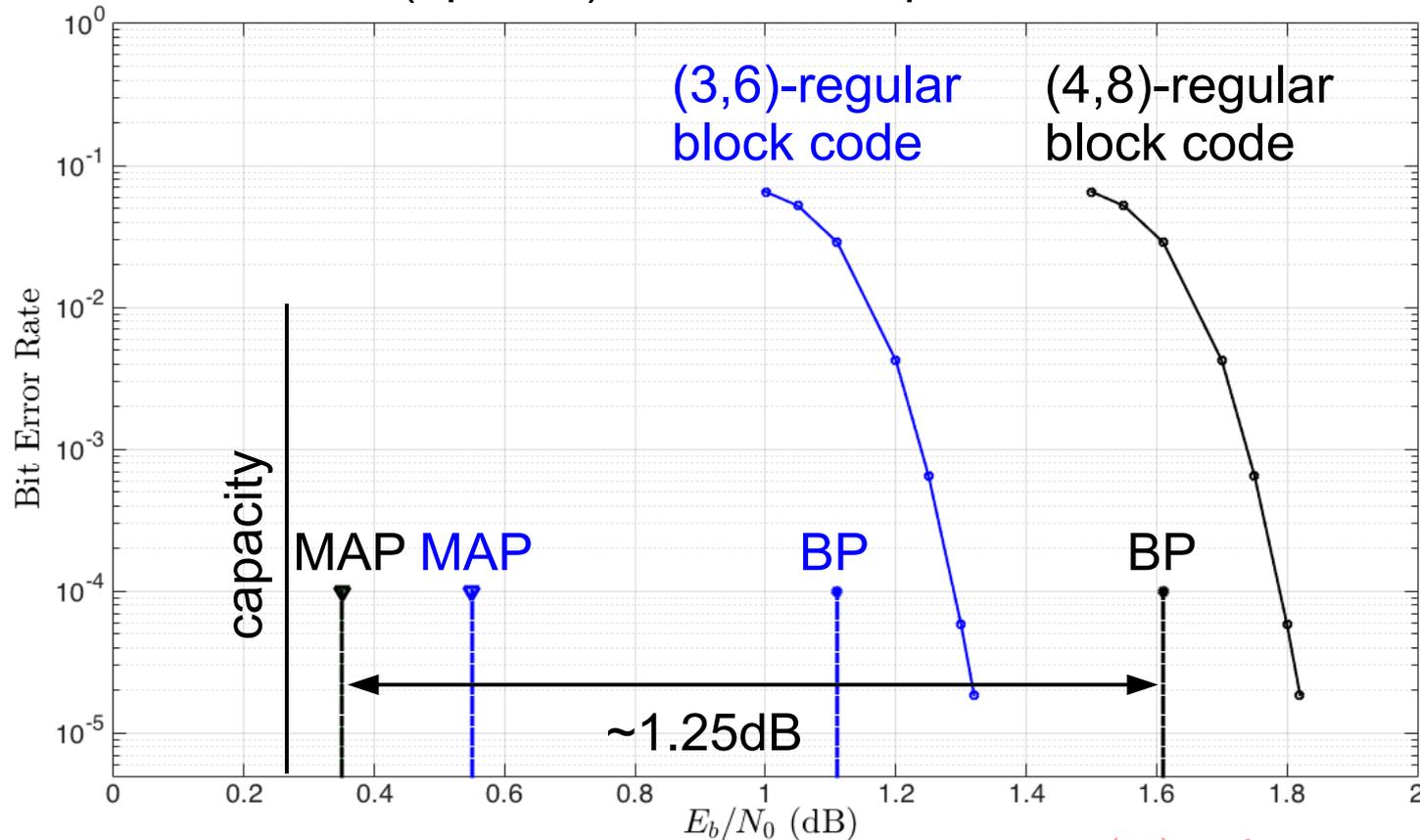
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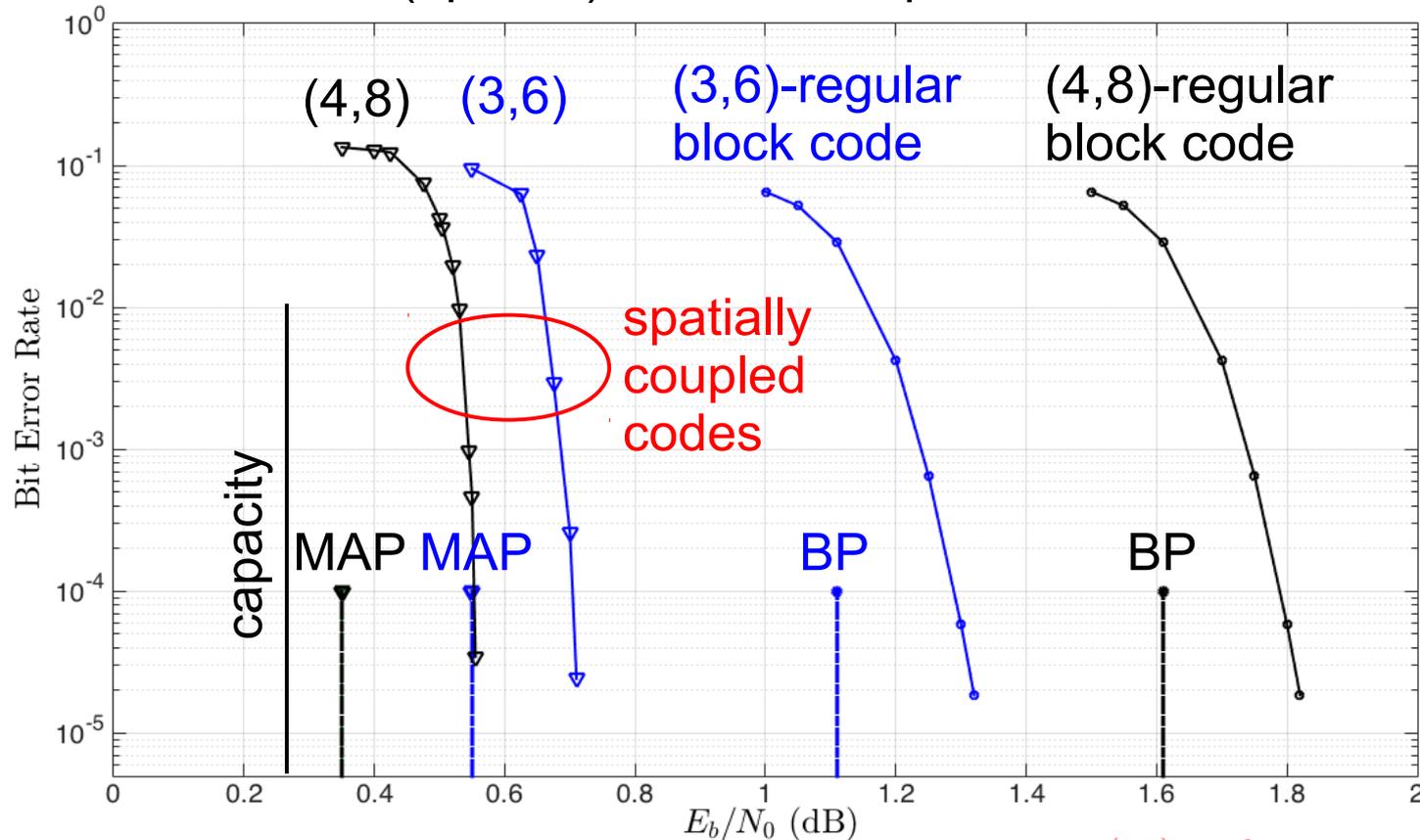
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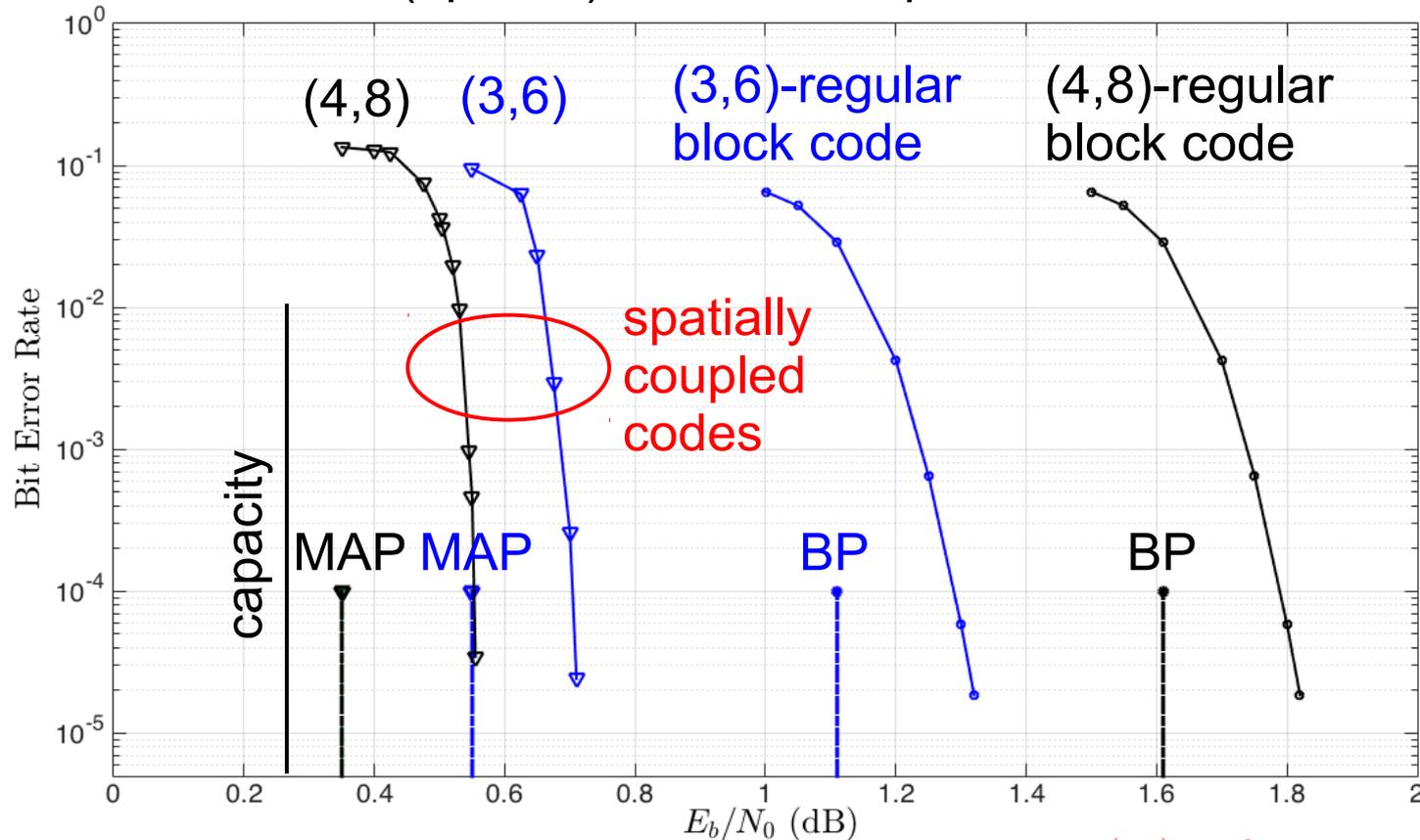
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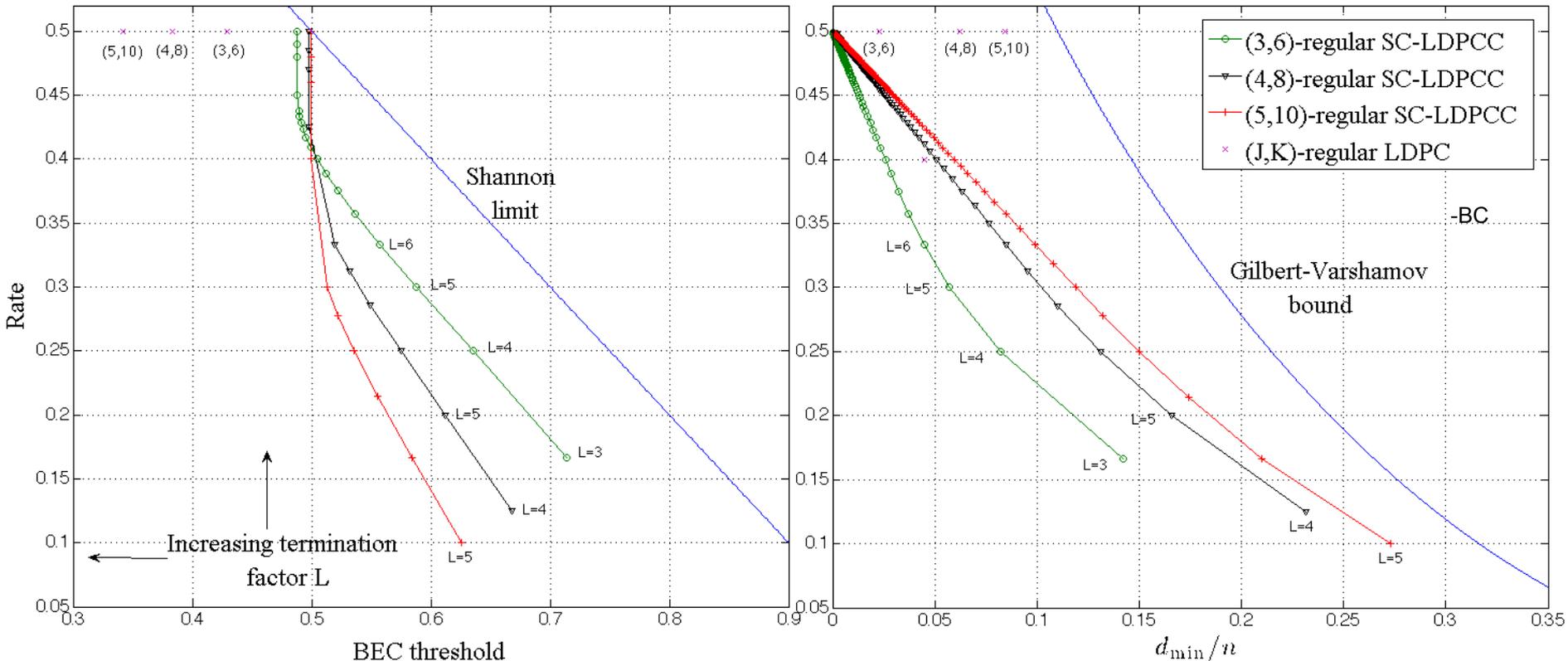
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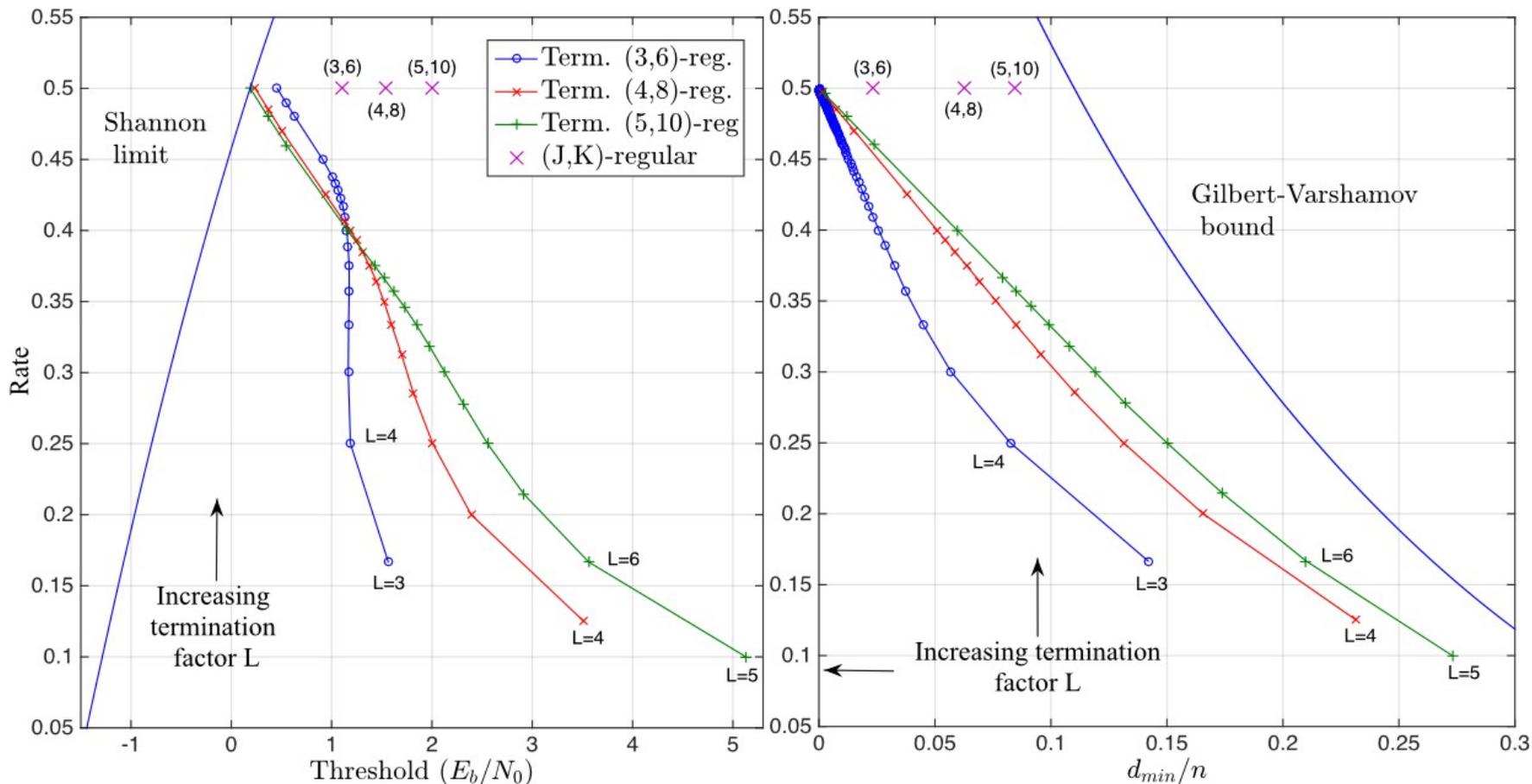
# BEC Thresholds vs Distance Growth

- By increasing  $J$  and  $K$ , we obtain **capacity achieving**  $(J,K)$ -regular SC-LDPC code ensembles with linear minimum distance growth.



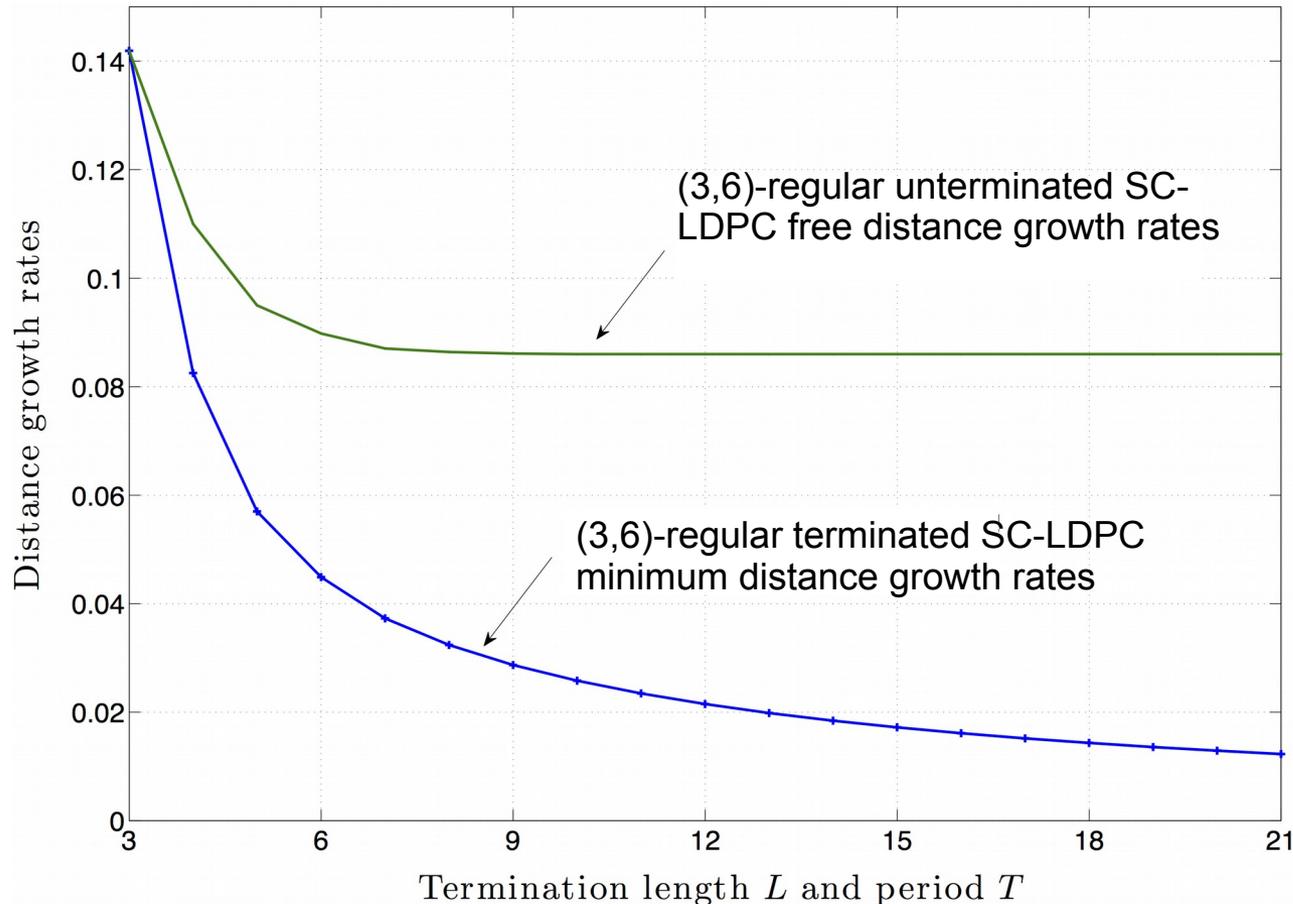
- $(J,K)$ -regular SC-LDPC codes combine the best features of irregular and regular LDPC-BCs, i.e., capacity approaching thresholds and linear distance growth.

■ Similar results are obtained for the AWGNC

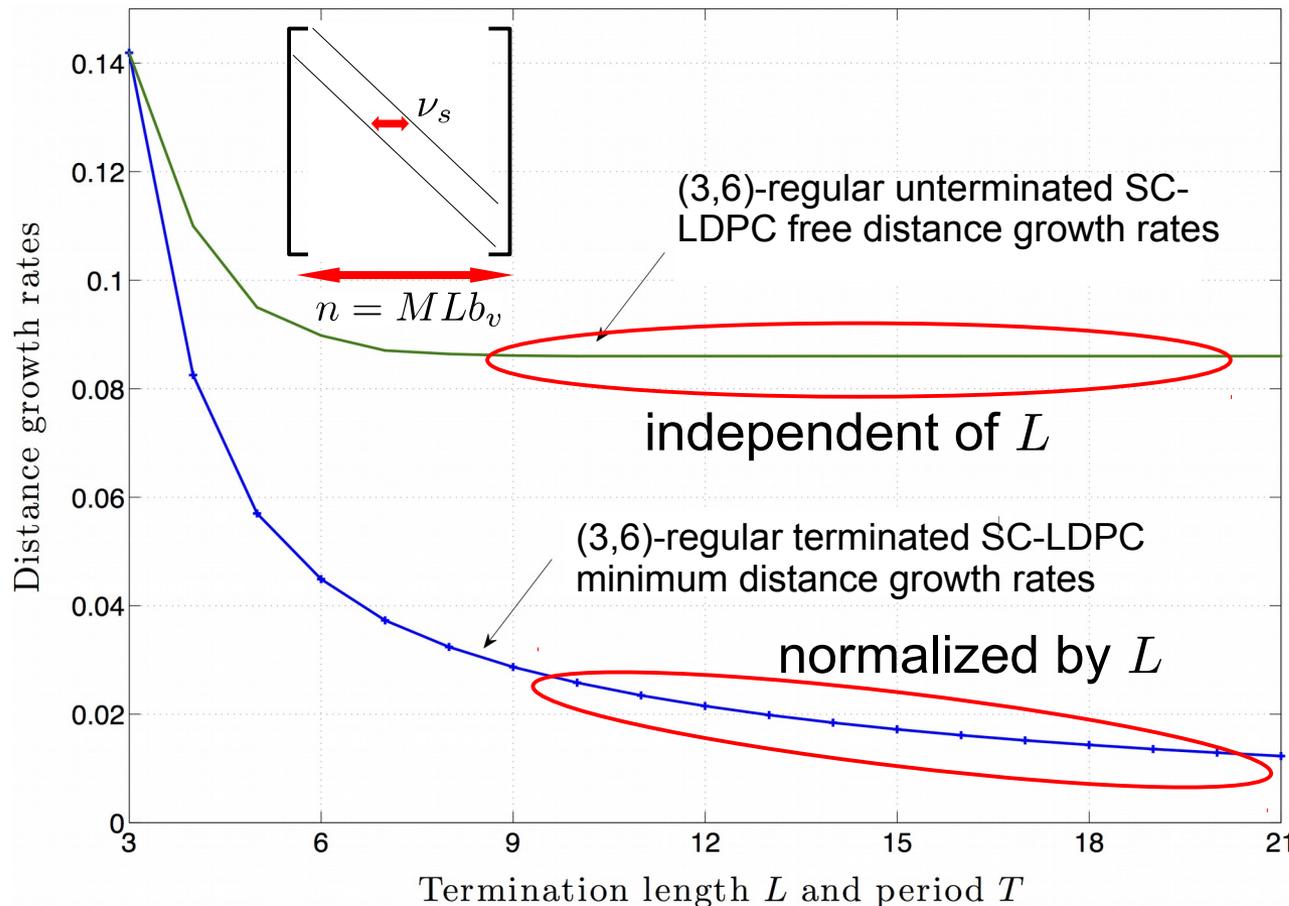


[MLC10] D. G. M. Mitchell, M. Lentmaier and D. J. Costello, Jr., "AWGN Channel Analysis of Terminated LDPC Convolutional Codes", *Proc. Information Theory and Applications Workshop*, San Diego, Feb. 2011.

- As  $L \rightarrow \infty$  the minimum distance growth rates of **terminated** SC-LDPC code ensembles tend to zero. However, the free distance growth rates of the **unterminated** ensembles remain constant.

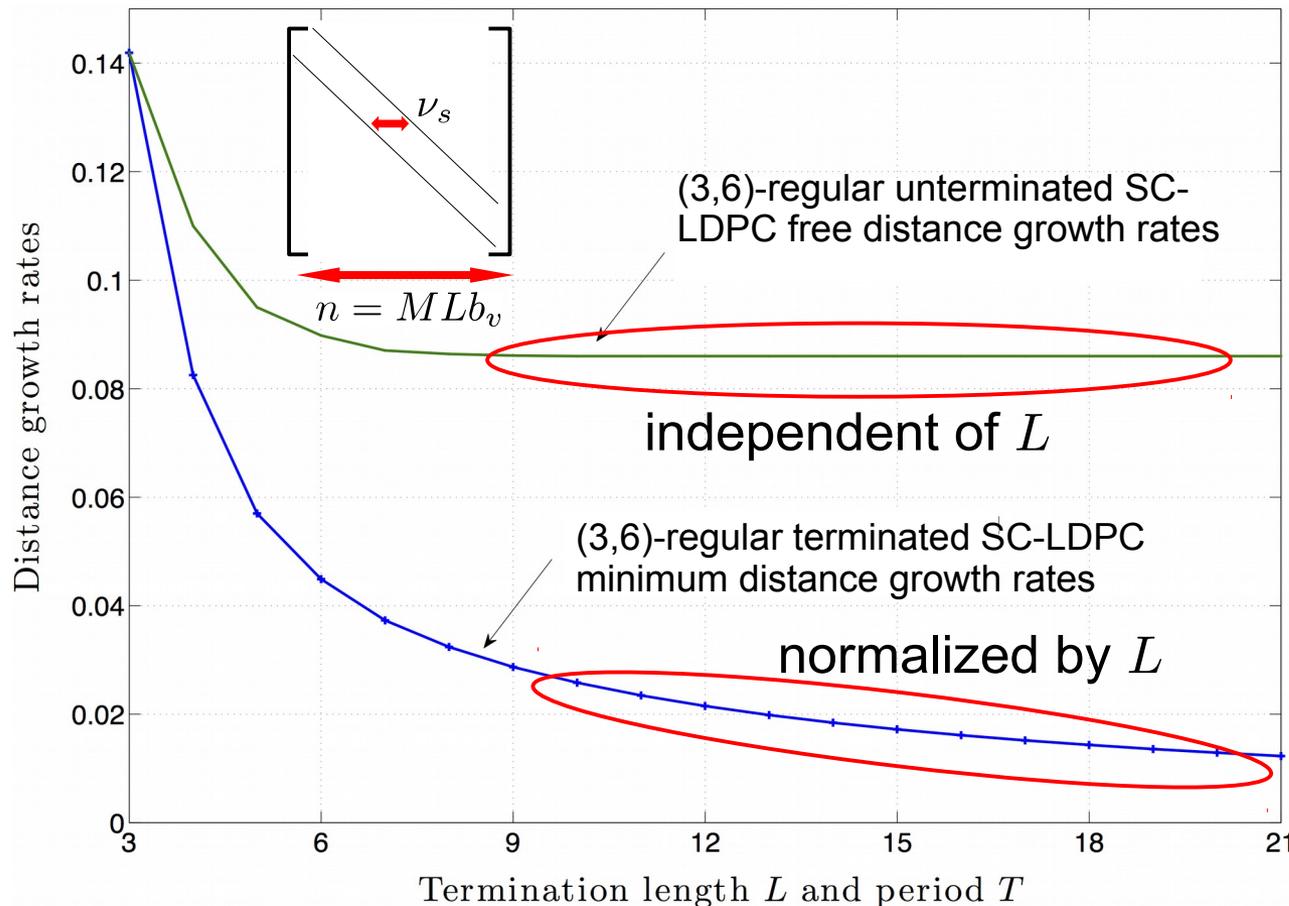


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- An appropriate distance measure for 'convolutional-like' terminated ensembles should be independent of  $L$ .

## ■ LDPC Block Codes

- ➔ Parity-check matrix and Tanner graph representations, minimum distance bounds, iterative decoding thresholds, protograph-based constructions

## ■ Spatially Coupled LDPC Codes

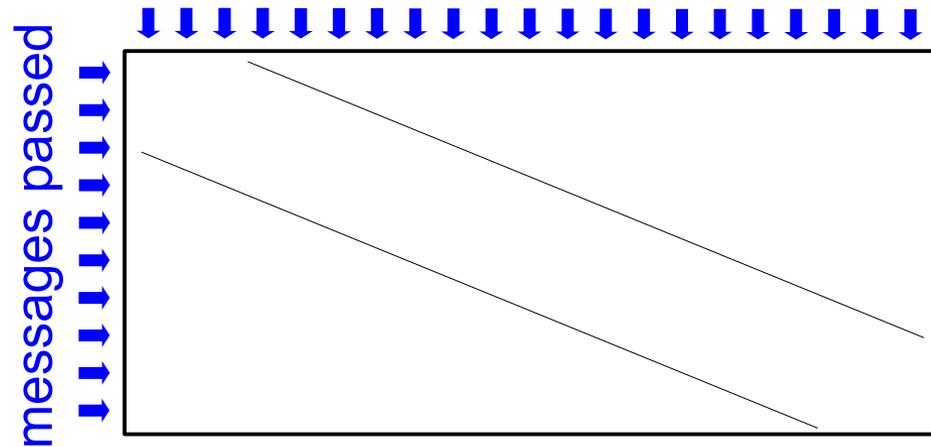
- ➔ Protograph representation, edge-spreading construction, termination
- ➔ Iterative decoding thresholds, threshold saturation, minimum distance

## ■ Practical Considerations

- ➔ Window decoding; performance, latency, and complexity comparisons to LDPC block codes; rate-compatibility; implementation aspects

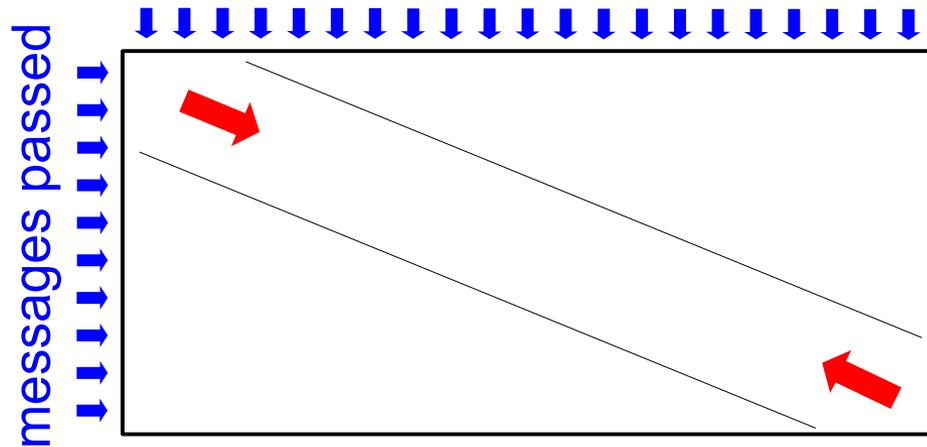
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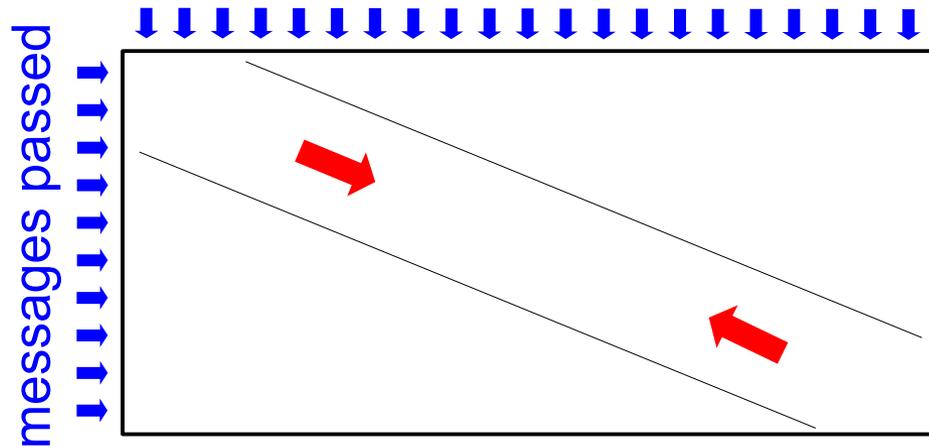
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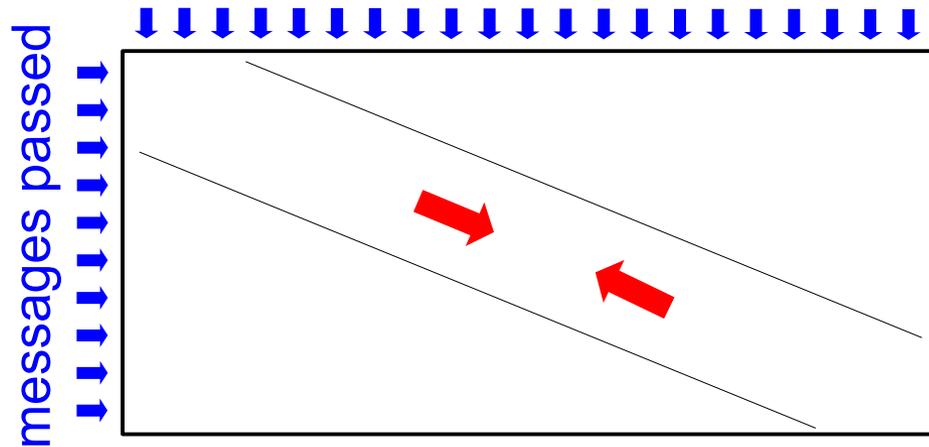
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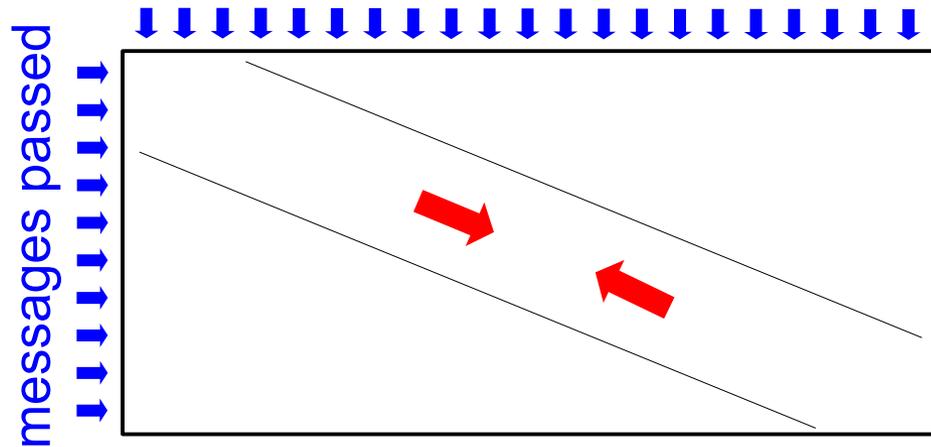
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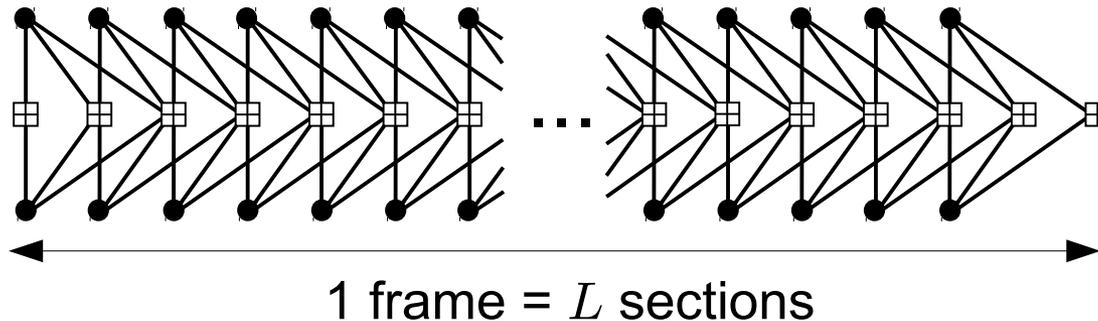
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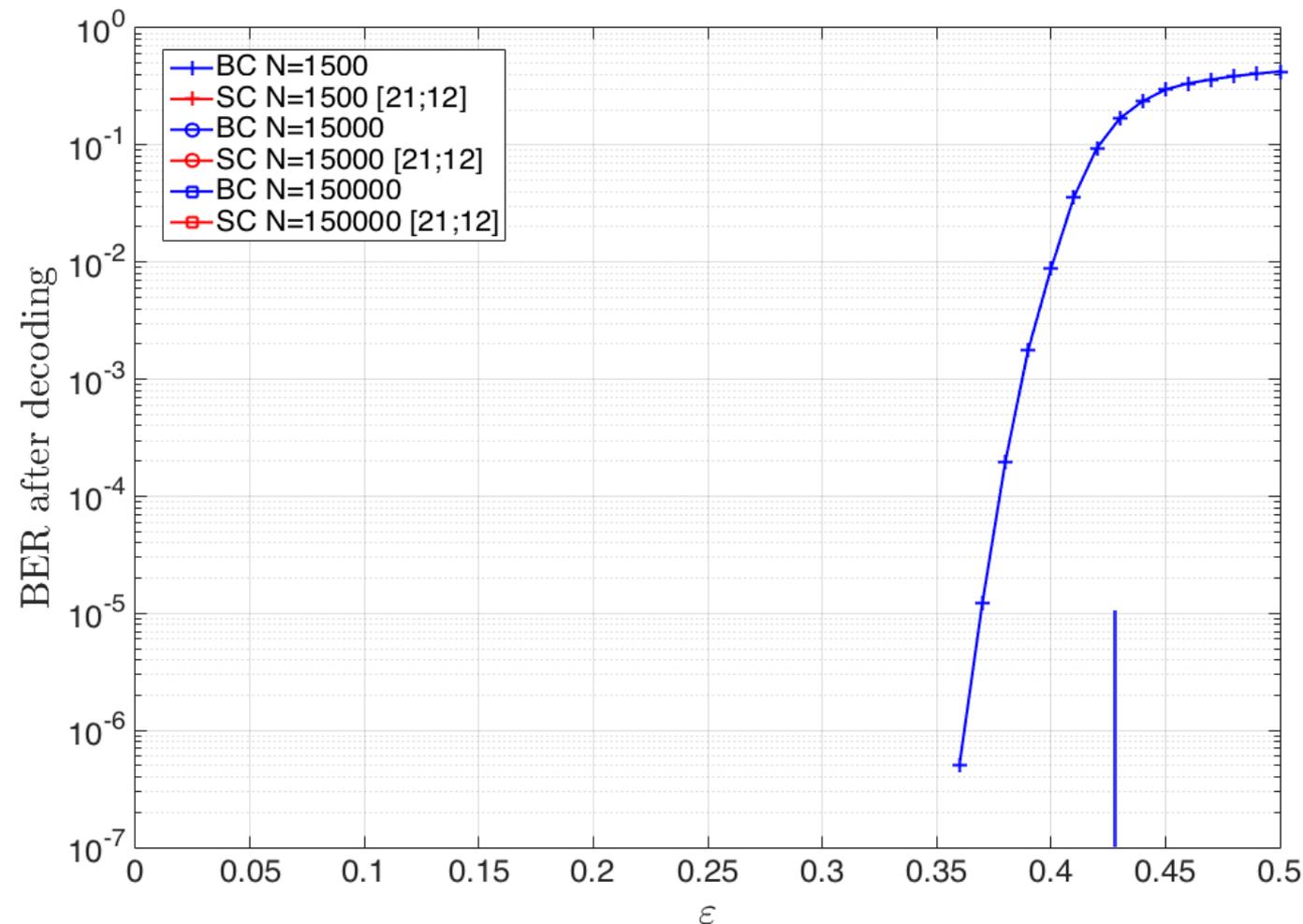
- The **frame error rate (FER)** of a terminated graph can be analyzed



→ The **FER depends on  $L$**  ( $\text{FER} \xrightarrow{L \rightarrow \infty} 1$ )

# Block Decoding Performance

- Consider LDPC-BCs and SC-LDPC codes with increasing frame length  $N$

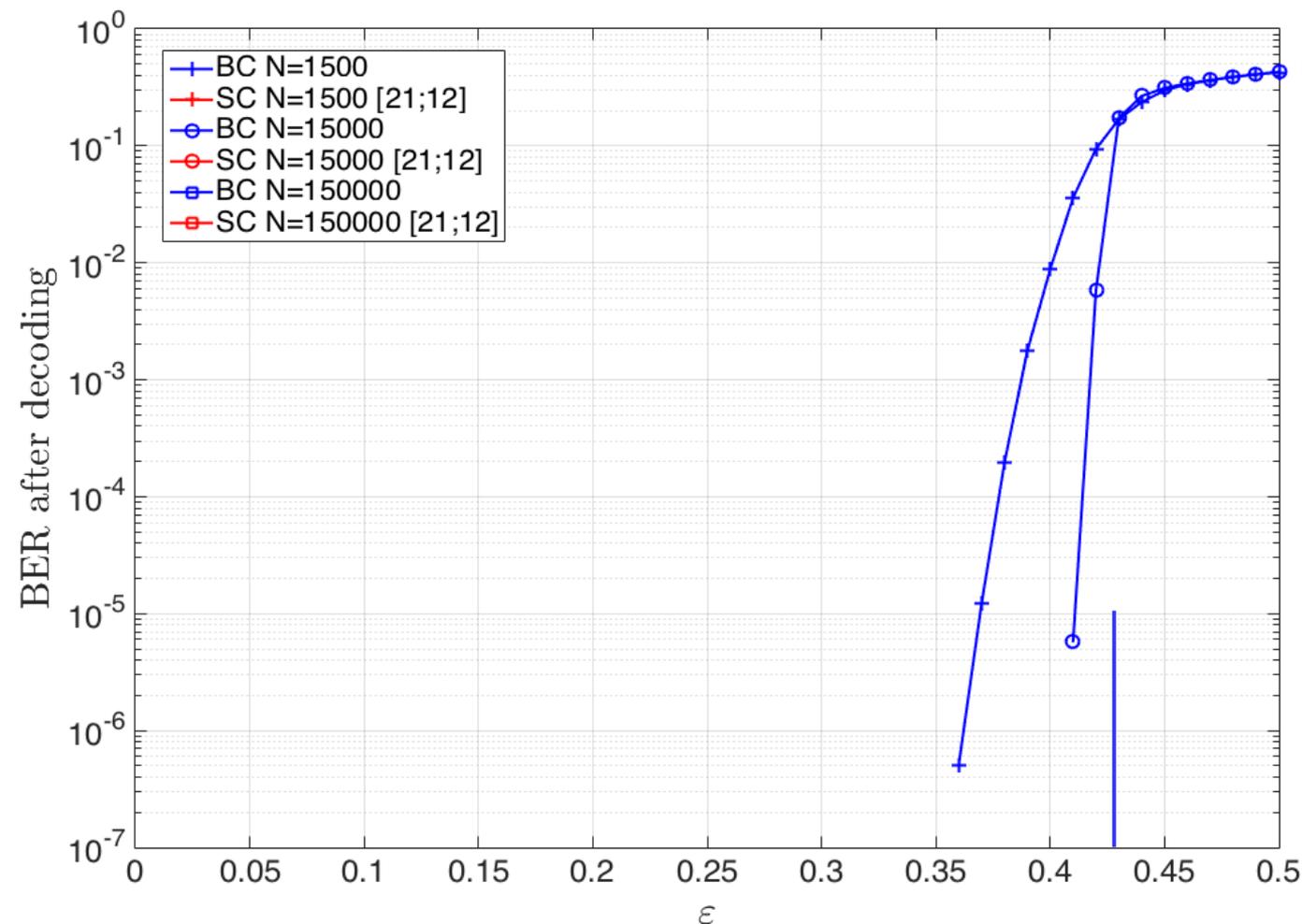


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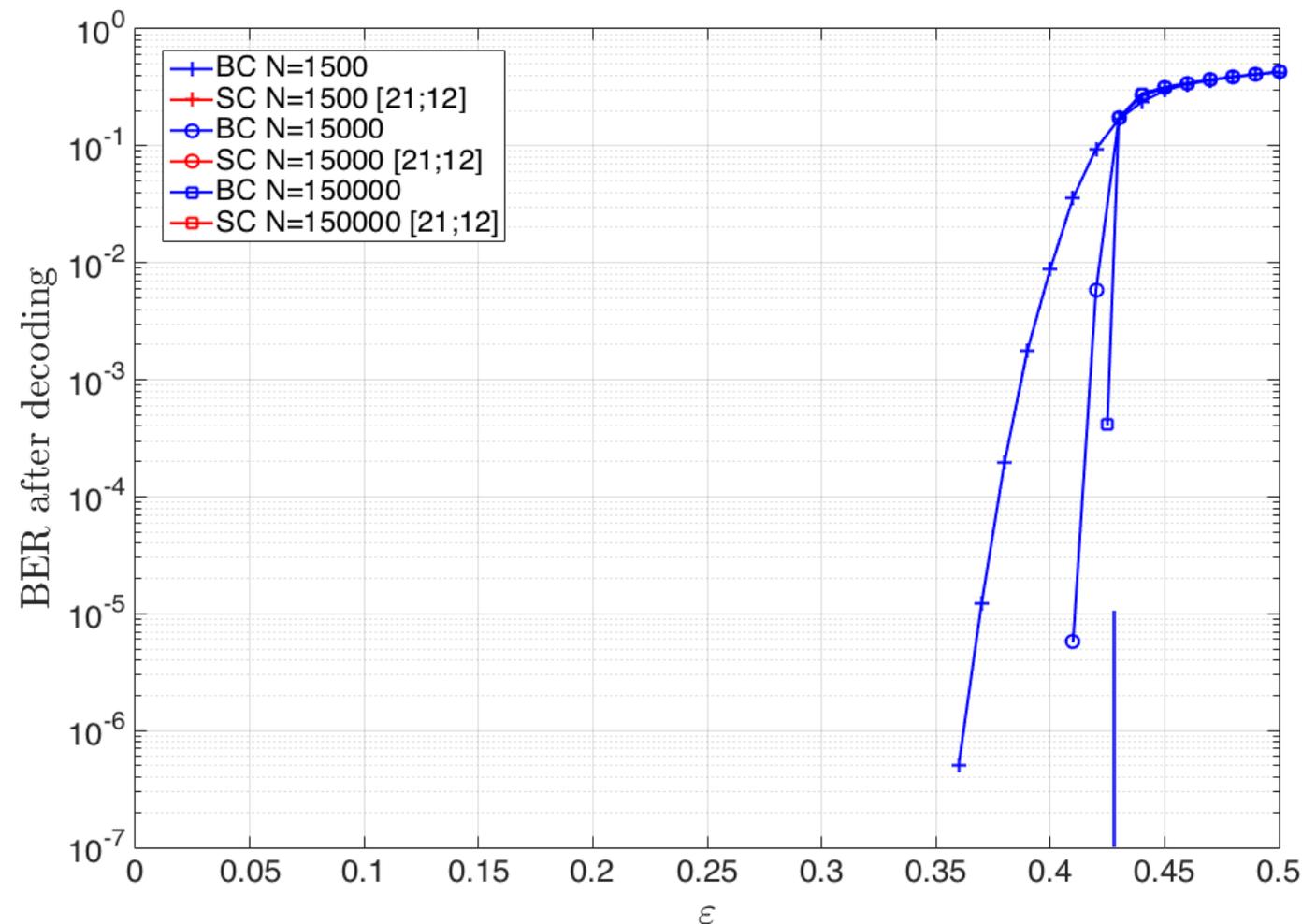


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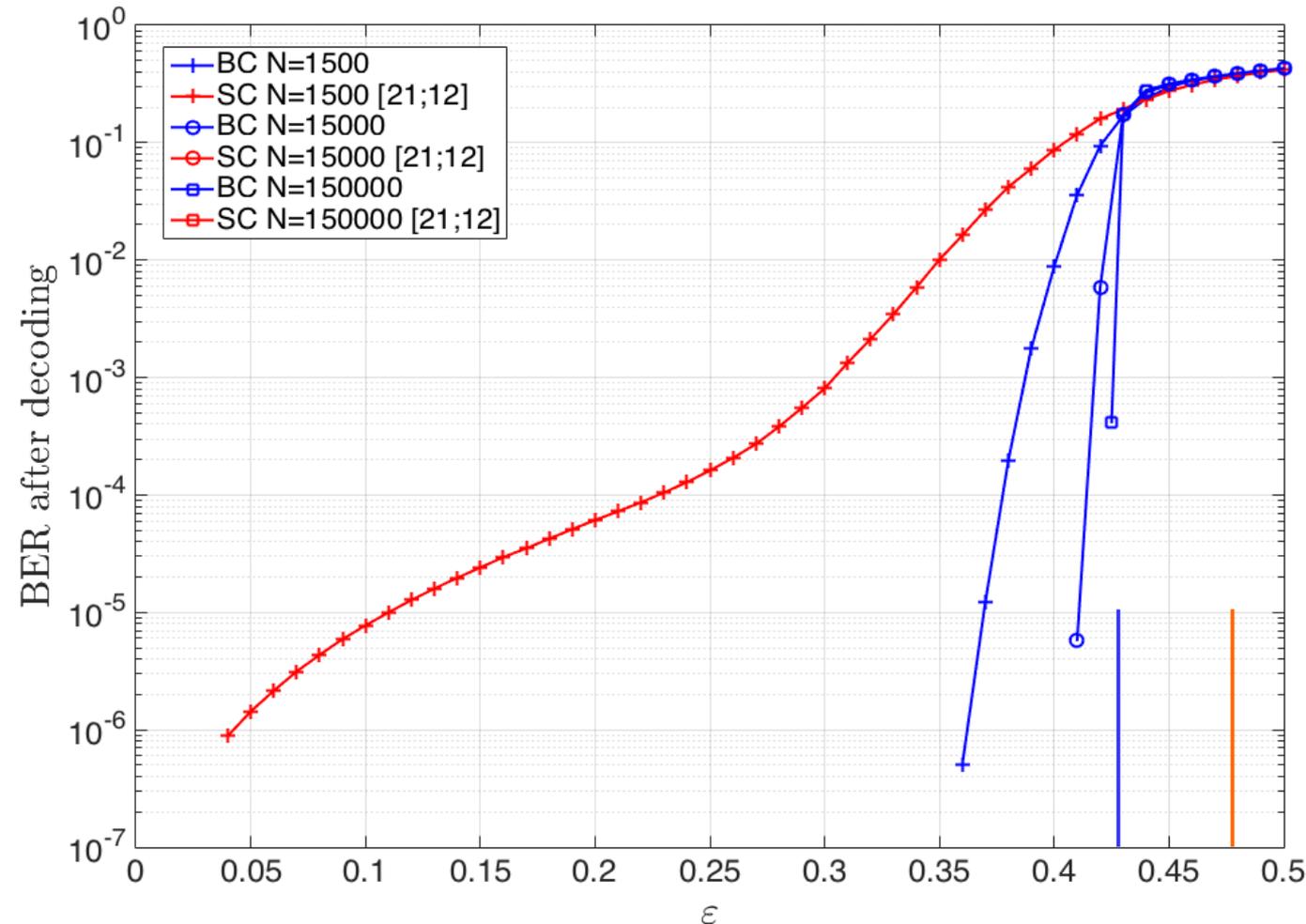


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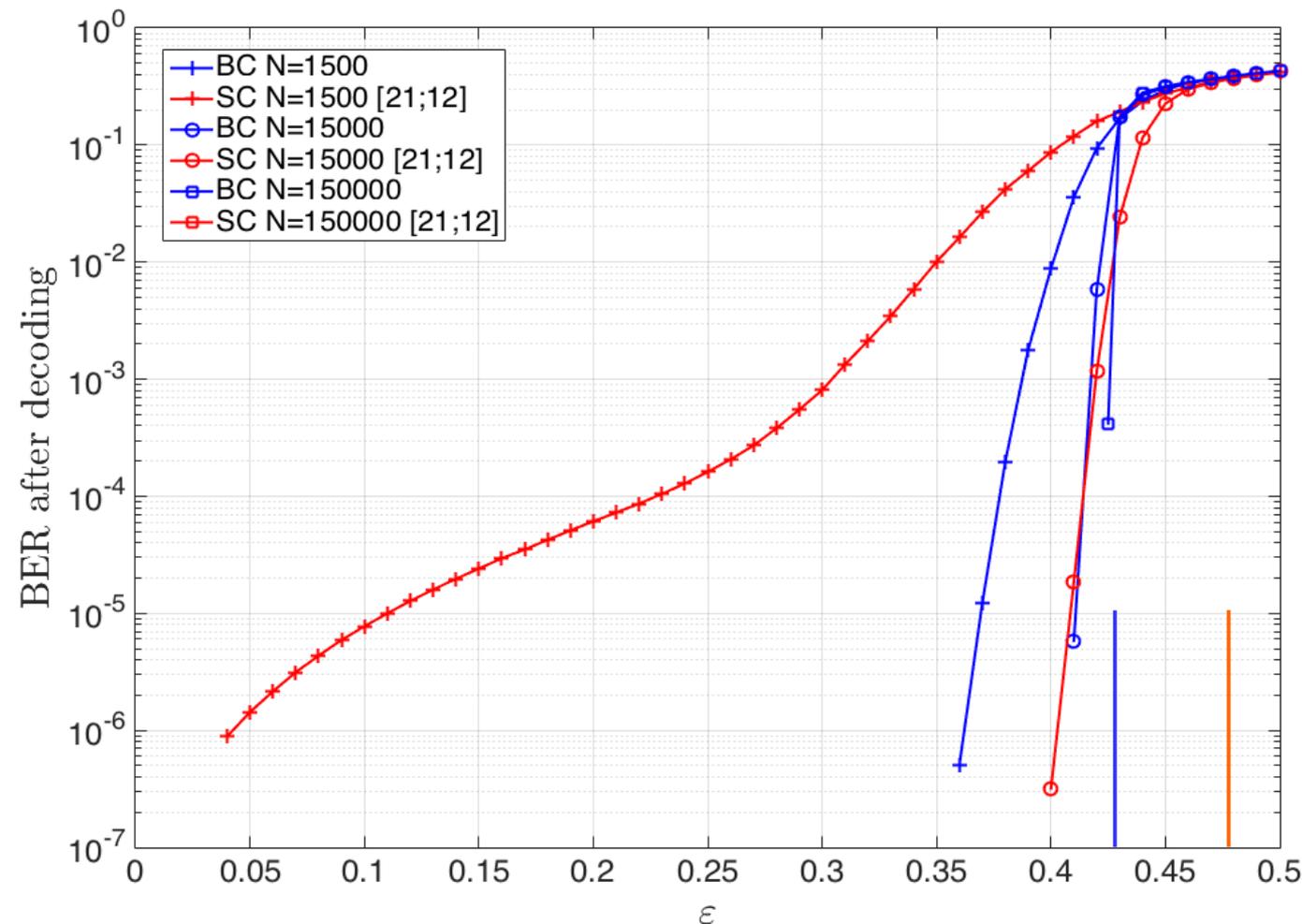
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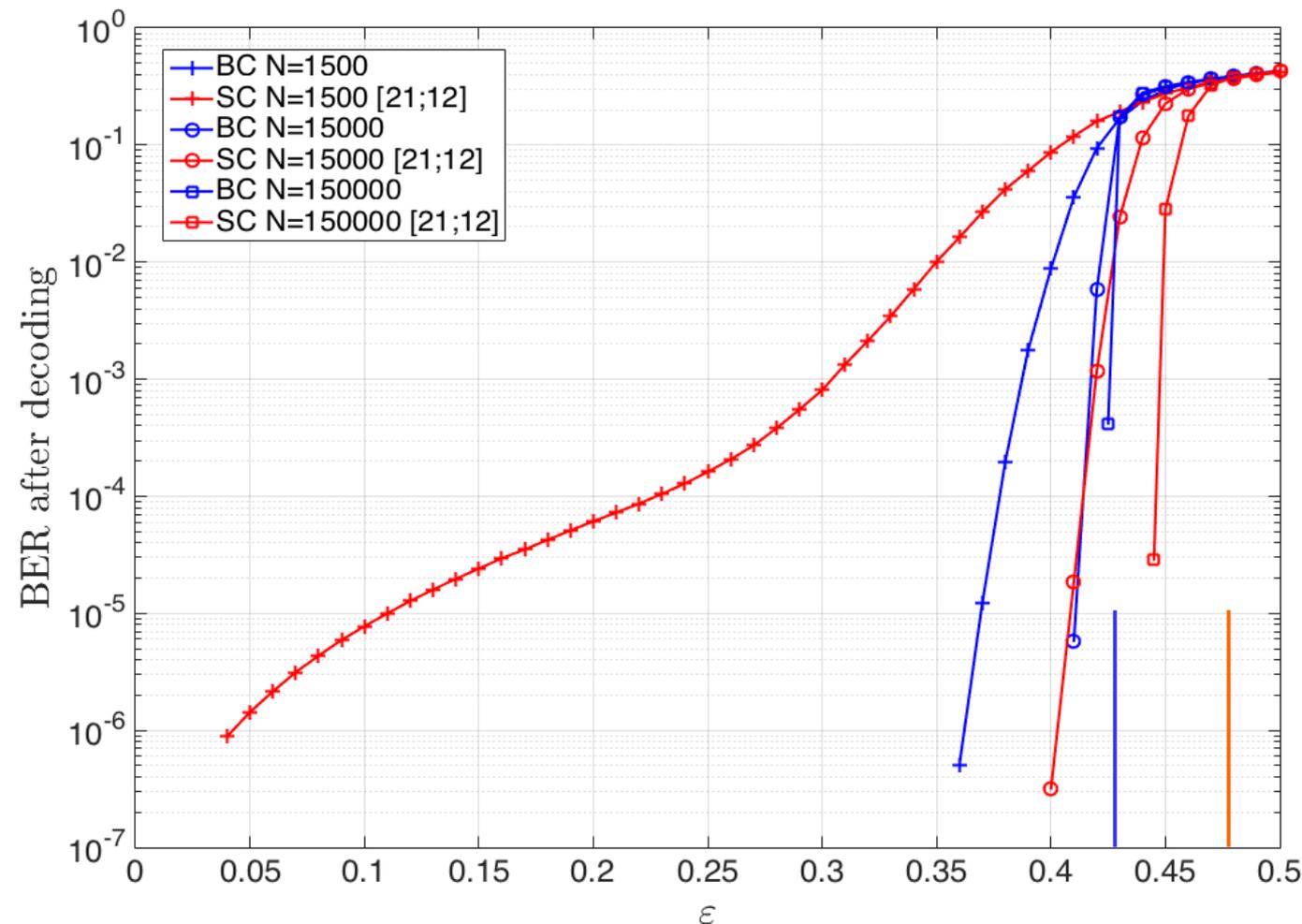
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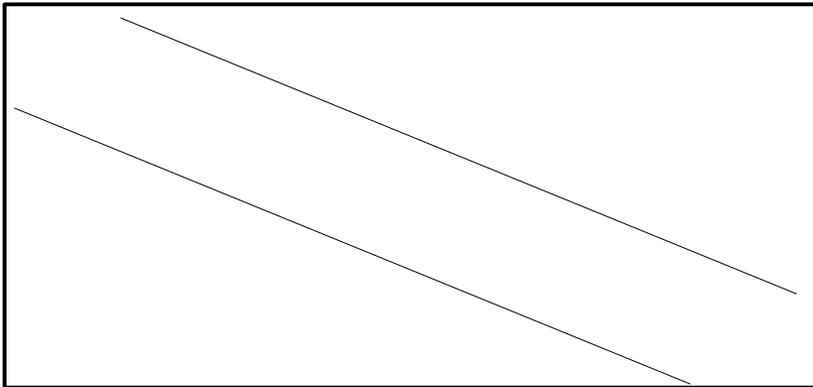
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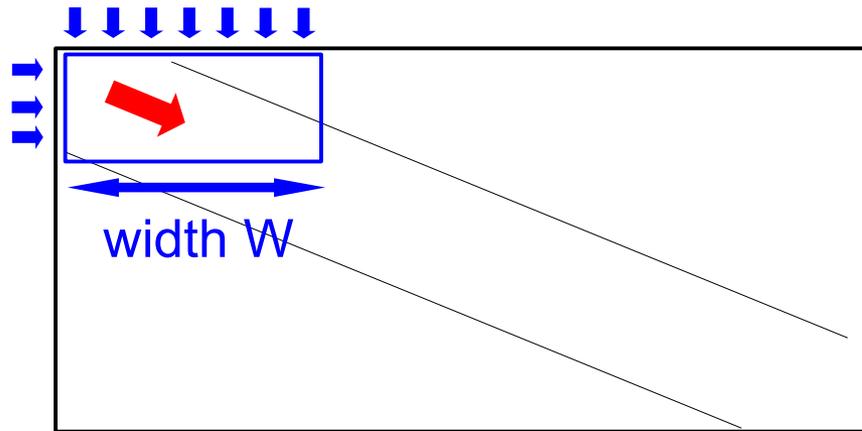
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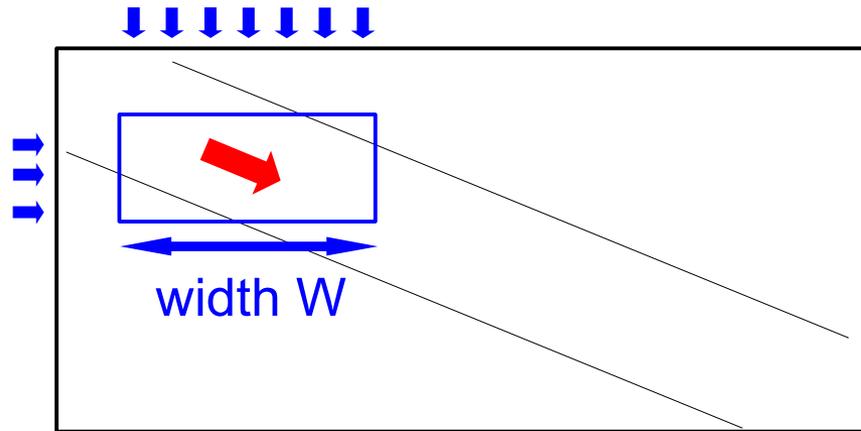


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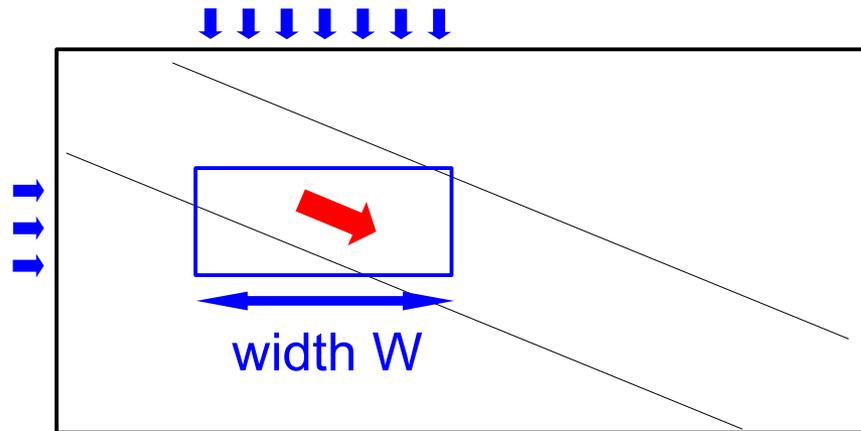
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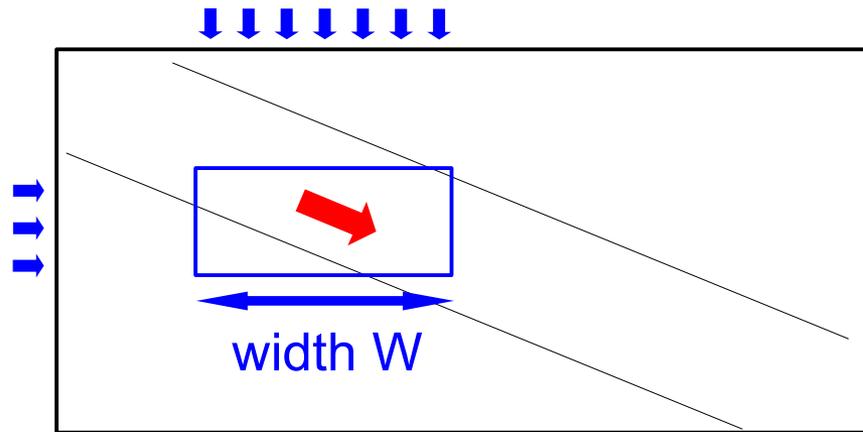
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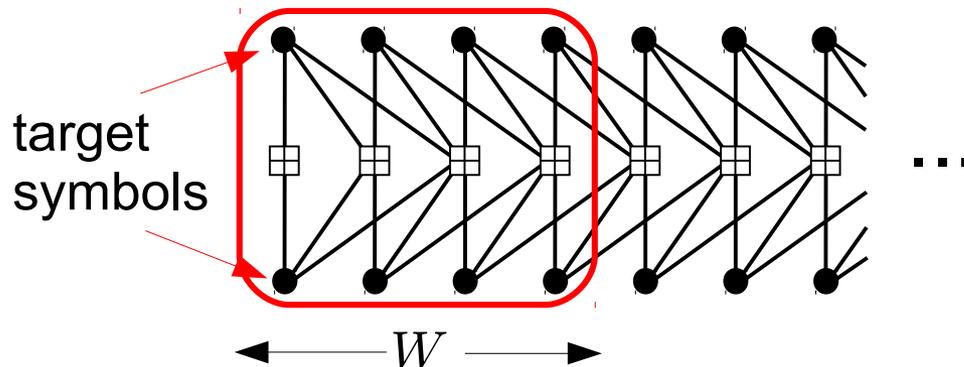


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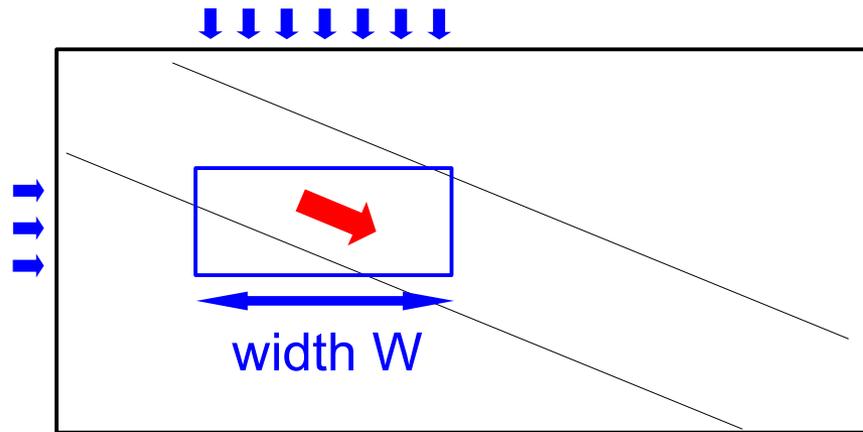


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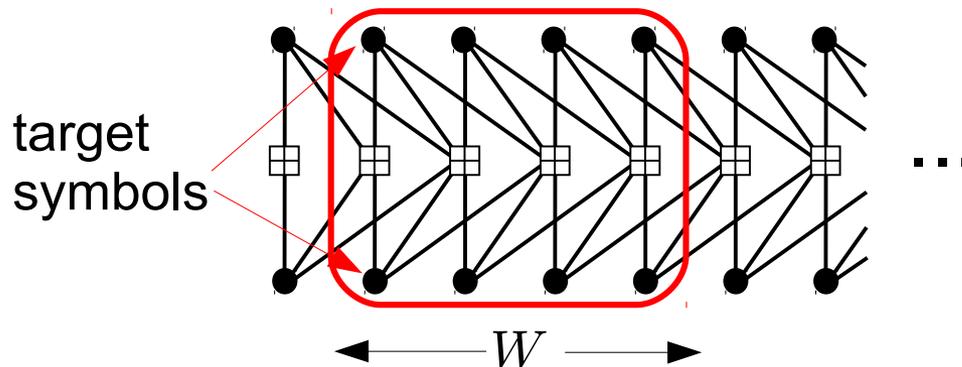


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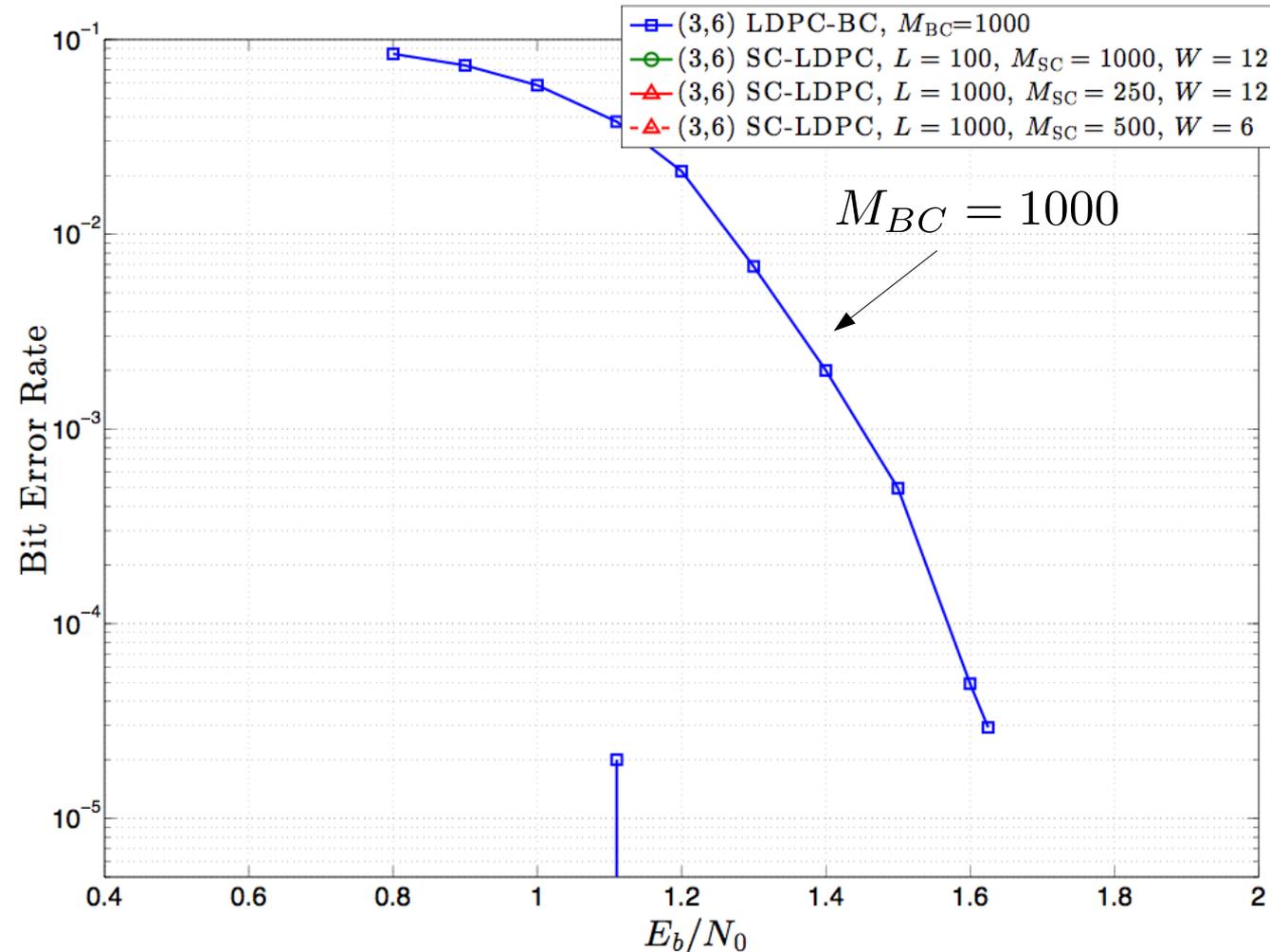
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# Window Decoding Performance



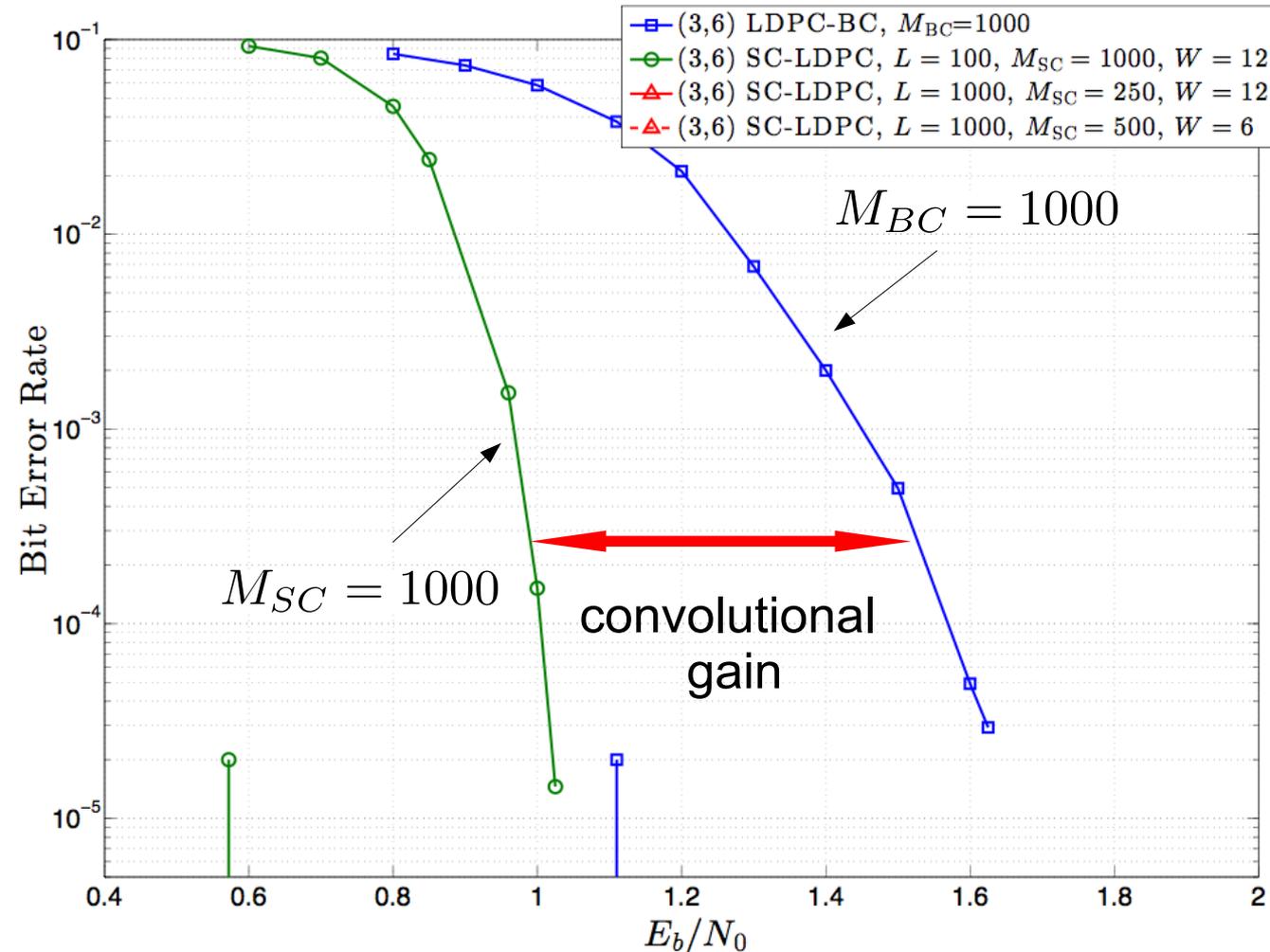
## Latencies:

LDPC:  $6M_{BC}$

SC-LDPC:  $2M_{SC}W$

[LPF11] M. Lentmaier, M. M. Prenda, and G. Fettweis, "Efficient Message Passing Scheduling for Terminated LDPC Convolutional Codes", *Proc. IEEE ISIT*, St. Petersburg, Russia, July 2011.

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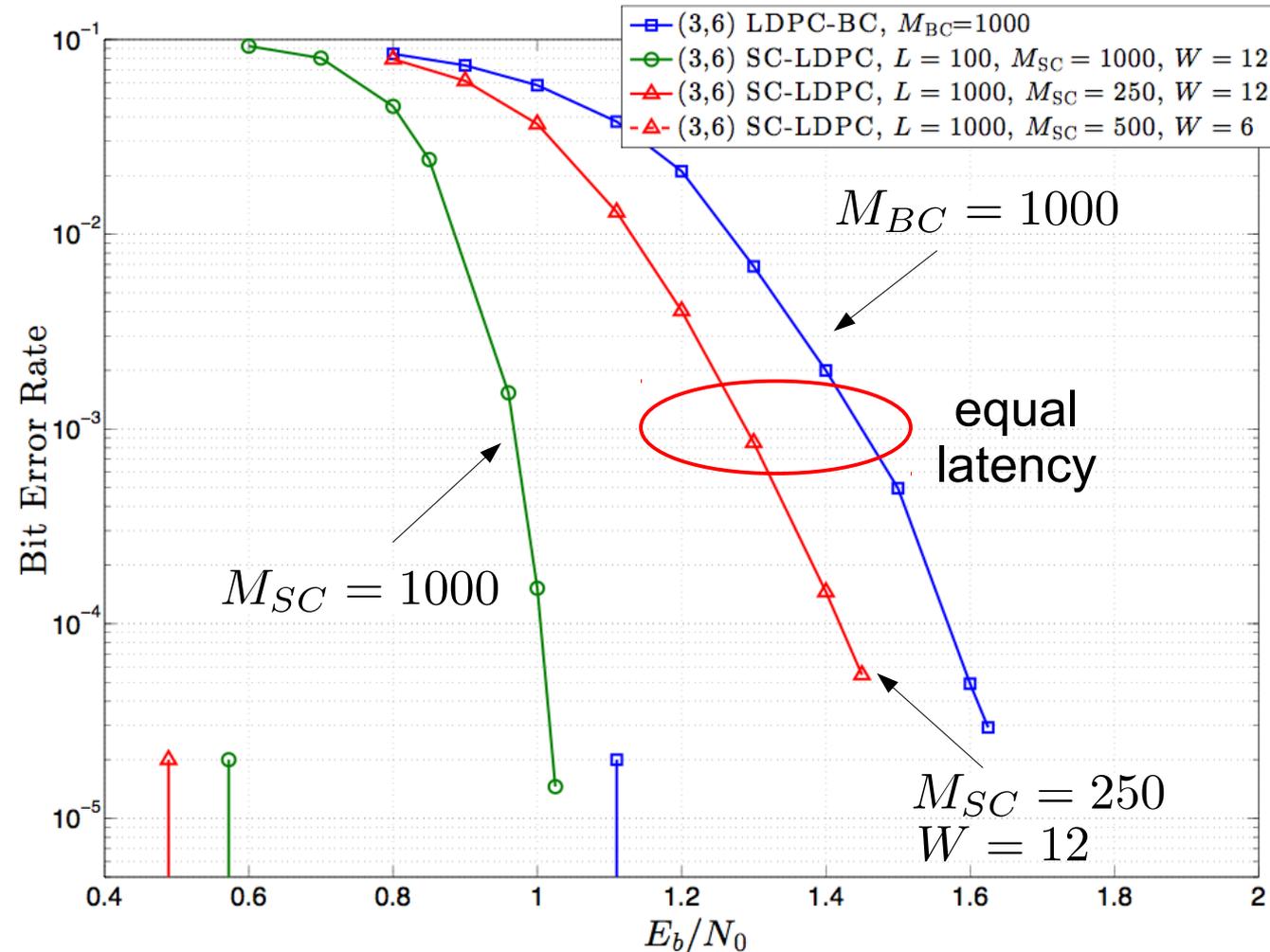
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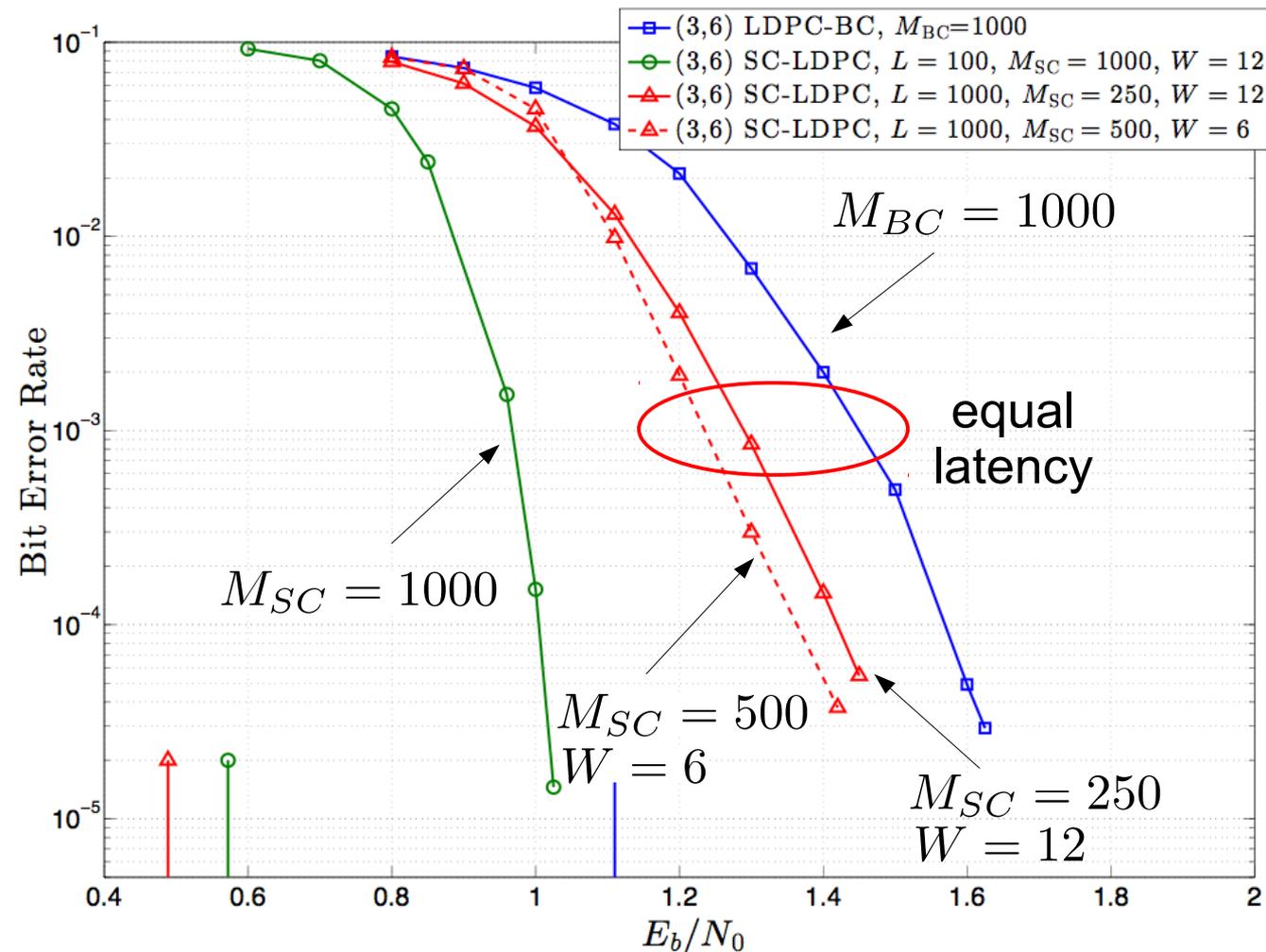
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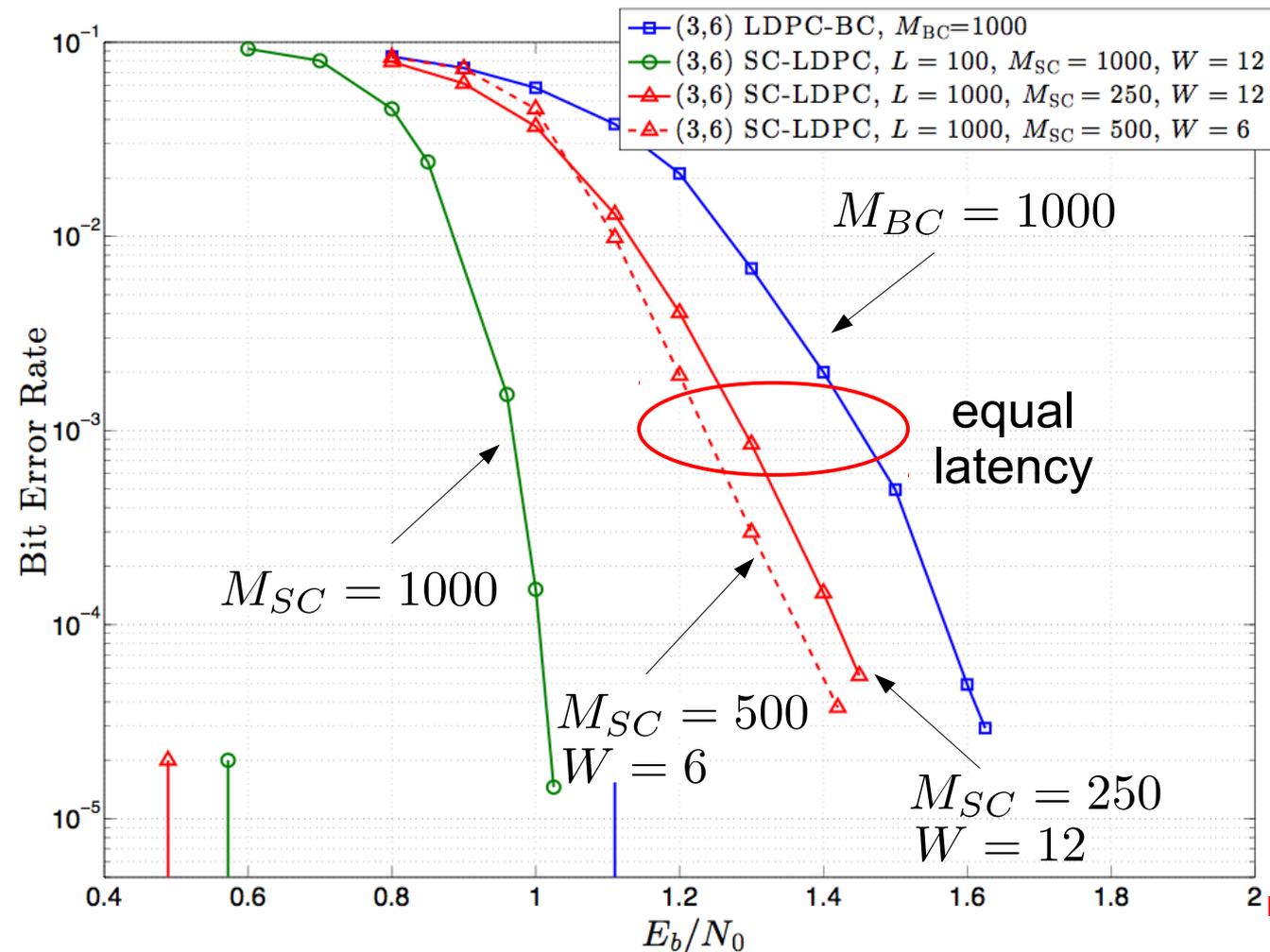
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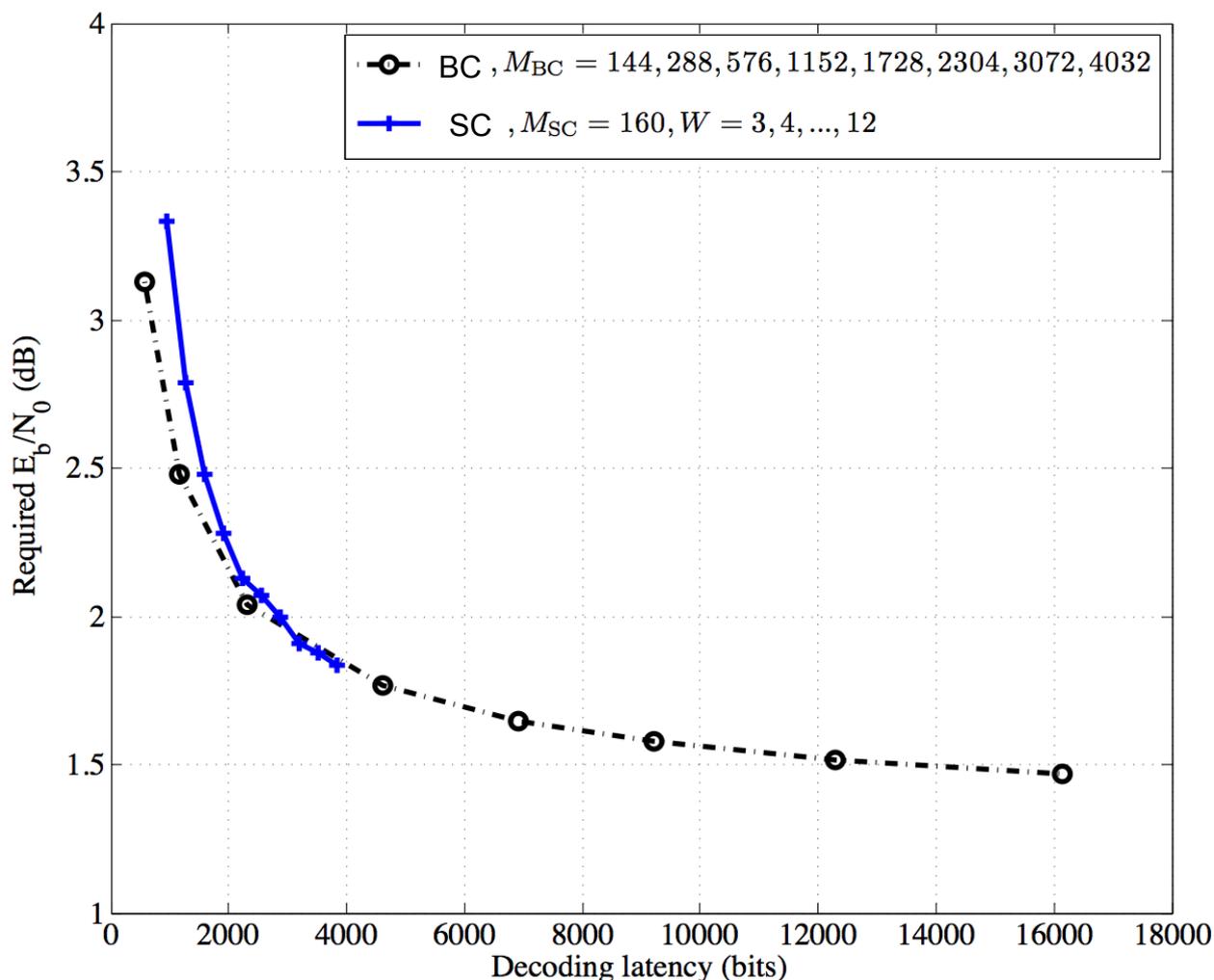
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- ➔ Trade-off in  $M$  vs  $W$

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# Equal Latency Comparison for (3,6)-Regular LDPC Codes

- Required  $E_b/N_0$  to achieve a BER of  $10^{-5}$  as a function of latency:



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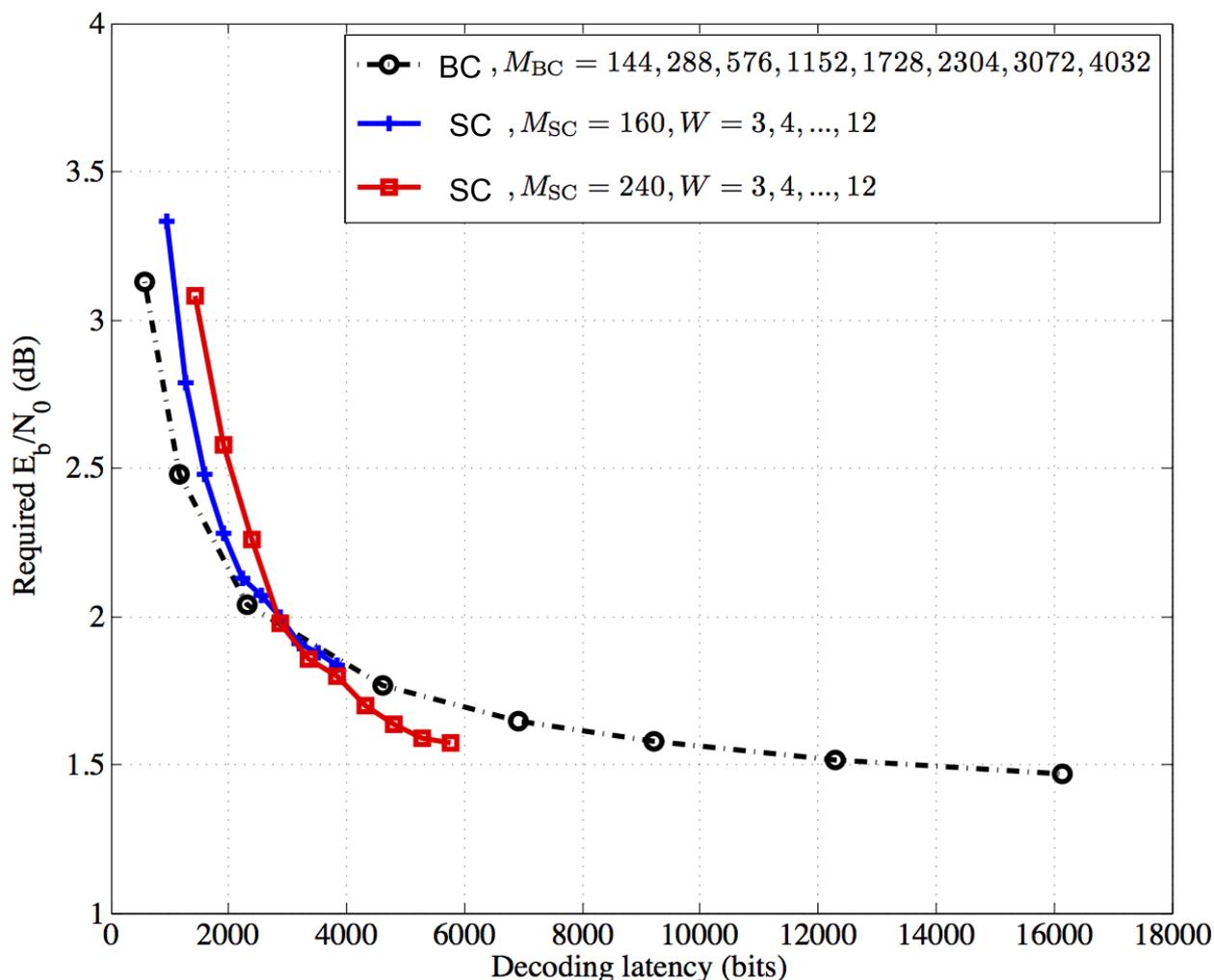
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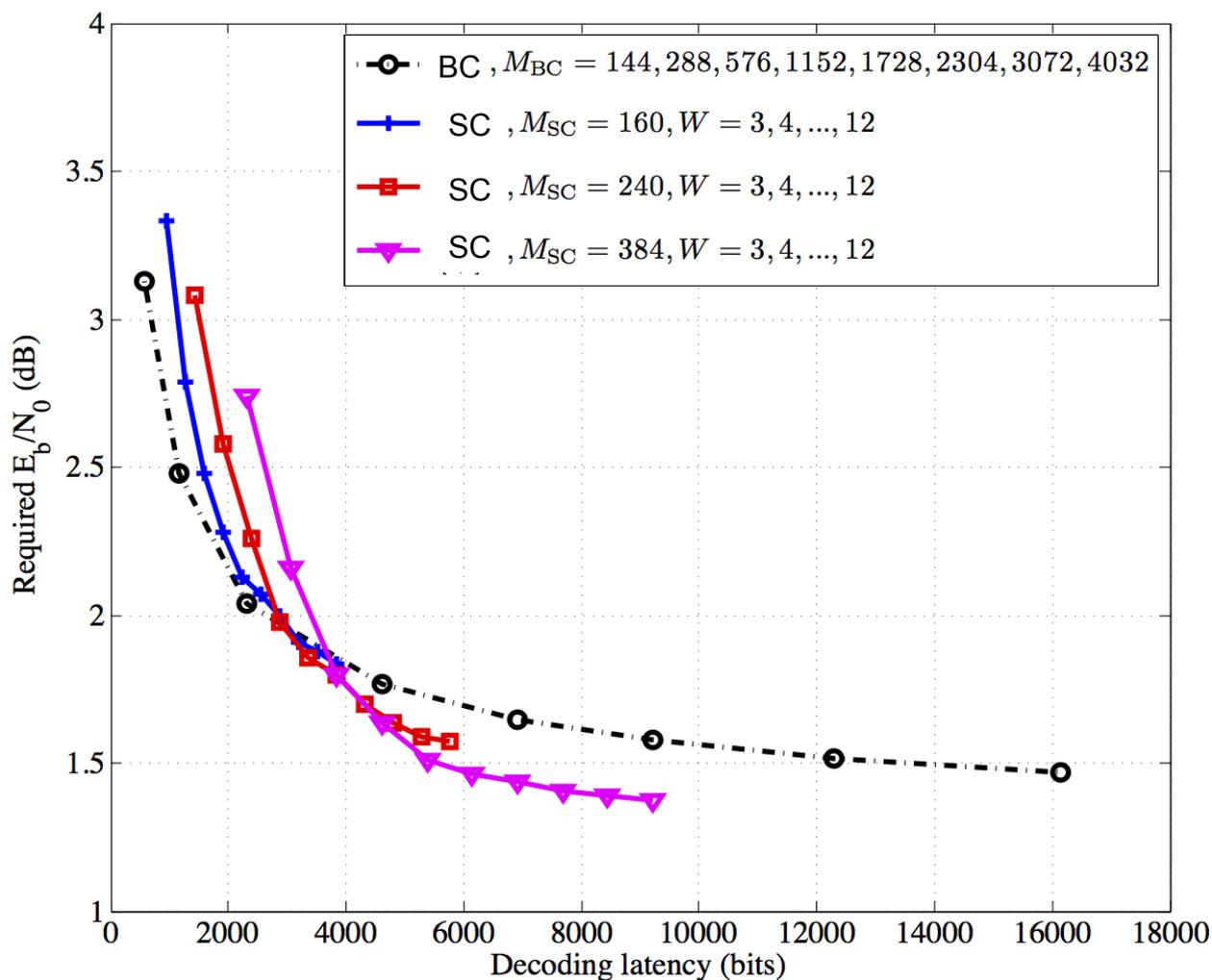
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## Latencies:

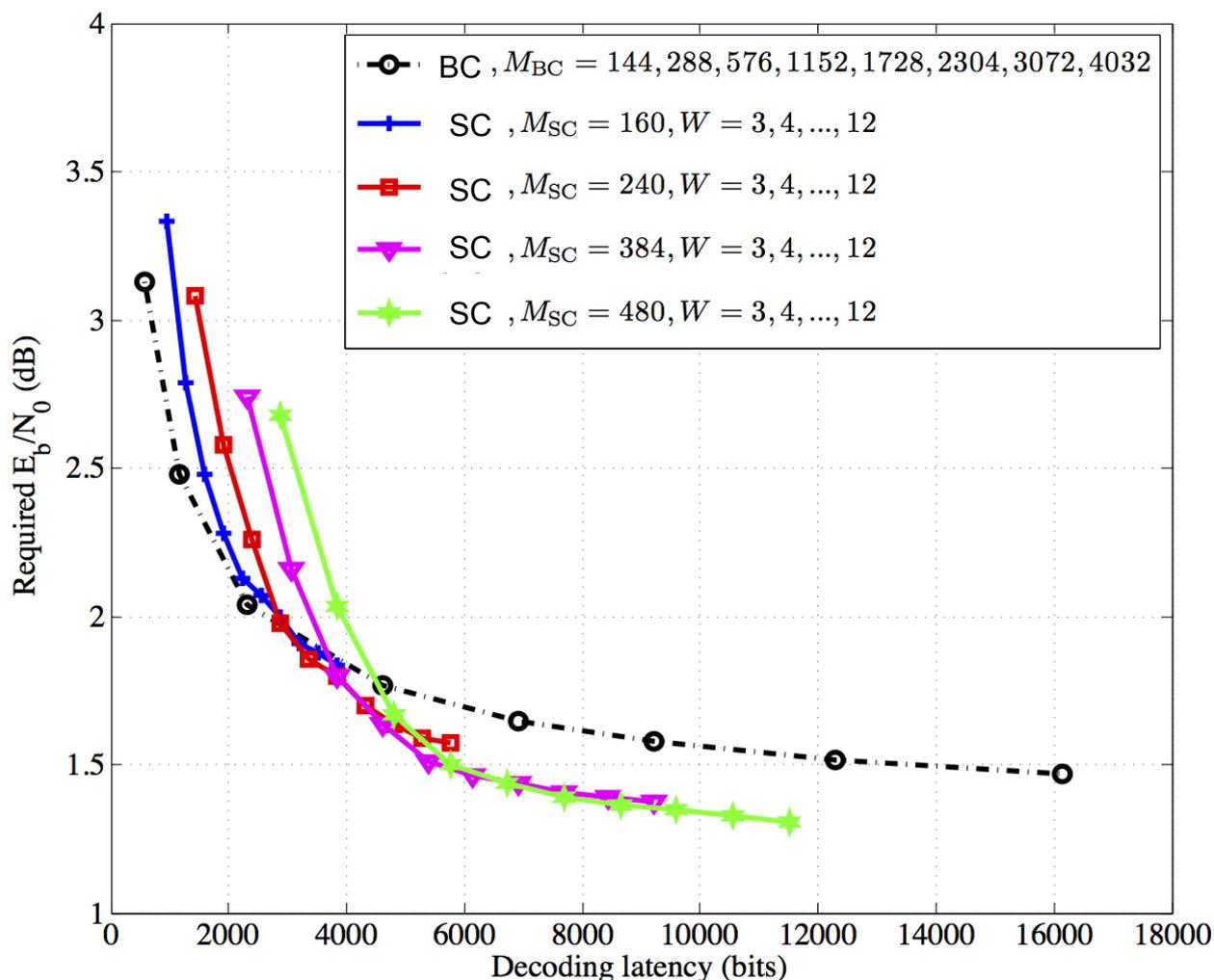
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SC-LDPC:  $2M_{SC}W$

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- does not decrease significantly beyond a certain  $W$  ( $W \approx 10$ ).

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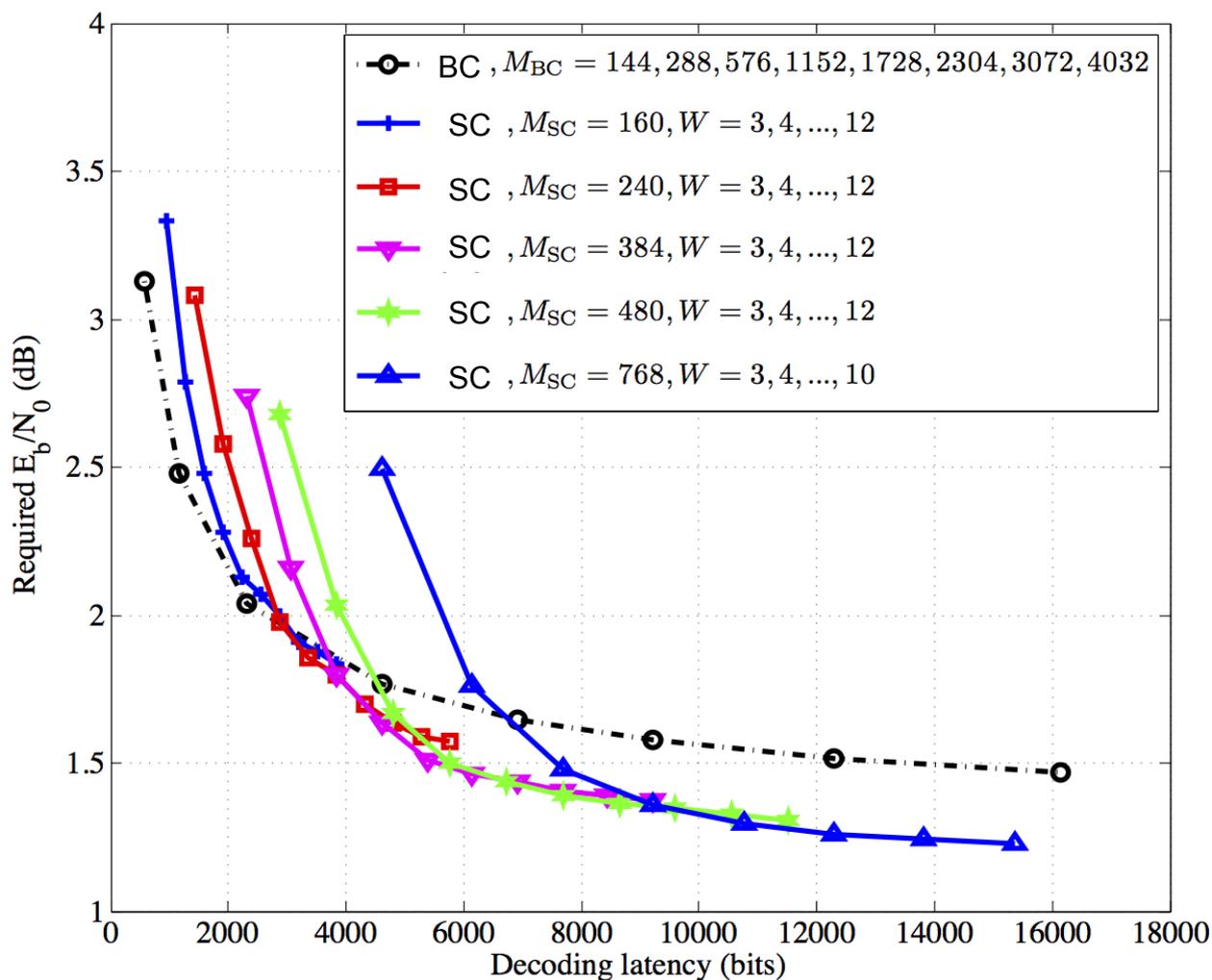
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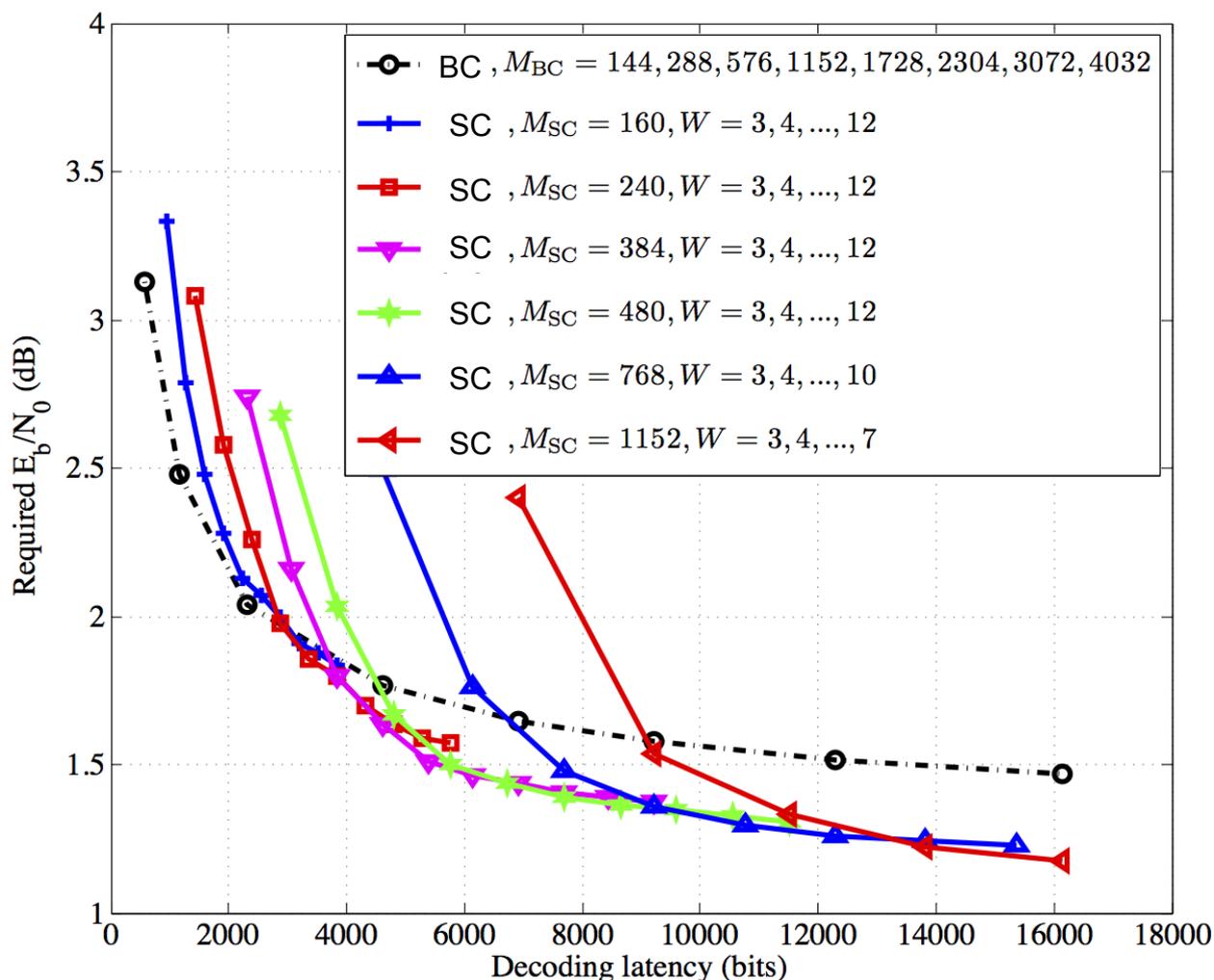


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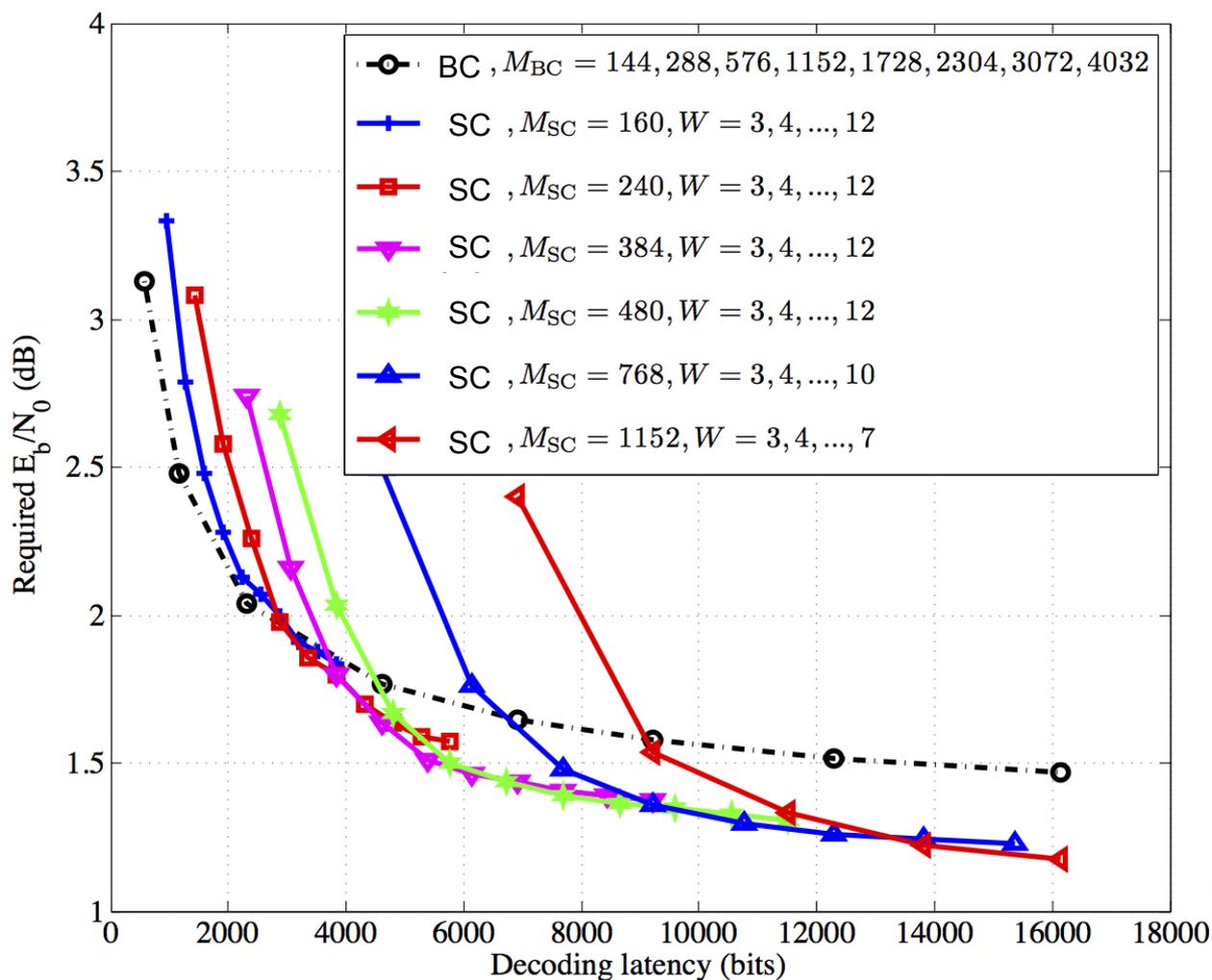


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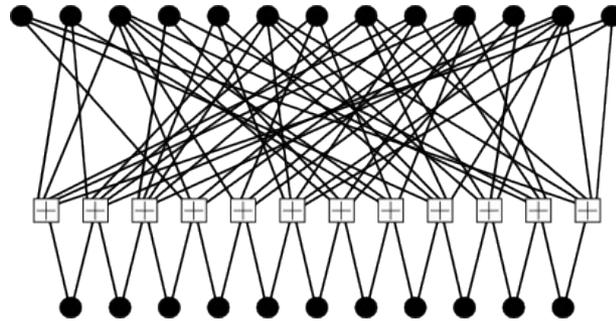
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- When choosing parameters:
  - large  $M_{SC}$  improves code performance.
  - large  $W$  improves decoder performance.

# Regular SC-LDPC Codes vs. Irregular LDPC-BCs

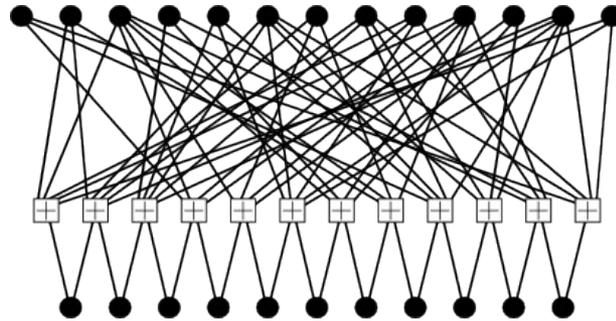
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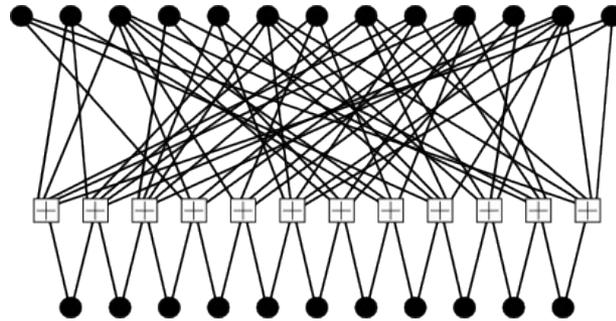


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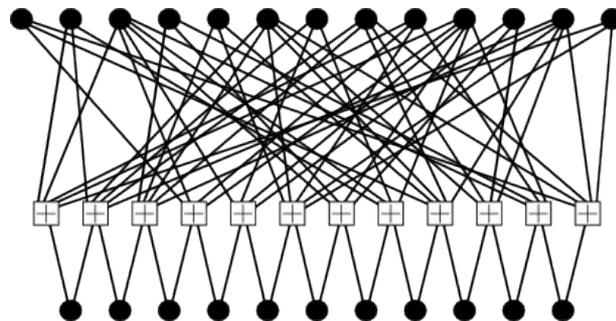


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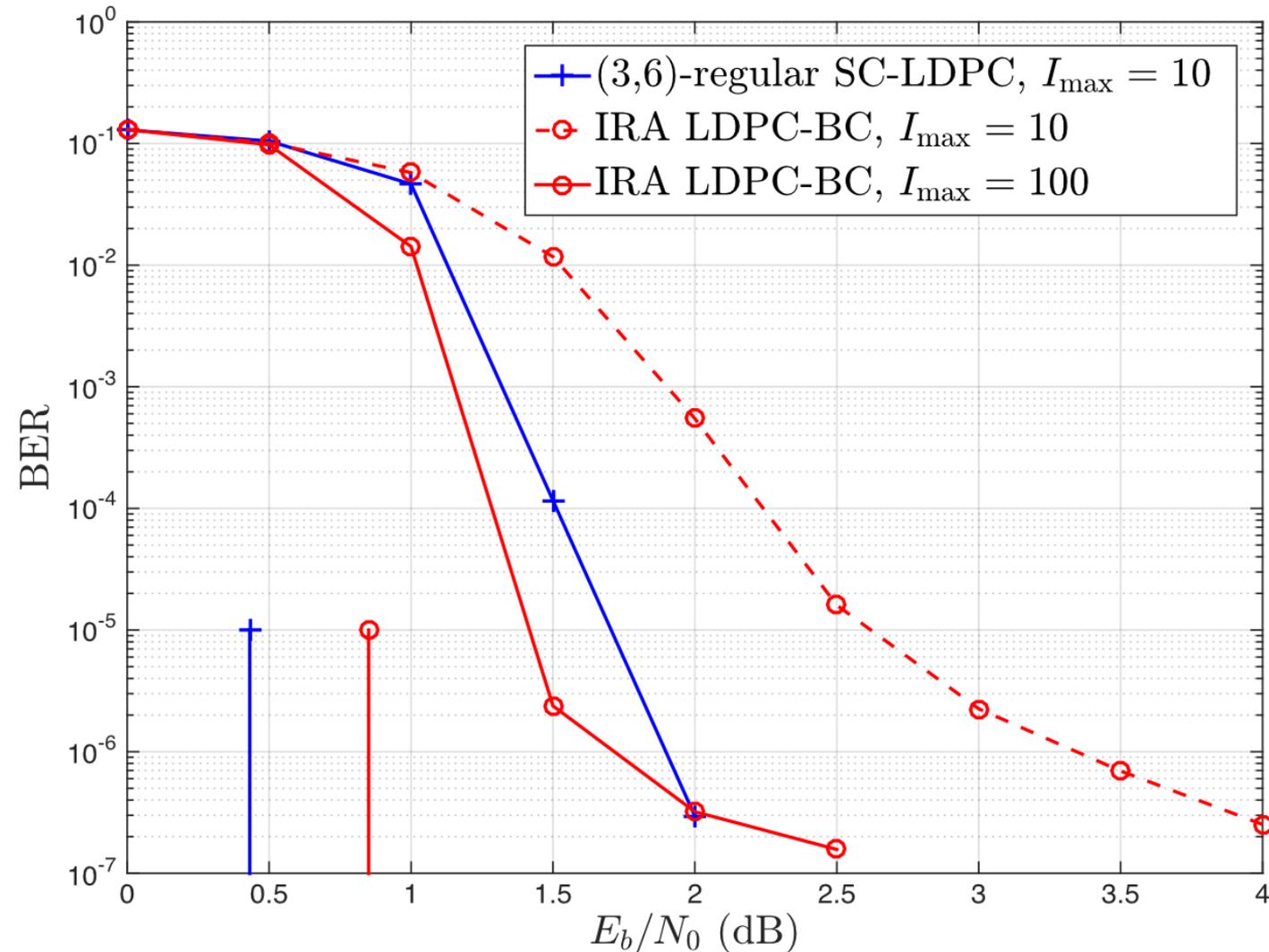
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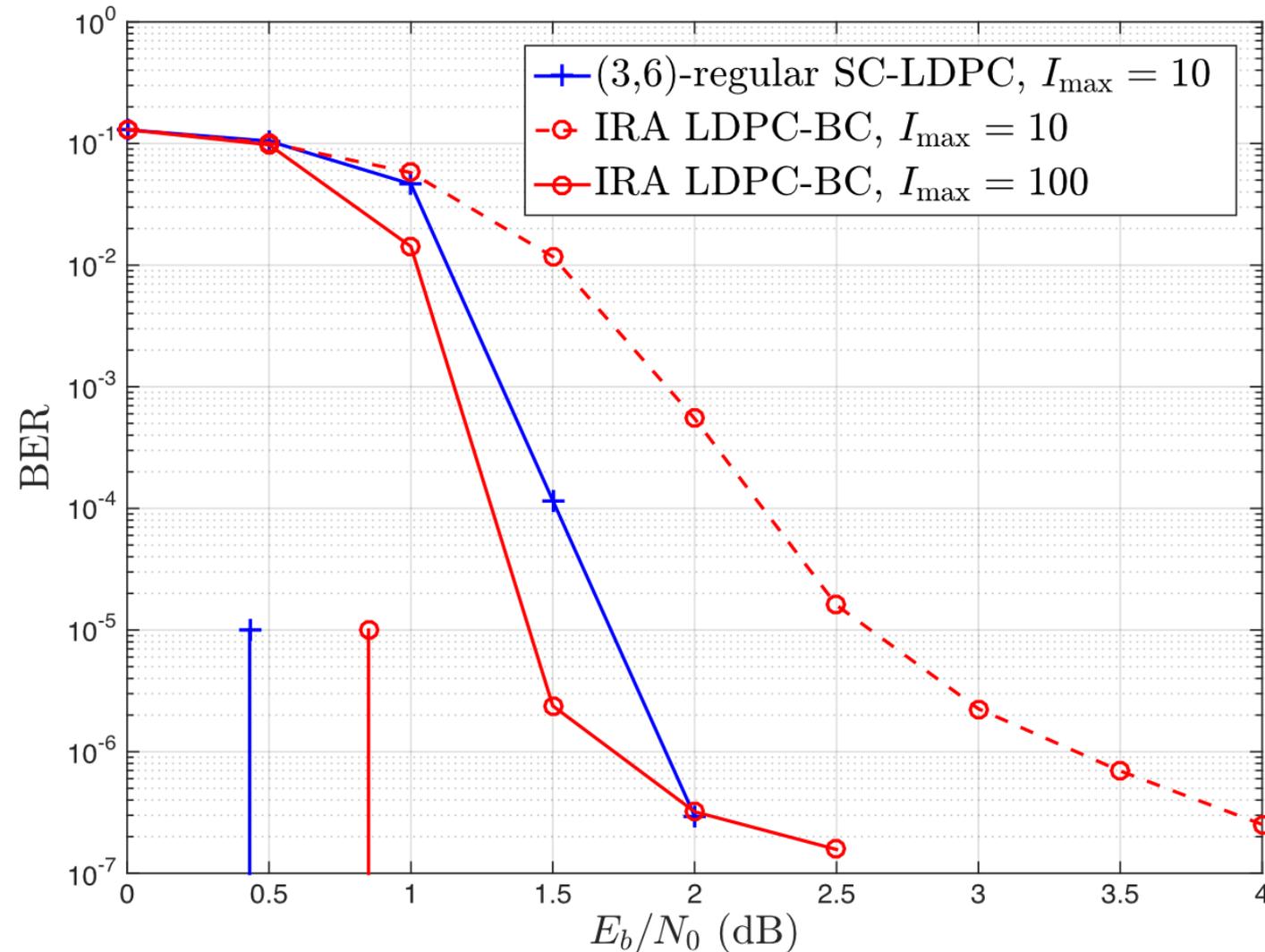
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- For the SC-LDPC code, we choose  $W=6$  and  $M=500$  so that the latency of both codes is 6000 bits. (Since a code symbol is present in  $W=6$  'windows', we allow fewer iterations per position for the SC-LDPC window decoder.)

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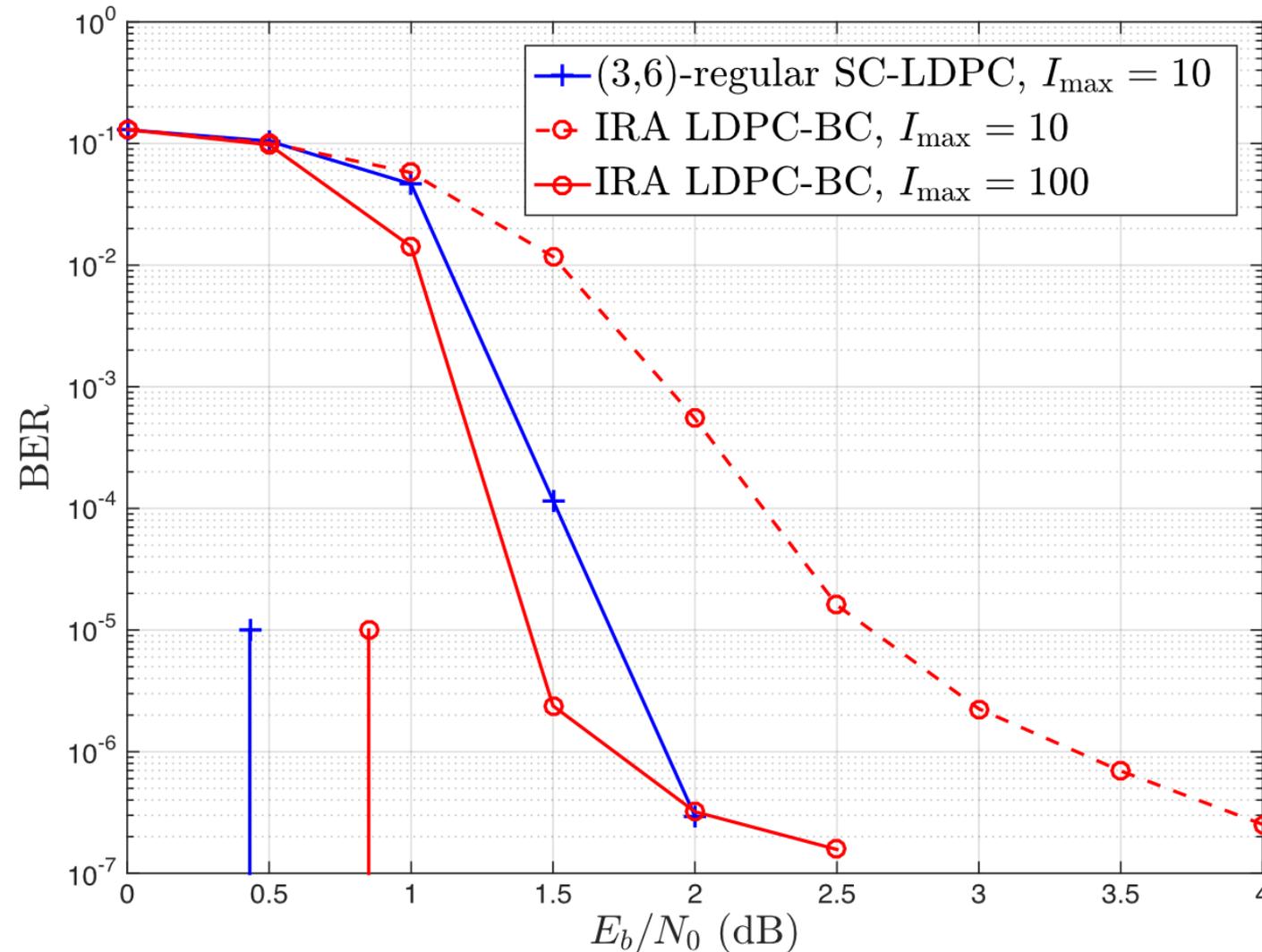
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- Gaps to threshold will reduce with increasing latency
- The asymptotically good regular SC-LDPC code shows no sign of an error floor
- The regular SC-LDPC code structure has implementation advantages

- As a result of their capacity approaching performance and simple structure, regular SC-LDPC codes may be attractive for future coding standards. Several key features will require further investigation:
  - ➔ Hardware advantages of QC designs obtained by circulant liftings
  - ➔ Hardware advantages of the 'asymptotically-regular' structure
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- Of particular importance for applications requiring extremely low decoded bit error rates (e.g., optical communication, data storage) is an investigation of error floor issues related to **stopping sets**, **trapping sets**, and **absorbing sets**.

- Spatially coupled LDPC code ensembles achieve **threshold saturation**, i.e., their iterative decoding thresholds (for large  $L$  and  $M$ ) approach the MAP decoding thresholds of the underlying LDPC block code ensembles.
- The threshold saturation and linear minimum distance growth properties of  $(J,K)$ -regular SC-LDPC codes combine the best asymptotic features of both regular and irregular LDPC-BCs.
- With window decoding, SC-LDPC codes also compare favorably to LDPC-BCs in the finite-length regime, providing flexible tradeoffs between BER performance, decoding latency, and decoding complexity.
- SC-LDPC codes can be punctured to achieve robustly good performance over a wide variety of code rates.